# BIFURCATION ANALYSIS AND COMPUTATION OF DOUBLE TAKENS－BOGDANOV POINT IN $Z_{2}$－EQUIVARIABLE NONLINEAR EQUATIONS＊ 

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#### Abstract

The paper deals with the computation and bifurcation analysis of double Takens－Bogdanov point $\left(u^{0}, \Lambda^{0}\right)$（in short，DTB point）in the $Z_{2}$－equivariable nonlinear equation $f(u, \Lambda)=0, f: U \times R^{4} \rightarrow V$ ，where $U$ and $V$ are Banach spaces，param－ eters $\Lambda \in R^{4}$ ．At $\left(u^{0}, \Lambda^{0}\right)$ ，the null space of $f_{u}^{0}$ has geometric multiplicity 2 and algebraic multiplicity 4．Firstly a regular extended system for computing DTB point is proposed．Secondly，it is proved that there are four branches of singular points bifur－ cated from DTB point：two paths of STB points，two paths of TB－Hopf points．Finally， the numerical results of one dimensional Brusselator equations are given to show the effectiveness of our theory and method．


Key words $Z_{2}$－equivariance，Takens－Bogdanov point，Hopf point，extended system． AMS（2000）subject classifications 58F14

## 1 Introduction

The singular points in $Z_{2}$－equivariable nonlinear equations have been studied in［1］－［6］．The purpose of the paper is to discuss the computation of DTB point in $Z_{2}$－equivariable nonlinear equations with four parameters and relative properties．

Consider the $Z_{2}$－equivariable nonlinear equation with four parameters

$$
\begin{equation*}
f(u, \lambda, \alpha, \beta, \gamma)=0, \quad f: U \times R^{4} \rightarrow V, \tag{1.1}
\end{equation*}
$$

where $U$ and $V$ are Banach spaces，$f$ is a smooth Fredholm operator with index zero satisfying

[^0]$Z_{2}$-equivariance. There is an $s \in L(V) \cap L(U)$, such that
$$
s \neq I, s^{2}=I, f(s u, \lambda, \alpha, \beta, \gamma)=s f(u, \lambda, \alpha, \beta, \gamma), \forall(u, \lambda, \alpha, \beta, \gamma) \in U \times R^{4}
$$

It is well known that the presence of $Z_{2}$-equivariance implies the decomposition of $\mathrm{U}, \mathrm{V}$ and their dual space $U^{\prime}, V^{\prime}$

$$
\begin{aligned}
& U=U_{s} \oplus U_{a}, V=V_{s} \oplus V_{a} \\
& U^{\prime}=U_{s}^{\prime} \oplus U_{a}^{\prime}, V^{\prime}=V_{s}^{\prime} \oplus V_{a}^{\prime}
\end{aligned}
$$

where

$$
\begin{gathered}
U_{s}=\{u \in U, s u=u\}, U_{a}=\{u \in U, s u=-u\}, \\
V_{s}=\{v \in V, s v=v\}, V_{a}=\{v \in V, s v=-v\}, \\
U_{s}^{\prime}=\left\{\psi \in U^{\prime}, \psi s=\psi\right\}, U_{a}^{\prime}=\left\{\psi \in U^{\prime}, \psi s=-\psi\right\}, \\
V_{s}^{\prime}=\left\{\psi \in V^{\prime}, \psi s=\psi\right\}, V_{a}^{\prime}=\left\{\psi \in V^{\prime}, \psi s=-\psi\right\} .
\end{gathered}
$$

It is easy to check

$$
\psi u=0, \text { when } \psi \in U_{s}^{\prime}, u \in U_{a} ; \text { or } \psi \in U_{a}^{\prime}, u \in U_{s}
$$

Fixing $\gamma,(1.1)$ becomes nonlinear equation with three parameters $\lambda, \alpha, \beta$.
Definition $1.1 \quad\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)$ is called a STB1 point of (1.1) if

$$
\begin{align*}
& f\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)=0, u_{0} \in U_{s}  \tag{1.2a}\\
& N\left(f_{u}^{0}\right)=\operatorname{span}\left(\phi_{s}, \phi_{a}\right), \phi_{s} \in U_{s}, \phi_{a} \in U_{a}  \tag{1.2b}\\
& R\left(f_{u}^{0}\right)=\left\{v \in V, \psi_{s} v=\psi_{a} v=0\right\}, \psi_{s} \in V_{s}^{\prime}, \psi_{a} \in V_{a}^{\prime},  \tag{1.2c}\\
& \psi_{s} \phi_{s}=0, \psi_{a} \phi_{a} \neq 0 \tag{1.2d}
\end{align*}
$$

