

INTERPOLATION FORMULAS OF INTERMEDIATE QUOTIENTS FOR DISCRETE FUNCTIONS WITH SEVERAL INDICES*

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§ 1

The imbedding relations and the interpolation formulas of Sobolev spaces are very important and powerful tools in the study of the linear and nonlinear theory of partial differential equations and systems. The finite difference method is commonly used in practical and theoretical study of various problems of partial differential equations and systems of different type. Many authors are attracted to establish the imbedding relations and the interpolation formulas for the discrete functions. These are undoubtedly important in practical and theoretical use of finite difference method. As in [1] the Sobolev inequalities are given for the discrete function on number axis. In [2] the difference imbedding theorems of the Sobolev space with weight are considered. In [3—5] for the discrete functions on finite segment the interpolation formulas are established. These interpolation formulas can be used to establish the convergence and stability of the finite difference schemes for the various problems of the nonlinear partial differential systems of different types. And these can also be used to construct the generalized and weak global solutions for the nonlinear systems of partial differential equations^[3-9]. Now in the present note we want to consider the interpolation formulas of intermediate quotients for the discrete functions with several indices.

§ 2

Suppose that the finite interval $[0, l]$ is divided into the small segment grids by the points $x_j = jh$ ($j = 0, 1, \dots, J$), where $Jh = l$, J is an integer and h is the stepsize. The discrete function $u_h = \{u_j\}$ ($j = 0, 1, \dots, J$) is defined on the grid points x_j ($j = 0, 1, \dots, J$). Let us denote $\Delta_+ u_j = u_{j+1} - u_j$, $\Delta_- u_j = u_j - u_{j-1}$. For the norms of the discrete function $u_h = \{u_j\}$ ($j = 0, 1, \dots, J$) and its difference quotients

$$\delta^k u_h = \left\{ \frac{\Delta_+^k u_j}{h^k} \right\} \quad (j = 0, 1, \dots, J - k)$$

of order $k \geq 0$, we take the notations

$$\|\delta^k u_h\|_p = \left(\sum_{j=0}^{J-k} \left| \frac{\Delta_+^k u_j}{h^k} \right|^p h \right)^{\frac{1}{p}}, \quad 1 \leq p < \infty;$$

$$\|\delta^k u_h\|_\infty = \max_{j=0, 1, \dots, J-k} \left| \frac{\Delta_+^k u_j}{h^k} \right|, \quad k \geq 0. \tag{1}$$

The interpolation formulas of the intermediate quotients for the discrete functions defined on finite interval $[0, l]$ can be stated as follows^[3-5].

Theorem 1. For any discret function $u_h = \{u_j\}$ ($j=0, 1, \dots, J$) defined on the finite interval $[0, l]$, there is the interpolation formula

$$\|\delta^k u_h\|_p \leq K_1 \|u_h\|_2^{-\frac{k+\frac{1}{2}-\frac{1}{p}}{n}} \left\{ \|\delta^n u_h\|_2 + \frac{\|u_h\|_2}{l^n} \right\}^{\frac{k+\frac{1}{2}-\frac{1}{p}}{n}}, \tag{2}$$

where $2 \leq p < \infty$, $0 \leq k < n$ and K_1 is a constant independent of h, l and u_h .

§ 3

Let us introduce some notations for discrete functions with several indices.

Take a m -dimensional rectangular domain $Q^m = \{x | x = (x_1, \dots, x_m) | 0 \leq x_i \leq l_i, i=1, 2, \dots, m\}$ in the m -dimensional Euclidean space R^m , where $m \geq 1$ and $l_i > 0, i=1, 2, \dots, m$. For the rectangular domain Q^m we define $l = \min_{i=1, 2, \dots, m} \{l_i\} > 0$. Divide the rectangular domain Q^m into small grids by the parallel hyperplanes $x_i = x_{j_i}$ ($j_i=0, 1, \dots, J_i; i=1, 2, \dots, m$) where $x_{j_i} = j_i h_i$ ($j_i=0, 1, \dots, J_i; i=1, 2, \dots, m$) and $J_i h_i = l_i$ ($i=1, 2, \dots, m$). The set of the grids points $(x_{1j_1}, \dots, x_{mj_m})$ ($j_i=0, 1, \dots, J_i; i=1, 2, \dots, m$) is denoted by $Q_\Delta^m = \{(x_{1j_1}, \dots, x_{mj_m})\}$. We use the notation $u_\Delta = \{u_{j_1, \dots, j_m}\}$ to denote the discrete function with m indices defined on the grid domain Q_Δ^m .

