

ON STABILITY AND CONVERGENCE OF THE FINITE DIFFERENCE METHODS FOR THE NONLINEAR PSEUDO-PARABOLIC SYSTEM*

Du Ming-sheng

(Institute of Applied Physics and Computational Mathematics, Beijing, China)

Abstract

In this paper, we deal with the finite difference method for the initial boundary value problem of the nonlinear pseudo-parabolic system

$$\begin{aligned} (-1)^M u_t + A(x, t, u, u_x, \dots, u_{x^{2M-1}}) u_{x^{2M}} &= F(x, t, u, u_x, \dots, u_{x^{2M}}), \\ u_{x^k}(0, t) = \psi_{0k}(t), \quad u_{x^k}(L, t) = \psi_{1k}(t), \quad k = 0, 1, \dots, M-1, \quad u(x, 0) &= \phi(x) \end{aligned}$$

in the rectangular domain $D = [0 \leq X \leq L, 0 \leq t \leq T]$, where $u(x, t) = (u_1(x, t), u_2(x, t), \dots, u_m(x, t))$, $\phi(x)$, $\psi_{0k}(t)$, $\psi_{1k}(t)$, $F(x, t, u, u_x, \dots, u_{x^{2M}})$ are m -dimensional vector functions, and $A(x, t, u, u_x, \dots, u_{x^{2M-1}})$ is an $m \times m$ positive definite matrix. The existence and uniqueness of solution for the finite difference system are proved by fixed-point theory. Stability, convergence and error estimates are derived.

§1

The linear and nonlinear pseudo-parabolic equations and systems often appear in practical research. There are many works contributed to the finite difference study of different problems for the nonlinear pseudo-parabolic equations. In this paper, we consider the nonlinear pseudo-parabolic system

$$(-1)^M u_t + A(x, t, u, u_x, \dots, u_{x^{2M-1}}) u_{x^{2M}} = F(x, t, u, u_x, \dots, u_{x^{2M}}) \quad (1.1)$$

with the nonhomogeneous boundary conditions

$$u_{x^k}(0, t) = \psi_{0k}(t), \quad u_{x^k}(L, t) = \psi_{1k}(t), \quad k = 0, 1, \dots, M-1 \quad (1.2)$$

and the initial condition

$$u(x, 0) = \phi(x), \quad (1.3)$$

in the rectangular domain $D = [0 \leq x \leq L, 0 \leq t \leq T]$, by the finite difference method, where $u(x, t) = (u_1(x, t), u_2(x, t), \dots, u_m(x, t))$ and $\phi(x)$, $\psi_{0k}(t)$, $\psi_{1k}(t)$, $F(x, t, u, u_x, \dots, u_{x^{2M}})$ are m -dimensional vector functions.

The equation for the long waves in nonlinear dispersion

$$u_t + f(u)_x = u_{xxt}$$

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is a simple special case of the system (1.1). Some evolutionary equations of Sobolev-Galpern type also belong to the system (1.1).

We make the following assumptions for the system (1.1)-(1.3):

(1) The system (1.1)-(1.3) has a unique smooth solution.

(2) $A(x, t, p_0, p_1, \dots, p_{2M-1})$ is an $m \times m$ symmetric positive definite matrix for $(x, t) \in D$ and $p_0, p_1, \dots, p_{2M-1} \in \mathbb{R}^m$. Or rather, there exists a constant $a_0 > 0$, such that for all $\xi \in \mathbb{R}^m$,

$$(A\xi, \xi) \geq a_0|\xi|^2.$$

(3) $A(x, t, p_0, p_1, \dots, p_{2M-1})$ is a continuous function with respect to $(x, t) \in D$ and it has the first order continuous partial derivatives with respect to $p_0, p_1, \dots, p_{2M-1} \in \mathbb{R}^m$ and with respect to $t \in [0, T]$.

(4) $F(x, t, p_0, p_1, \dots, p_{2M})$ is a continuous function with respect to $(x, t) \in D$ and it has the first order continuous partial derivatives with respect to $p_0, p_1, \dots, p_{2M} \in \mathbb{R}^m$.

