## AN IMPROVED EIGENVALUE PERTURBATION BOUND ON A NONNORMAL MATRIX AND ITS APPLICATION IN ROBUST STABILITY ANALYSIS\*

Yang Ya-guang
(Systems Research Center, University of Maryland, USA)

## Abstract

This paper presents an improved estimation of the eigenvalue perturbation bound developed by the author. The result is useful for robust stability analysis of linear control systems.

## §1. Introduction

The research on robust control systems has become one of the most attractive areas in recent studies [1],[4],[5]. An important aspect in this field is robust stability analysis. The problem under consideration can usually be reduced as an estimation of the eigenvalue perturbation bound for a prescribed matrix. Mathematically, the proposed problem is also important, especially in numerical analysis. Therefore, many contributions (such as Bauer and Fike [3], Kahan et al. [6]) have been made for this problem. The main purpose of this paper is to improve the estimation of their results, because in control theory, to get a more accurate estimate on robust stability is very important.

## §2. Main Results

**Theorem 1.** Suppose that  $A = Q^{-1}JQ \in C^{n*n}$ , and J is a Jordan matrix with the order of its largest block being m. Then for an arbitrary  $u \in \lambda(B)$ , where B = A + E, there must exist a  $\lambda \in \lambda(A)$  such that, if m is an even number,

$$\frac{|\lambda - u|^m}{(1 + 2|\lambda - u| + \dots + \frac{m}{2}|\lambda - u|^{\frac{m}{2} - 1} + \dots + \frac{m}{2}|\lambda - u|^{2m - 3 - \frac{m}{2}} + \dots + 2|\lambda - u|^{2m - 3} + |\lambda - u|^{2m - 2})^{\frac{1}{2}}}{\text{coefficients in these items are all } \frac{m}{2}} \leq ||Q^{-1}EQ||_2$$

$$(1)$$

and if m is an odd number,

$$\frac{|\lambda-u|^m}{(1+2|\lambda-u|+\cdots+\frac{m+1}{2}|\lambda-u|^{\frac{m+1}{2}-1}+\cdots+\frac{m+1}{2}|\lambda-u|^{2m-3}-\frac{m+1}{2}+\cdots+2|\lambda-u|^{2m-3}+|\lambda-u|^{2m-2})^{\frac{1}{2}}}{\operatorname{coefficients in these items are all}\frac{m+1}{2}}$$

<sup>\*</sup> Received June 7, 1990.

$$\leq \|Q^{-1}EQ\|_{2}. \tag{2}$$

*Proof.* If  $u \in \lambda(A)$ , the result is obvious. Therefore, we only consider  $u \notin \lambda(A)$ . According to the proof of Theorem 8 in [6], we have

$$||(J-uI)^{-1}||_2^{-1} \le ||QEQ^{-1}||_2.$$
 (3)

Since  $\sigma_{\min}(J - uI) = ||(J - uI)^{-1}||_2^{-1}$ , where  $\sigma_{\min}(J - uI)$  represents the minimal singular value of (J - uI), Kahan, Parlett, and Jiang suggested estimating the minimum eigenvalue for

$$T_1 = J_1 J_1^H = \operatorname{diag} \left( \begin{pmatrix} 1 + |\delta|^2 \left( \delta \right)^* \\ \delta & 1 + |\delta|^2 \end{pmatrix} \cdots \begin{pmatrix} 1 + |\delta|^2 \delta^* \\ \delta & 1 + |\delta|^2 \end{pmatrix}, \begin{pmatrix} 1 + |\delta|^2 \delta^* \\ \delta & |\delta|^2 \end{pmatrix} \right)$$

where  $\delta = \lambda - u$ ,  $\lambda \in \lambda(A)$ ,  $\lambda \neq u$ , and  $J_1$  is an arbitrary kth order Jordan block of the matrix (J - uI). Let  $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_k$  be the eigenvalues of  $T_1$ . Since

$$\lambda_k = \frac{\lambda_1 \cdots \lambda_k}{\lambda_1 \cdots \lambda_{k-1}} = \frac{\det(T_1)}{\lambda_1 \cdots \lambda_{k-1}} = \frac{|\delta|^{2k}}{\lambda_1 \cdots \lambda_{k-1}}, \tag{4}$$

the main task is to estimate the product of  $\lambda_1 \cdots \lambda_{k-1}$ .

Let  $C_r(T)$  be the rth compound or the rth adjugate of T, and  $\lambda_1^{(r)}$  be the maximal eigenvalue of  $C_r(T)$ . Then, according to [2], we have

$$\lambda_1^{(k-1)} = \lambda_1 \cdots \lambda_{k-1}. \tag{5}$$

Therefore, it is necessary to estimate merely  $\lambda_1^{(k-1)}$ . Denote the element of the *i*th row and the *j*th column of  $C_{k-1}(T_1)$  by  $C_{k-1}(T_1)_{ij}$ . Then

$$\lambda_1^{(k-1)} \le \max_{1 \le i \le k} \sum_{j=1}^k |C_{k-1}(T_1)_{ij}| \tag{6}$$

is a well known result. From

$$T_1 \operatorname{adj}(T_1) = |T_1|I = |\delta|^{2k}I$$

we have

$$\mathrm{adj}(T_1) = |\delta|^{2k} T_1^{-1} \tag{7}$$

while

$$T_{1}^{-1} = \frac{1}{|\delta|^{2}} \begin{pmatrix} \begin{pmatrix} 1 & -\frac{1}{\delta} & & \\ -\frac{1}{\delta} & 1 + \frac{1}{|\delta|^{2}} & & \\ (-\frac{1}{\delta^{2}})^{2} & (-\frac{1}{\delta^{2}})^{(1} + \frac{1}{|\delta|^{2}}) \end{pmatrix} & \underbrace{-a_{ij} = (-\frac{1}{\delta^{2}})^{i-i}(1 + \frac{1}{|\delta|^{2}} + \cdots + \frac{1}{|\delta|^{2}(i-1)})}_{i>j} \\ \underbrace{-a_{ij} = (-\frac{1}{\delta^{2}})^{i-j}(1 + \frac{1}{|\delta|^{2}} + \cdots + \frac{1}{|\delta|^{2}(j-1)})}_{j>i} & \underbrace{-a_{ij} = (-\frac{1}{\delta^{2}})^{i-j}(1 + \frac{1}{|\delta|^{2}} + \cdots + \frac{1}{|\delta|^{2}(k-1)})}_{j>i} \end{pmatrix}$$

$$\equiv |\delta|^{-2}F$$

$$(8)$$