Usually we have the abbreviations $\Delta_i u_{j_1, \dots, j_i, \dots, j_m} = (u_{j_1, \dots, j_i+1, \dots, j_m} - u_{j_1, \dots, j_i, \dots, j_m})/h_i$ and $\bar{\Delta}_i u_{j_1, \dots, j_i, \dots, j_m} = (u_{j_1, \dots, j_i, \dots, j_m} - u_{j_1, \dots, j_i-1, \dots, j_m})/h_i$. And then furthermore we adopt the notations $\delta^\alpha u_\Delta = \left\{ \frac{\Delta^\alpha u_{j_1, \dots, j_m}}{h^\alpha} \mid j_i=0, 1, \dots, J_i - \alpha_i; i=1, 2, \dots, m \right\}$, where $\alpha = (\alpha_1, \alpha_2, \dots, \alpha_m)$ is a m -index and then $\delta^\alpha = \delta_1^{\alpha_1} \dots \delta_m^{\alpha_m}$, $\Delta^\alpha = \Delta_1^{\alpha_1} \dots \Delta_m^{\alpha_m}$, $h^\alpha = h_1^{\alpha_1} \dots h_m^{\alpha_m}$, $|\alpha| = \alpha_1 + \dots + \alpha_m \geq 0$ and α_i ($i=1, 2, \dots, m$) are integers. Similarly we have

$$\delta_s^\beta u_{j_1, \dots, j_s, \dots} = \left\{ \frac{\bar{\Delta}^\beta u_{j_1, \dots, j_s, j_{s+1}, \dots, j_m}}{h^\beta} \mid j_i=0, 1, \dots, J_i - \beta_i; i=s+1, \dots, m \right\},$$

where $\beta = (\beta_{s+1}, \dots, \beta_m)$ and $s=0, 1, \dots, m$.

Now we adopt the following notations of the norms for the discrete functions and their difference quotients:

$$\|\delta^\alpha u_\Delta\|_{L_p(Q^m)} = \left(\sum_{i=1}^m \sum_{j_i=0}^{J_i - \alpha_i} \left| \frac{\Delta^\alpha u_{j_1, \dots, j_m}}{h^\alpha} \right|^p h_1 h_2 \dots h_m \right)^{\frac{1}{p}}, \quad 1 \leq p < \infty; \tag{3}$$

$$\|\delta^\alpha u_\Delta\|_{L_\infty(Q^m)} = \max_{\substack{j_i=0, 1, \dots, J_i - \alpha_i \\ i=1, 2, \dots, m}} \left| \frac{\Delta^\alpha u_{j_1, \dots, j_m}}{h^\alpha} \right|$$

and

$$(01) \quad \|\delta_s^\beta u_{j_1, \dots, j_s, \dots}\|_{L_p(Q^{m-s})} = \left(\sum_{i=s+1}^m \sum_{j_i=0}^{J_i - \beta_i} \left| \frac{\bar{\Delta}^\beta u_{j_1, \dots, j_m}}{h^\beta} \right|^p h_{s+1} \dots h_m \right)^{\frac{1}{p}}, \quad 1 \leq p < \infty; \tag{4}$$

$$\|\delta_s^\beta u_{j_1, \dots, j_s, \dots}\|_{L_\infty(Q^{m-s})} = \max_{\substack{j_i=0, 1, \dots, J_i - \beta_i \\ i=s+1, \dots, m}} \left| \frac{\bar{\Delta}^\beta u_{j_1, \dots, j_m}}{h^\beta} \right|, \quad s=0, 1, \dots, m,$$

where $\alpha = (\alpha_1, \dots, \alpha_m)$, $\beta = (\beta_{s+1}, \dots, \beta_m)$ ($s=0, 1, \dots, m$) and $|\alpha| \geq 0, |\beta| \geq 0$. Similarly we can define the seminorms and the norms for discrete functions in Sobolev spaces as follows.