(5) $\psi_{0k}(t) \in C^{(1)}([0, T]), \psi_{1k}(t) \in C^{(1)}([0, T])$ and $\phi(x) \in C^{(2M)}([0, L])$ satisfy the following conditions:

$$\psi_{0k}(0) = \phi_{x^k}(0), \quad \psi_{1k}(0) = \phi_{x^k}(L), \quad k = 0, 1, \dots, M-1.$$

Let us divide the rectangular domain D into small grids by the parallel lines $x = x_j$ ($j = 0, 1, \dots, J$) and $t = t^n$ ($n = 0, 1, \dots, N$), where $x_j = jh, t^n = n\tau, Jh = L, N\tau = T$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). Denote the vector valued discrete function on the grid point (x_j, t^n) by v_j^n ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). For simplicity, we adopt the same notations and abbreviations as used in [1-3].

Let us construct the finite difference system

$$\begin{aligned} (-1)^M \frac{v_j^{n+1} - v_j^n}{\tau} + A_j^{n+\alpha}(v) \frac{\Delta_+^M \Delta_-^M (v_j^{n+1} - v_j^n)}{\tau h^{2M}} = F_j^{n+\alpha}(v), \\ j = M, M+1, \dots, J-M; n = 0, 1, \dots, N-1 \end{aligned} \quad (1.4)$$

where

$$A_j^{n+\alpha}(v) = A(x_j, t^{n+\alpha}, \bar{\delta}^0 v_j^{n+\alpha}, \bar{\delta}^1 v_j^{n+\alpha}, \dots, \bar{\delta}^{M-1} v_j^{n+\alpha}, \bar{\delta}^M v_j^{n+\alpha}, \dots, \bar{\delta}^{2M-1} v_j^{n+\alpha}),$$

$$F_j^{n+\alpha}(v) = F(x_j, t^{n+\alpha}, \hat{\delta}^0 v_j^{n+\alpha}, \hat{\delta}^1 v_j^{n+\alpha}, \dots, \hat{\delta}^{M-1} v_j^{n+\alpha}, \hat{\delta}^M v_j^{n+\alpha}, \dots, \hat{\delta}^{2M} v_j^{n+\alpha}),$$

$$\bar{\delta}^k v_j^{n+\alpha} = \sum_{i=j-M}^{j+M-k} (\alpha \beta_{ki}^{(1)} \frac{\Delta_+^k v_i^{n+1}}{h^k} + \beta_{ki}^{(2)} \frac{\Delta_+^k v_i^n}{h^k}), \quad k = 0, 1, \dots, M-1,$$

$$\hat{\delta}^k v_j^{n+\alpha} = \sum_{i=j-M}^{j+M-k} (\alpha \beta_{ki}^{(3)} \frac{\Delta_+^k v_i^{n+1}}{h^k} + \beta_{ki}^{(4)} \frac{\Delta_+^k v_i^n}{h^k}), \quad k = 0, 1, \dots, M-1,$$

$$\sum_{i=j-M}^{j+M-k} (\alpha \beta_{ki}^{(1)} + \beta_{ki}^{(2)}) = 1, \quad \sum_{i=j-M}^{j+M-k} (\alpha \beta_{ki}^{(3)} + \beta_{ki}^{(4)}) = 1, \quad k = 0, 1, \dots, M-1,$$

$$v_j^{n+\alpha} = \alpha v_i^{n+1} + (1-\alpha)v_i^n, \quad 0 \leq \alpha \leq 1,$$

$$\bar{\delta}^k v_j^{n+\alpha} = \sum_{i=j-M}^{j+M-k} \bar{\beta}_{ki} \frac{\Delta_+^k v_i^{n+1}}{h^k}, \quad \sum_{i=j-M}^{j+M-k} \bar{\beta}_{ki} = 1, \quad k = M, M+1, \dots, 2M. \quad (1.5)$$