Definition $1.2 \quad\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)$ is called a STB2 point of (1.1) if

$$
\begin{equation*}
f\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)=0, u_{0} \in U_{s}, \tag{1.3a}
\end{equation*}
$$

$$
\begin{equation*}
N\left(f_{u}^{0}\right)=\operatorname{span}\left(\phi_{s}, \phi_{a}\right), \phi_{s} \in U_{s}, \phi_{a} \in U_{a} \tag{1.3b}
\end{equation*}
$$

$$
\begin{equation*}
R\left(f_{u}^{0}\right)=\left\{v \in V, \psi_{s} v=\psi_{a} v=0\right\}, \psi_{s} \in V_{s}^{\prime}, \psi_{a} \in V_{a}^{\prime} \tag{1.3c}
\end{equation*}
$$

$$
\begin{equation*}
\psi_{s} \phi_{s} \neq 0, \psi_{a} \phi_{a}=0 \tag{1.3d}
\end{equation*}
$$

Definition 1.3 $\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)$ is called a TB-Hopf1 point of (1.1) if

$$
\begin{align*}
& f\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)=0, u_{0} \in U_{s}  \tag{1.4a}\\
& N\left(f_{u}^{0}\right)=\operatorname{span}\left(\phi_{s}\right), \phi_{s} \in U_{s}  \tag{1.4b}\\
& R\left(f_{u}^{0}\right)=\left\{v \in V, \psi_{s} v=0\right\}, \psi_{s} \in V_{s}^{\prime}  \tag{1.4c}\\
& \psi_{s} \phi_{s}=0  \tag{1.4d}\\
& N\left(f_{u}^{0} \pm \omega_{0} i I\right)=\operatorname{span}\left(a_{a}+i b_{a}\right), \omega_{0}>0, a_{a}, b_{a} \in U_{a} . \tag{1.4e}
\end{align*}
$$

Definition $1.4 \quad\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)$ is called a TB-Hopf2 point of (1.1) if

$$
\begin{align*}
& f\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}\right)=0, u_{0} \in U_{s}  \tag{1.5a}\\
& N\left(f_{u}^{0}\right)=\operatorname{span}\left(\phi_{a}\right), \phi_{a} \in U_{a}  \tag{1.5b}\\
& R\left(f_{u}^{0}\right)=\left\{v \in V, \psi_{a} v=0\right\}, \psi_{a} \in V_{a}^{\prime}  \tag{1.5c}\\
& \psi_{a} \phi_{a}=0  \tag{1.5d}\\
& N\left(f_{u}^{0} \pm \omega_{0} i I\right)=\operatorname{span}\left(a_{s}+i b_{s}\right), \omega_{0}>0, a_{s}, b_{s} \in U_{s} . \tag{1.5e}
\end{align*}
$$

For (1.1) with four parameters, we have
Definition 1.5 $\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}, \gamma_{0}\right)$ is called a double TB point of (1.1) if

$$
\begin{equation*}
f\left(u_{0}, \lambda_{0}, \alpha_{0}, \beta_{0}, \gamma_{0}\right)=0, u_{0} \in U_{s}, \tag{1.6a}
\end{equation*}
$$

$$
\begin{equation*}
N\left(f_{u}^{0}\right)=\operatorname{span}\left(\phi_{s}, \phi_{a}\right), \phi_{s} \in U_{s}, \phi_{a} \in U_{a} \tag{1.6b}
\end{equation*}
$$

$$
\begin{equation*}
R\left(f_{u}^{0}\right)=\left\{v \in V, \psi_{s} v=\psi_{a} v=0\right\}, \psi_{s} \in V_{s}^{\prime}, \psi_{a} \in V_{a}^{\prime} \tag{1.6c}
\end{equation*}
$$


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