$$\|u_\Delta\|_{L^p(Q_T)}^p = \sum_{|\alpha|=k} \|\delta^\alpha u_\Delta\|_{L^p(Q_T)}^p \tag{5}$$

and

$$\|u_\Delta\|_{W^p(Q_T)}^p = \|u_\Delta\|_{L^p(Q_T)}^p + \|u_\Delta\|_{L^p(Q_T)}^p, \tag{6}$$

where $1 \leq p < \infty$ and $k \geq 0$. As $p=2$, we have $W_2^{(k)}(Q_\Delta^m) = H^k(Q_\Delta^m)$.

§ 4

Now we turn to prove the interpolation formulas for the discrete functions with several indices.

Theorem 2. For any discrete function $u_\Delta = \{u_{j_1, \dots, j_m}\}$ with m -index defined on the discrete rectangular domain $Q_\Delta^m = \{(a_{1j_1}, \dots, a_{mj_m})\}$ ($j_i = 0, 1, \dots, J_i; i = 1, 2, \dots, m$), there is the interpolation relation

$$\|u_\Delta\|_{L^p(Q_T)} \leq K_2 \|u_\Delta\|_{L^1(Q_T)}^{1-\frac{k}{n}} \left\{ \|u_\Delta\|_{L^1(Q_T)} + \frac{\|u_\Delta\|_{L^2(Q_T)}}{l^{\frac{k}{n}}} \right\}^{\frac{k}{n}}, \tag{7}$$

where $0 \leq k \leq n$, $m \geq 1$ and K_2 is a constant independent of the steplengths h_i ($i = 1, 2, \dots, m$), the minimum width l of Q^m and the discrete function u_Δ .

Proof. When $m=1$, the theorem reduces to the Theorem 1 for $p=2$.

Suppose that the theorem is valid for the discrete functions with not more than $(m-1)$ indices, where $m \geq 2$.

Let $\beta = (\beta_2, \dots, \beta_m)$ be a $(m-1)$ -index ($m \geq 2$) and $|\beta| = \beta_2 + \dots + \beta_m = k - r \geq 0$. Then we have

$$J^2 = \|\delta_1^r \delta_1^\beta u_\Delta\|_{L_1(Q_T)}^2 = \sum_{j_1=0}^{J_1-r} \sum_{j_2=0}^m \sum_{j_3=0}^{J_3-\beta_3} \dots \sum_{j_m=0}^{J_m-\beta_m} \left| \frac{\Delta_1^r \Delta_1^\beta u_{j_1, j_2, \dots, j_m}}{h_1^r h^\beta} \right|^2 h_1 h_2 \dots h_m. \tag{8}$$

Regarding $\frac{\Delta_1^r \Delta_1^\beta u_{j_1, j_2, \dots, j_m}}{h_1^r h^\beta}$ as the discrete function with $(m-1)$ indices j_2, \dots, j_m , we have from induction assumption.

$$\begin{aligned} \sum_{j_2=0}^m \sum_{j_3=0}^{J_3-\beta_3} \dots \sum_{j_m=0}^{J_m-\beta_m} \left| \frac{\Delta_1^r \Delta_1^\beta u_{j_1, j_2, \dots, j_m}}{h_1^r h^\beta} \right|^2 h_2 \dots h_m &= \left\| \frac{\Delta_1^r}{h_1^r} \delta_1^\beta u_{j_1, \dots} \right\|_{L_1(Q_T^{-1})}^2 \\ &\leq K_2^2 \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})}^{2(1-\frac{k-r}{n-r})} \left\{ \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})} + \frac{1}{l^{n-r}} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})} \right\}^{2\frac{k-r}{n-r}}, \end{aligned}$$

