

# WEAK AND STRONG CONVERGENCE THEOREMS FOR SPLIT GENERALIZED MIXED EQUILIBRIUM PROBLEM<sup>\*†</sup>

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## Abstract

The purpose of this paper is to introduce a split generalized mixed equilibrium problem (SGMEP) and consider some iterative sequences to find a solution of the generalized mixed equilibrium problem such that its image under a given bounded linear operator is a solution of another generalized mixed equilibrium problem. We obtain some weak and strong convergence theorems.

**Keywords** split generalized mixed equilibrium problem; weak convergence; strong convergence; fixed point

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## 1 Introduction and Preliminaries

Let  $H$  be a real Hilbert space with inner product  $\langle \cdot, \cdot \rangle$  and norm  $\| \cdot \|$  and  $C$  be a nonempty closed convex subset of  $H$ . Let  $f$  be a bi-function from  $C \times C$  to  $R$  and  $\varphi : C \rightarrow R$  be a function, where  $R$  is the set of real numbers. Let  $B : C \rightarrow H$  be a nonlinear mapping. Then we consider the following generalized mixed equilibrium problem: There exists an  $x \in C$ , such that

$$f(x, y) + \varphi(y) - \varphi(x) + \langle Bx, y - x \rangle \geq 0, \quad \text{for any } y \in C. \quad (1.1)$$

The set of solutions of (1.1) is denoted by  $GMEP(f, \varphi, B)$ .

If  $B = 0$ , problem (1.1) becomes the following mixed equilibrium problem: There exists an  $x \in C$ , such that

$$f(x, y) + \varphi(y) - \varphi(x) \geq 0, \quad \text{for any } y \in C. \quad (1.2)$$

The set of solutions of (1.2) is denoted by  $MEP(f, \varphi)$ .

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If  $\varphi = 0$ , problem (1.1) reduces to the following generalized equilibrium problem: There exists an  $x \in C$ , such that

$$f(x, y) + \langle Bx, y - x \rangle \geq 0, \quad \text{for any } y \in C. \quad (1.3)$$

The set of solutions of (1.3) is denoted by  $GEP(f, B)$ .

If  $\varphi = 0$  and  $B = 0$ , problem (1.1) becomes the following equilibrium problem: There exists an  $x \in C$ , such that

$$f(x, y) \geq 0, \quad \text{for any } y \in C. \quad (1.4)$$

The set of solutions of (1.4) is denoted by  $EP(f)$ .

Equilibrium problem is very general in the sense that it includes, as special cases, optimization problems, variational inequalities, mini or max problems, Nash equilibrium problem in noncooperative games and others; see for instance [1-20].

In 2012, Zhenhua He [12] proposed a new equilibrium problem which is called split equilibrium problem (SEP). Let  $E_1$  and  $E_2$  be two real Banach spaces,  $C$  be a closed convex subset of  $E_1$ ,  $K$  be a closed convex subset of  $E_2$ ,  $A : E_1 \rightarrow E_2$  be a bounded linear operator,  $f$  be a bi-function from  $C \times C$  into  $R$  and  $g$  be a bi-function from  $K \times K$  into  $R$ . The SEP is to find an element  $x^* \in C$ , such that

$$f(x^*, y) \geq 0, \quad \text{for any } y \in C,$$

and such that  $u := Ax^* \in K$  satisfying

$$g(u, v) \geq 0, \quad \text{for any } v \in K.$$

Inspired and motivated by the above works, we propose a split generalized mixed equilibrium problem (SGMEP). Let  $E_1$  and  $E_2$  be two real Banach spaces,  $E_1^*$  and  $E_2^*$  denote the dual of  $E_1$  and  $E_2$ , respectively,  $C$  be a closed convex subset of  $E_1$ ,  $K$  be a closed convex subset of  $E_2$ ,  $A : E_1 \rightarrow E_2$  be a bounded linear operator,  $f$  be a bi-function from  $C \times C$  into  $R$ ,  $g$  be a bi-function from  $K \times K$  into  $R$ ,  $B : C \rightarrow E_1^*$  and  $S : K \rightarrow E_2^*$  be two mappings,  $\varphi : C \rightarrow R$  and  $\psi : K \rightarrow R$  be two functions. The SGMEP is to find an element  $p \in C$  such that

$$f(p, y) + \varphi(y) - \varphi(p) + \langle Bp, y - p \rangle \geq 0, \quad \text{for any } y \in C, \quad (1.5)$$

and that  $u := Ap \in K$  satisfies

$$g(u, v) + \psi(v) - \psi(u) + \langle Su, v - u \rangle \geq 0, \quad \text{for any } v \in K. \quad (1.6)$$

For convenience, we denote the solution set of the SGMEP by  $\Omega$ , that is,  $\Omega = \{x \in GMEP(f, \varphi, B) : Ax \in GMEP(g, \psi, S)\}$ .

Now, we give two examples to show  $\Omega \neq \emptyset$ .