

On The Maximal-Like Solution of Matrix Equation $X + A^* X^{-2} A = I^*$ †

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Abstract. In this paper, we study several iterative methods for finding the maximal-like solution of the matrix equation $X + A^* X^{-2} A = I$, and deduce some properties of the maximal-like solution with these methods.

Key words: Matrix equation; maximal-like solution.

AMS subject classifications: 65F10, 65F30

1 Introduction

In this paper we consider the matrix equation

$$X + A^* X^{-2} A = I \quad (1)$$

where I is the $n \times n$ identity matrix and A is an $n \times n$ complex matrix.

Throughout this paper we denote $\|\cdot\|$ the Euclidean vector norm, or corresponding subordinate matrix norm (simply 2-norm). $\lambda(M)$, $\rho(M)$ are respectively the spectrum and spectral radius of a square matrix M , A^* is conjugate transpose of a matrix A . For two positive definite (Hermitian) matrices P , Q of the same dimension, $P > Q$ ($P \geq Q$) means that $P - Q$ is positive definite (semi-definite). For any positive definite solution X of Eq. (1), we have $X_S \leq X \leq X_L$, where X_L and X_S are respectively the maximal solution and minimal solution, and X_l is the maximal-like solution whose inverse has the minimal 2-norm.

In the literature, matrix equations of type like Eq. (1) have been extensively studied. Articles [3, 4, 11] discuss the matrix equation $X + A^* X^{-1} A = I$ and obtained some properties of the equation, including the existence of maximal and minimal solutions. [1, 2, 10] generalize the results, and [7, 8] directly discuss nonlinear matrix equation of type in Eq. (1). [7, 8] mainly study the following algorithms:

$$\begin{cases} X_0 = \alpha I \\ X_k = I - A^* X_{k-1}^{-2} A \end{cases}, \quad \begin{cases} X_0 = \alpha I \\ X_{k+1} = \sqrt{A(I - X_k)^{-1} A^*} \end{cases}, \quad (2)$$

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and provide some convergence properties under different conditions. However, they do not show the existence of the maximal and minimal solutions and the properties of solutions. [5] proves the existence of the minimal solutions. [9] studies more general matrix equations of the type $X^s \pm A^T X^{-t} A = I$.

In this paper, we discuss the maximal-like solution X_l , which is the maximal solution X_L when X_L exists. In Sections 2 and 3 we propose two algorithms for finding X_l , and study properties of these algorithms; in Section 4 we provide some numerical experiments.

2 An algorithm for computing X_l

In this section, we propose an iterative algorithm for computing X_l . We will prove that the algorithm is linearly convergent, and derive some properties of X_l . Unlike the commonly used algorithms given in Eq. (2) which involve computing the inverse, our algorithm only requires matrix multiplications.

We first give a necessary condition for existence of a solution of Eq. (1)

Theorem 2.1 ([5]). *If Eq. (1) has a positive definite solution X , then*

$$\rho(A) \leq \frac{2\sqrt{3}}{9}.$$

Corollary 2.1. *Suppose that A is normal. If Eq. (1) has a positive definite solution, then*

$$\|A\| \leq \frac{2\sqrt{3}}{9}.$$

Lemma 2.1. *Define*

$$f(\eta) = \frac{\eta}{(1+\eta)^3}, \quad \eta \geq 0.$$

Then f is increasing for $0 \leq \eta \leq \frac{1}{2}$, decreasing for $\frac{1}{2} \leq \eta \leq +\infty$, and

$$f_{\max} = f\left(\frac{1}{2}\right) = \frac{4}{27}.$$

Proof: From

$$f'(\eta) = \frac{1}{(1+\eta)^4}(1-2\eta),$$

we know that $f(\eta)$ is increasing in $[0, \frac{1}{2}]$, and decreasing in $[\frac{1}{2}, +\infty]$. When $\eta = \frac{1}{2}$, $f_{\max} = f(\frac{1}{2}) = \frac{4}{27}$. ■

We now present the main result of this section.

Theorem 2.2. *If $\|A\| < \frac{2\sqrt{3}}{9}$, then there exists a unique solution X_l of Eq. (1) satisfying*

$$\|X_l^{-1}\| < \frac{3}{2}.$$

Moreover, for any other positive definite solution X we have

$$\|X^{-1}\| \geq \frac{3}{2}.$$