where $l = \min_{i=2, 3, \dots, m} \{l_i\}$. Then (8) becomes

$$\begin{aligned} J^2 &\leq 4K_2^2 \sum_{j_1=0}^{J_1-r} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})}^{2(1-\frac{k-r}{n-r})} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})}^{2\frac{k-r}{n-r}} h_1 + \frac{4K_2^2}{l^{2(k-r)}} \sum_{j_1=0}^{J_1-r} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{-1})}^2 h_1 \\ &\leq 4K_2^2 \left\| \delta_1^r u_\Delta \right\|_{L_1(Q_T)}^{2(1-\frac{k-r}{n-k})} \left\| \delta_1^r u_\Delta \right\|_{L_1(Q_T)}^{2\frac{k-r}{n-r}} + \frac{4K_2^2}{l^{2(k-r)}} \left\| \delta_1^r u_\Delta \right\|_{L_1(Q_T)}^2. \end{aligned} \tag{9}$$

Here we have

$$\|\delta_1^r u_\Delta\|_{L_1(Q_T)}^2 \leq \|u_\Delta\|_{L^p(Q_T)}^2 \tag{10}$$

And also from Theorem 1, we have

$$\begin{aligned} \|\delta_1^r u_\Delta\|_{L_1(Q_T)}^2 &= \sum_{j_1=0}^{J_1-r} \sum_{j_2=0}^{J_2} \dots \sum_{j_m=0}^{J_m} \|\delta_1^r u_{j_1, j_2, \dots, j_m}\|_{L_1(Q_1)}^2 h_2 \dots h_m \\ &\leq 4K_1^2 \sum_{j_1=0}^{J_1-r} \sum_{j_2=0}^{J_2} \dots \sum_{j_m=0}^{J_m} \|u_{j_1, j_2, \dots, j_m}\|_{L_1(Q_1)}^{2(1-\frac{k-r}{n})} \left\| \delta_1^r u_{j_1, j_2, \dots, j_m} \right\|_{L_1(Q_1)}^{2\frac{k-r}{n}} h_2 \dots h_m \end{aligned}$$

$$\begin{aligned}
 & + \frac{4K_1^2}{l_1^{2r}} \sum_{i=2}^m \sum_{j_i=0}^{J_i} \|u_{\dots, j_i, \dots, j_m}\|_{L_1(Q_i)}^2 h_2 \dots h_m \\
 & \leq 4K_1^2 \|u_\Delta\|_{L_1(Q_T)}^{2(1-\frac{r}{n})} \|u_\Delta\|_{L_1^{(r)}(Q_T)}^{\frac{2r}{n}} + \frac{4K_1^2}{l_1^{2r}} \|u_\Delta\|_{L_1(Q_T)}^2
 \end{aligned} \tag{11}$$

Substituting (10) and (11) into (9), we obtain by direct calculation

$$\begin{aligned}
 J & \leq 4K_1 K_2 \|u_\Delta\|_{L_1(Q_T)}^{1-\frac{k}{n}} \left\{ \|u_\Delta\|_{L_1^{(r)}(Q_T)} + \left(\frac{\|u_\Delta\|_{L_1(Q_T)}}{l_1^n} \right)^{\frac{r(n-k)}{k(n-r)}} \|u_\Delta\|_{L_1^{(r)}(Q_T)}^{\frac{n(k-r)}{k(n-r)}} \right. \\
 & \quad \left. + \left(\frac{\|u_\Delta\|_{L_1(Q_T)}}{l_1^n} \right)^{1-\frac{r}{k}} \|u_\Delta\|_{L_1^{(r)}(Q_T)}^{\frac{r}{k}} + \frac{\|u_\Delta\|_{L_1(Q_T)}^{\frac{k}{n}}}{l_1^n \left(\frac{l_1}{l} \right)^{\frac{rn}{k}}} \right\}.
 \end{aligned}$$

Then we get the estimate

$$J \leq O_1 \|u_\Delta\|_{L_1(Q_T)}^{1-\frac{k}{n}} \left\{ \|u_\Delta\|_{L_1^{(r)}(Q_T)} + \frac{\|u_\Delta\|_{L_1(Q_T)}^{\frac{k}{n}}}{l^n} \right\},$$

where $l = \min\{l_1, l\}$ and O_1 is a constant. This proves the interpolation formula (7).