The corresponding finite difference boundary conditions are

$$\frac{\Delta_+^k v_0^n}{h^k} = \tilde{\psi}_{0k}^n, \quad \frac{\Delta_-^k v_J^n}{h^k} = \tilde{\psi}_{1k}^n, \quad k = 0, 1, \dots, M-1 \quad (1.6)$$

and the corresponding finite difference initial condition is

$$v_j^0 = \tilde{\phi}_j, \quad j = 0, 1, \dots, J. \quad (1.7)$$

Suppose that the initial-boundary condition satisfies

$$\begin{aligned} & \sum_{k=0}^{2M} \left\| \delta^k (\phi_h - \tilde{\phi}_h) \right\|_2 + \max_{n=0,1,\dots,N} \sum_{k=0}^{M-1} \left(\left| \psi_{0k}^n - \tilde{\psi}_{0k}^n \right| + \left| \psi_{1k}^n - \tilde{\psi}_{1k}^n \right| \right) \\ & + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{M-1} \left[\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right| \right. \\ & \left. + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right| \right] \leq c_0 (\tau + h) \end{aligned} \quad (1.8)$$

where c_0 is independent of τ and h .

§2

The following Lemmas 1-5 are easily verified by direct calculation .

Lemma 1. For any $\{u_j\}$ and $\{v_j\} (j = 0, 1, \dots, J)$, there are the relations

$$\sum_{j=0}^{J-1} u_j \Delta_+ v_j = - \sum_{j=1}^J v_j \Delta_- u_j - u_0 v_0 + u_J v_J, \quad (2.1)$$

$$\sum_{j=1}^{J-1} u_j \Delta_+ \Delta_- v_j = - \sum_{j=0}^{J-1} (\Delta_+ u_j) (\Delta_+ v_j) - u_0 \Delta_+ v_0 + u_J \Delta_- v_J. \quad (2.2)$$

Lemma 2. For any $\{w_j\} (j = 0, 1, \dots, J)$, there is the relation

$$\|w_h\|_\infty \leq \frac{\|w_h\|_2}{h^{1/2}}. \quad (2.3)$$

Lemma 3. For any $\{w_j\} (j = 0, 1, \dots, J)$, there is the relation

$$\|w_h\|_2^2 \leq 2L^2 \|\delta w_h\|_2^2 + 4L |w_0|^2. \quad (2.4)$$

When $\frac{\Delta_+^k w_0}{h^k} = \psi_{0k}$ and $\frac{\Delta_-^k w_J}{h^k} = \psi_{1k}$, $k = 0, 1, \dots, M-1$, we have

$$\|\delta^k v_h\|_2^2 \leq c_1 \left(\|\delta^M v_h\|_2^2 + \sum_{k=0}^{M-1} |\psi_{0k}|^2 + \sum_{k=0}^{M-1} |\psi_{1k}|^2 \right), \quad k = 0, 1, \dots, M-1, \quad (2.5)$$

where c_1 is independent of τ and h .

Lemma 4. Assume that the following statement is true: for any $w_h = \{w_n | n = 0, 1, \dots, N\}$,

$$w_n \leq A_0 + B_0 \sum_{k=1}^n w_k \tau, n = 0, 1, \dots, N, \quad (2.6)$$

where A_0 and B_0 are constants, $A_0 \geq 0, B_0 \geq 0$ and $B_0 < \frac{1}{2}$. Then, there is

$$\|w_h\|_{\infty} \leq A_0 \exp(2B_0 T). \quad (2.7)$$

Lemma 5. For any discrete function

$$w_h = \{w_j | \frac{\Delta_+^k w_0}{h^k} = \psi_{0k}, \frac{\Delta_-^k w_J}{h^k} = \psi_{1k}, k = 0, 1, \dots, M-1, j = 0, 1, \dots, J\}$$

there are the relations

$$w_k = \sum_{i=0}^k \binom{k}{i} h^i \psi_{0i}, k = 0, 1, \dots, M-1, \quad (2.8)$$

$$w_{J-k} = \sum_{i=0}^k (-1)^i \binom{k}{i} h^i \psi_{1i}, k = 0, 1, \dots, M-1, \quad (2.9)$$

$$\frac{\Delta_+^{k-1} w_{M-k}}{h^{k-1}} = \sum_{i=0}^{M-k} \binom{M-k}{i} h^i \psi_{0,i+k-1}, k = 1, 2, \dots, M, \quad (2.10)$$

$$\frac{\Delta_-^{k-1} w_{J-M+1}}{h^{k-1}} = \sum_{i=0}^{M-k} (-1)^i \binom{M-k}{i} h^i \psi_{1,i+k-1}, k = 1, 2, \dots, M. \quad (2.11)$$

