EXISTENCE OF BOUNDED SOLUTIONS FOR QUASILINEAR SUBELLIPTIC DIRICHLET PROBLEMS*

Xu Chaojiang

(Institute of Mathematics, Wuhan University, Wuhan 430072, China) (Received Sept. 29, 1992; revised April 27, 1994)

Abstract This paper proves the existence of solution for the following quasilinear subelliptic Dirichlet problem:

$$\begin{cases} \sum_{j=1}^{m} X_j^* a_j(x, v, Xv) + a_0(x, v, Xv) + H(x, v, Xv) = 0 \\ v \in M_0^{1,p}(\Omega) \cap L^{\infty}(\Omega) \end{cases}$$

Here $X = \{X_1, \dots, X_m\}$ is a system of vector fields defined in an open domain M of \mathbb{R}^n , $n \geq 2$, $\Omega \subset\subset M$, and X satisfies the so-called Hörmander's condition at the order of r > 1 on M. $M_0^{1,p}(\Omega)$ is the weighted Sobolev's space associated with the system X. The Hamiltonian H grows at most like $|Xv|^p$.

Key Words Subelliptic equation; weighted Sobolev's space; Dirichlet problem.
Classification 35H.

1. Introduction

This paper is concerned with the existence of bounded solutions for the following quasilinear boundary value problem:

$$\begin{cases} A(v) + H(x, v, Xv) = 0 \\ v \in M_0^{1,p}(\Omega) \cap L^{\infty}(\Omega) \end{cases}$$

$$(1.1)$$

where $X = \{X_1, \dots, X_m\}$ is a system of real smooth vector fields defined in an open domain M of \mathbb{R}^n , $n \geq 2$, $\Omega \subset\subset M$. The principal part A is a differential operator of second order in divergence form of Leray-Lions:

$$A(v) = \sum_{j=1}^{m} X_{j}^{*} a_{j}(x, v, Xv) + a_{0}(x, v, Xv)$$
(1.3)

The Hamiltonian H grows at most like $|Xv|^p$.

^{*}The work supported by National Natural Science Foundation of China.

We assume that the system $X = \{X_1, \dots, X_m\}$ satisfies the following Hörmander's condition:

(H) $\begin{cases} X \text{ together with their commutators } X_{\alpha} = [X_{\alpha_1}, \cdots [X_{\alpha_{s-1}}, X_{\alpha_s} \cdots]] \\ \text{up to some fixed length } r \text{ span the tangent space at each point of } M. \end{cases}$

 $M_0^{1,p}(\Omega)$ is the associate weighted Sobolev's space (see Section 2).

We assume that a_j , a_0 , H, are Carathéodory functions, which mean

$$\forall (s,\xi) \in \mathbb{R} \times \mathbb{R}^n, \ x \to a_j(x,s,\xi) \text{ are measurable}$$
 (1.4)

$$a.e. \ x \in \Omega, \ (s,\xi) \to a_j(x,s,\xi) \text{ are continuous}$$
 (1.5)

And they satisfy the following conditions for all $s \in \mathbb{R}$, $\xi, \xi^* \in \mathbb{R}^n$, and for almost every $x \in \Omega$,

$$|a_j(x,s,\xi)| \le \beta [k(x) + |s|^{p-1} + |\xi|^{p-1}], \quad j = 0, 1, \dots, m$$
 (1.6)

$$|H(x,s,\xi)| \le c_0 + b(|s|)|\xi|^p$$
 (1.7)

$$\sum_{j=1}^{m} [a_j(x, s, \xi)] \le c_0 + b(|s|)|\xi|^s$$

$$\sum_{j=1}^{m} [a_j(x, s, \xi) - a_j(x, s, \xi^*)](\xi_j - \xi_j^*) > 0, \quad \xi \neq \xi^*$$

$$\sum_{j=1}^{m} a_j(x, s, \xi) \le a_j(\xi|^p)$$
(1.8)

$$\sum_{j=1}^{m} a_j(x, s, \xi) \xi_j \ge \alpha |\xi|^p \tag{1.9}$$

$$a_0(x, s, \xi)s \ge \alpha_0|s|^p \tag{1.10}$$

where $\alpha, \alpha_0, \beta, c_0$ are strictly positive constants, k(x) is a given positive function in $L^{p'}(\Omega)$, 1 , <math>1/p+1/p' = 1, and b(s) is a positive, increasing, continuous function defined on \mathbb{R}^+ . Since the system of vector fields $X = \{X_1, \dots, X_m\}$ is degenerate of order r > 1, the equation (1.1) is called subelliptic.

We shall prove the following existence and regularity theorem.

Theorem 1 Assume that $\partial\Omega$ is C^{∞} , and non characteristic for the system of vector fields X. Then, under the hypotheses (H) and (1.4)–(1.10), there exists at least one solution of problem (1.1) and (1.2).

As in Theorem 7 of [1], we can also prove that this weak solution is in the class $C_{loc}^{\tau}(\Omega)$ for some $\tau > 0$.

The proof of Theorem 1 consists in the following steps. We first define an approximate problem. We then prove a priori estimates in $L^{\infty}(\Omega)$ and $M_0^{1,p}(\Omega)$ for the solutions of these approximate problems. Finally we prove that the sequence of solutions of approximate problems is compact in the strong topology of $M_0^{1,p}(\Omega)$, a result which allows to pass to the limit and to obtain the existence result.

The existence result does not require any smoothness assumptions on the coefficients a_j , $j = 0, 1, \dots, m, H$. We could also consider other types of boundary conditions.