§ 5

Theorem 3. For any discrete function $u_\Delta = \{u_{j_1, \dots, j_m}\}$ with m indices defined on $Q_\Delta^m = \{(x_{1j_1}, \dots, x_{mj_m})\}$ ($j_i = 0, 1, \dots, J_i; i = 1, 2, \dots, m$), there is the interpolation relation

$$\|u_\Delta\|_{L^\infty(Q_T)} \leq K_3 \|u_\Delta\|_{L_1(Q_T)}^{1-\frac{k+m}{n}} \left\{ \|u_\Delta\|_{L_1^{(r)}(Q_T)} + \frac{\|u_\Delta\|_{L_1(Q_T)}}{l^n} \right\}^{\frac{k+m}{n}}, \tag{12}$$

where $n \geq k+m$, $m \geq 1$ and K_3 is a constant independent of h_i ($i = 1, 2, \dots, m$), l and u_Δ .

Proof. When $m=1$, (12) becomes (2) as $p = \infty$.

Suppose that (12) is valid for the discrete functions with $(m-1)$ indices, where $m \geq 2$. Similarly denote $\beta = (\beta_2, \beta_3, \dots, \beta_m)$ and $|\beta| = \beta_2 + \dots + \beta_m = k-r \geq 0$.

Let us consider

$$J = \|\delta_1^r \delta_1^\beta u_\Delta\|_{L_1(Q_T)} = \max_{j_1=0, 1, \dots, J_1-r} \left\| \frac{\Delta_1^r}{h_1^r} \delta_1^\beta u_{j_1, \dots} \right\|_{L_1(Q_T^{(r)})}.$$

By induction assumption we get

$$\begin{aligned}
 J & \leq O_2 \max_{j_1=0, 1, \dots, J_1-r} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{(r)})}^{1-\frac{k-r+m-1}{n-r-1}} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1^{(r-\beta)}(Q_T^{(r)})}^{\frac{k-r+m-1}{n}} \\
 & \quad + \frac{O_3}{l^{(k-r+m-1)}} \max_{j_1=0, 1, \dots, J_1-r} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{(r)})}.
 \end{aligned} \tag{13}$$

Here we have

$$\max_{j_1=0, 1, \dots, J_1-r} \left\| \frac{\Delta_1^r u_{j_1, \dots}}{h_1^r} \right\|_{L_1(Q_T^{(r)})}^2 \leq \sum_{i=2}^m \sum_{j_i=0}^{J_i} \|\delta_1^r u_{\dots, j_i, \dots, j_m}\|_{L_1(Q_i)}^2 h_2 \dots h_m$$

$$\begin{aligned}
 & \leq O_4 \sum_{i=2}^m \sum_{j_i=0}^{J_i} \left\{ \|u_{\dots, j_i, \dots, j_m}\|_{L_1(Q_i)}^{2(1-\frac{r+\frac{1}{2}}{n})} \|\delta_1^r u_{\dots, j_i, \dots, j_m}\|_{L_1(Q_i)}^{\frac{2r+1}{n}} \right. \\
 & \quad \left. + \frac{1}{l_1^{2r+1}} \|u_{\dots, j_i, \dots, j_m}\|_{L_1(Q_i)}^{2r+2} \right\} h_2 \dots h_m \\
 & \leq O_5 \|u_\Delta\|_{L_1(Q_T)}^{2(1-\frac{r+\frac{1}{2}}{n})} \|\delta_1^r u_\Delta\|_{L_1(Q_T)}^{\frac{2r+1}{n}} + \frac{1}{l_1^{2r+1}} \|u_\Delta\|_{L_1(Q_T)}^{2r+2}
 \end{aligned}$$

