## **Existence of Positive Solutions for Kirchhoff Type Problems with Critical Exponent**

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**Abstract.** In this paper, we consider the following Kirchhoff type problem with critical exponent

$$\begin{cases} -\left(a+b\int_{\Omega}|\nabla u|^{2}\mathrm{d}x\right)\Delta u = \lambda u^{q}+u^{5}, & \text{in }\Omega,\\ u=0, & \text{on }\partial\Omega \end{cases}$$

where  $\Omega \subset \mathbb{R}^3$  is a bounded smooth domain, 0 < q < 1 and the parameters  $a, b, \lambda > 0$ . We show that there exists a positive constant  $T_4(a)$  depending only on a, such that for each a > 0 and  $0 < \lambda < T_4(a)$ , the above problem has at least one positive solution. The method we used here is based on the Nehari manifold, Ekeland's variational principle and the concentration compactness principle.

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**Key Words**: Kirchhoff type equation; Nehari manifold; Ekeland's variational principle; critical exponent.

## 1 Introduction and main results

This paper is devoted to the study of the existence of positive solutions of the following Kirchhoff-type problem with critical exponent

$$\begin{cases} -\left(a+b\int_{\Omega}|\nabla u|^{2}dx\right)\Delta u = \lambda u^{q}+u^{5}, & \text{ in }\Omega,\\ u=0, & \text{ on }\partial\Omega, \end{cases}$$
  $(P_{\lambda}^{a,b})$ 

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where, through this work,  $\Omega \subset R^3$  is a bounded smooth domain, 0 < q < 1, and the parameters  $a, b, \lambda > 0$ .

It is well known that the Kirchhoff type problem has a mechanical and biological motivation (c.f. [1,2]) and has attracted the attention of many researchers after the work of Lions [3], where a functional analysis approach was proposed to attack it. The reader may consult [1–9] and the references therein, for more information about this problem.

In the case a = 1 and b = 0, Problem  $(P_{\lambda}^{1,0})$  has been studied extensively. For example, Brezis et al. [10] has shown that Problem  $(P_{\lambda}^{1,0})$  has at least one positive solution for 3 < q < 5. When 0 < q < 1, Ambrosetti et al. [11] has proved that there exists  $\lambda^*$  such that  $(P_{\lambda}^{1,0})$  has at least two positive solutions for  $\lambda \in (0, \lambda^*)$ .

A natural interesting question is whether the results concerning the solutions of  $(P_{\lambda}^{1,0})$  remain true for the problem  $(P_{\lambda}^{a,b})$  with b > 0. Stimulated by [4] and [12], in this paper we study problem  $(P_{\lambda}^{a,b})$  and give some positive answers; to our knowledge, the results in this paper are new for the case 0 < q < 1.

The main idea of our paper is as follows. Firstly, we consider the Nehari manifold

$$\Lambda_{\lambda} = \left\{ u \in H_0^1(\Omega) | < I_{\lambda}'(u), u > = 0 \right\},$$

$$(1.1)$$

where  $I_{\lambda}(u) \in C^1(H_0^1(\Omega), R)$  is given by

$$I_{\lambda}(u) = \frac{a}{2} \int_{\Omega} |\nabla u|^2 \mathrm{d}x + \frac{b}{4} \left( \int_{\Omega} |\nabla u|^2 \mathrm{d}x \right)^2 - \frac{\lambda}{1+q} \int_{\Omega} |u|^{1+q} \mathrm{d}x - \frac{1}{6} \int_{\Omega} |u|^6 \mathrm{d}x.$$

Then we split  $\Lambda_{\lambda}$  into three parts:

$$\Lambda_{\lambda}^{+} = \left\{ u \in \Lambda_{\lambda} | (1-q)a \| u \|_{H^{1}}^{2} + (3-q)b \| u \|_{H^{1}}^{4} > (5-q) \int_{\Omega} |u|^{6} \mathrm{d}x \right\},$$
(1.2)

$$\Lambda_{\lambda}^{0} = \left\{ u \in \Lambda_{\lambda} | (1-q)a \| u \|_{H^{1}}^{2} + (3-q)b \| u \|_{H^{1}}^{4} = (5-q) \int_{\Omega} |u|^{6} \mathrm{d}x \right\},$$
(1.3)

$$\Lambda_{\lambda}^{-} = \left\{ u \in \Lambda_{\lambda} | (1-q)a \| u \|_{H^{1}}^{2} + (3-q)b \| u \|_{H^{1}}^{4} < (5-q) \int_{\Omega} |u|^{6} \mathrm{d}x \right\},$$
(1.4)

where we set  $||u||_{H^1} = (\int_{\Omega} |\nabla u|^2 dx)^{\frac{1}{2}}$  for  $u \in H^1_0(\Omega)$ . Finally by Ekeland's variational principle, we can prove that  $I_{\lambda}(u)$  has a critical point  $u_{\lambda} \in \Lambda^+_{\lambda}$ .

Before stating the main result, we give some constants. Throughout this paper, we denote by  $S_r$  the best Sobolev constant for the embedding of  $H_0^1(\Omega)$  into  $L^r(\Omega)$  for all  $1 < r \le 6$ . Moreover, we define  $T_1(a)$ , K,  $T_2(a)$ ,  $T_3(a)$  and  $T_4(a)$  by

$$T_1(a) = \frac{4}{5-q} \left(\frac{1-q}{5-q}\right)^{\frac{1-q}{4}} a^{\frac{5-q}{4}} S_{1+q}^{\frac{1+q}{2}} S_6^{\frac{3(1-q)}{4}},$$
(1.5a)

$$K = \frac{2(3-q)}{5-q},$$
(1.5b)