On the other hand we also have

$$\begin{aligned} & \max_{j_1=0,1,\dots,J_1-r} \left\| \frac{\Delta_1^r u_{j_1,\dots}}{h_1^r} \right\|_{L^{(n-r-1)}(Q_T)}^2 \\ & \leq \sum_{|\beta|=n-r-1} \sum_{i=2}^m \sum_{j_i=0}^{J_i-\beta_i} \left\| \frac{\Delta_1^\beta \delta_1^i u_{j_1,\dots,j_m}}{h^\beta} \right\|_{L_1(Q)}^2 h_2 h_3 \dots h_m \\ & \leq O_4 \sum_{|\beta|=n-r-1} \sum_{i=2}^m \sum_{j_i=0}^{J_i-\beta_i} \left\{ \left\| \frac{\Delta_1^\beta u_{j_1,\dots,j_m}}{h^\beta} \right\|_{L_1(Q)}^{\frac{1}{r+1}} \left\| \delta_1^{r+1} \frac{\Delta_1^\beta u_{j_1,\dots,j_m}}{h^\beta} \right\|_{L_1(Q)}^{\frac{2r+1}{r+1}} \right. \\ & \quad \left. + \frac{1}{l_1^{2r+1}} \left\| \frac{\Delta_1^\beta u_{j_1,\dots,j_m}}{h^\beta} \right\|_{L_1(Q)}^2 \right\} h_2^{r+1} \dots h_m^{r+1} \\ & \leq O_4 \left\| u_\Delta \right\|_{L_1^{r+1}(Q_T)}^{\frac{1}{r+1}} \left\| u_\Delta \right\|_{L_1^{2r+1}(Q_T)}^{\frac{2r+1}{r+1}} + \frac{O_4}{l_1^{2r+1}} \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)} \end{aligned}$$

From Theorem 2, there is

$$\left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)} \leq O_5 \left\| u_\Delta \right\|_{L_1(Q_T)}^{\frac{r+1}{n}} \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)}^{\frac{n-r-1}{n}} + \frac{O_5}{l_1^{n-r-1}} \left\| u_\Delta \right\|_{L_1(Q_T)}$$

Substituting the last relation into the previous inequality, we obtain

$$\max_{j_1=0,1,\dots,J_1-r} \left\| \frac{\Delta_1^r u_{j_1,\dots}}{h_1^r} \right\|_{L_1^{(n-r-1)}(Q_T)} \leq O_6 \left\| u_\Delta \right\|_{L_1(Q_T)}^{\frac{1}{2n}} \left\{ \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)} + \frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l_1^n} \right\}^{1-\frac{1}{2n}}, \quad (15)$$

where O_6 is a constant independent of u_Δ .

Substituting (14) and (15) into the right hand part of (13), we have the expression

$$\begin{aligned} J & \leq O_7 \left\| u_\Delta \right\|_{L_1(Q_T)}^{1-\frac{k+\frac{m}{2}}{n}} \left\{ \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)} \right. \\ & \quad + \left(\frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l_1^n} \right)^{\frac{(n-\frac{1}{2})(k-r+\frac{m-1}{2})}{(k+\frac{m}{2})(n-r-1)}} \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)}^{\frac{(r+\frac{1}{2})(n-k-\frac{m+1}{2})}{(k+\frac{m}{2})(n-r-1)}} \\ & \quad + \left(\frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l_1^n} \right)^{\frac{(r+\frac{1}{2})(n-k-\frac{m+1}{2})}{(k+\frac{m}{2})(n-r-1)}} \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)}^{\frac{(n-\frac{1}{2})(k-r+\frac{m-1}{2})}{(k+\frac{m}{2})(n-r-1)}} \\ & \quad + \left(\frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l_1^n} \right)^{\frac{k-r+\frac{m-1}{2}}{n}} \left\| u_\Delta \right\|_{L_1^{r+\frac{1}{2}}(Q_T)}^{\frac{r+\frac{1}{2}}{n}} \\ & \quad \left. + \frac{\left\| u_\Delta \right\|_{L_1(Q_T)} + \frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l_1^n}}{\left(\frac{l_1}{l} \right)^{\frac{n(r+\frac{1}{2})(n-\frac{1}{2})}{(k+\frac{m}{2})(n-r-1)}} \left(\frac{l}{l_1} \right)^{\frac{n}{n-r-1}}} + \frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{\left(\frac{l}{l} \right)^{\frac{k+\frac{m}{2}}{n}}} \right\} \end{aligned} \quad (31)$$

Replacing l and l_1 by the minimum width l of rectangular domain Q^m and using the inequality $A^{1-\alpha} B^\alpha \leq (1-\alpha)A + \alpha B$ ($0 < \alpha < 1$, $A > 0$, $B > 0$), we obtain

$$J \leq O_8 \left\| u_\Delta \right\|_{L_1(Q_T)}^{1-\frac{k+\frac{m}{2}}{n}} \left\{ \left\| u_\Delta \right\|_{L_1^{n-r-1}(Q_T)} + \frac{\left\| u_\Delta \right\|_{L_1(Q_T)}}{l^n} \right\}^{\frac{k+\frac{m}{2}}{n}}$$

where O_8 is a constant independent of h_i ($i=1, 2, \dots, m$), l and u_Δ . This implies (12) and then the theorem is proved.

§ 6

From the theorems obtained in the previous sections, we can verify immediately the following theorems.

Theorem 4. For any discrete function $u_\Delta = \{u_{j_1, j_2, \dots, j_m}\}$ defined on $R_\Delta^m = \{(x_{1j_1}, \dots, x_{mj_m})\}$, $(j_1, \dots, j_m = 0, \pm 1, \pm 2, \dots)$ for $m \geq 1$, there are interpolation formulas

$$\|u_\Delta\|_{L_1^\infty(Q_T^m)} \leq K_4 \|u_\Delta\|_{L_1(Q_T^m)}^{1-\frac{k}{n}} \|u_\Delta\|_{L_1^\infty(Q_T^m)}^{\frac{k}{n}}, \quad 0 \leq k \leq n, \quad (16)$$

and

$$\|u_\Delta\|_{L_2^\infty(Q_T^m)} \leq K_5 \|u_\Delta\|_{L_2(Q_T^m)}^{1-\frac{k+m}{n}} \|u_\Delta\|_{L_2^\infty(Q_T^m)}^{\frac{k+m}{n}}, \quad 0 \leq k \leq n-m, \quad (17)$$

where K_4 and K_5 are constants independent of h_i ($i=1, \dots, m$) and u_Δ .

Theorem 5. For any discrete function $u_\Delta = \{u_{j_1, j_2, \dots, j_m}\}$ defined on Q_Δ^m (or R_Δ^m), then for any $\varepsilon > 0$, there is a constant $K(\varepsilon)$ such that

$$\|u_\Delta\|_{L_1^\infty(Q_T^m)} \leq \varepsilon \|u_\Delta\|_{L_1^\infty(Q_T^m)} + K(\varepsilon) \|u_\Delta\|_{L_1(Q_T^m)}, \quad 0 \leq k \leq n \quad (18)$$

and

$$\|u_\Delta\|_{L_2^\infty(Q_T^m)} \leq \varepsilon \|u_\Delta\|_{L_2^\infty(Q_T^m)} + K(\varepsilon) \|u_\Delta\|_{L_2(Q_T^m)}, \quad 0 \leq k \leq n-m, \quad (19)$$

where $K(\varepsilon)$ is independent of h_i ($i=1, 2, \dots, m$) and u_Δ .

Theorem 6. For any discrete function $u_\Delta = \{u_{j_1, j_2, \dots, j_m}\}$ defined on Q_Δ^m (or R_Δ^m) for $m \geq 1$, there is interpolation relation

$$\|u_\Delta\|_{L_p^\infty(Q_T^m)} \leq K_6 \|u_\Delta\|_{L_2(Q_T^m)}^{1-\frac{k+\frac{m}{2}-\frac{m}{p}}{n}} \left\{ \|u_\Delta\|_{L_1^\infty(Q_T^m)} + \frac{\|u_\Delta\|_{L_2(Q_T^m)}}{l^n} \right\}^{\frac{k+\frac{m}{2}-\frac{m}{p}}{n}}, \quad (20)$$

where $0 \leq k \leq n-m$, $2 \leq p \leq \infty$ and K_6 is independent of h_i ($i=1, 2, \dots, m$), l and u_Δ .

In fact we have

$$\|u_\Delta\|_{L_p^\infty(Q_T^m)}^p \leq \|u_\Delta\|_{L_2^\infty(Q_T^m)}^{p-2} \|u_\Delta\|_{L_1^\infty(Q_T^m)}^2.$$

Then (20) follows immediately by substituting (7) and (12) into the right hand part of the above inequality.

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