Lemma 6. For any discrete function $v_h = \{v_j | j = 0, 1, \dots, J\}$ on the segment $[0, L]$ and for any given $\epsilon > 0$, there exists a constant $K(\epsilon, n)$ depending only on ϵ and n , such that

$$\|\delta^k v_h\|_2 \leq \epsilon \|\delta^n v_h\|_2 + K(\epsilon, n) \|v_h\|_2, 0 \leq k \leq n, \quad (2.12)$$

and

$$\|\delta^k v_h\|_{\infty} \leq \epsilon \|\delta^n v_h\|_2 + K(\epsilon, n) \|v_h\|_2, 0 \leq k < n, \quad (2.13)$$

where $K(\epsilon, n)$ is independent of v_h (see [3]).

§3

Now we are going to prove the existence of the solution $v_j^n (j = 0, 1, \dots, J, n = 0, 1, \dots, N)$ for the finite difference system (1.4), (1.6), (1.7) and to get a series of a priori estimates of the solution. Assume that $u(x, t)$ is the solution of the system (1.1)-(1.3). Then, we have

$$(-1)^M \frac{u_j^{n+1} - u_j^n}{\tau} + A_j^{n+\alpha}(u) \frac{\Delta_+^M \Delta_-^M (u_j^{n+1} - u_j^n)}{\tau h^{2M}} = F_j^{n+\alpha}(u) + R, \quad (3.1)$$

$$\frac{\Delta_+^k u_0^n}{h^k} = \psi_{0k}^n + O(h), \frac{\Delta_-^k u_J^n}{h^k} = \psi_{1k}^n + O(h), k = 0, 1, \dots, M-1, \quad (3.2)$$

$$u_j^0 = \phi_j, \quad (3.3)$$

where the truncation error $R = O(\tau + h)$.

Let $w_j^n = u_j^n - v_j^n$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). From (3.1), (3.2), (3.3) and (1.4), (1.6), (1.7), we get

$$\begin{aligned} & (-1)^M \frac{w_j^{n+1} - w_j^n}{\tau} + A_j^{n+\alpha}(v) \delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau} \\ & + \sum_{k=0}^{M-1} (E_k)_j^{n+\alpha}(u, v) \bar{\delta}^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau} \\ & + \sum_{k=M}^{2M-1} (E_k)_j^{n+\alpha}(u, v) \tilde{\delta}^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau} \\ & = \sum_{k=0}^{M-1} (G_k)_j^{n+\alpha}(u, v) \hat{\delta}^k w_j^{n+\alpha} + \sum_{k=M}^{2M} (G_k)_j^{n+\alpha}(u, v) \tilde{\delta}^k w_j^{n+\alpha} + R, \end{aligned} \quad (3.4)$$

$$\frac{\Delta_+^k w_0^n}{h^k} = \psi_{0k}^n - \tilde{\psi}_{0k}^n + O(h), \quad \frac{\Delta_-^k w_j^n}{h^k} = \psi_{1k}^n - \tilde{\psi}_{1k}^n + O(h), \quad k = 0, 1, \dots, M-1, \quad (3.5)$$

$$w_j^0 = \phi_j - \tilde{\phi}_j, \quad (3.6)$$

where

$$\begin{aligned} (E_k)_j^{n+\alpha}(u, v) &= \int_0^1 \frac{\partial A}{\partial p_k}(x_j, t^{n+\alpha}, \lambda \bar{\delta}^0 u_j^{n+\alpha} + (1-\lambda) \bar{\delta}^0 v_j^{n+\alpha}, \dots, \\ & \lambda \bar{\delta}^{M-1} u_j^{n+\alpha} + (1-\lambda) \bar{\delta}^{M-1} v_j^{n+\alpha}, \lambda \bar{\delta}^M u_j^{n+\alpha} + (1-\lambda) \bar{\delta}^M v_j^{n+\alpha}, \dots, \\ & \lambda \bar{\delta}^{2M-1} u_j^{n+\alpha} + (1-\lambda) \bar{\delta}^{2M-1} v_j^{n+\alpha}) d\lambda, \quad k = 0, 1, \dots, 2M-1, \end{aligned} \quad (3.7)$$

$$\begin{aligned} (G_k)_j^{n+\alpha}(u, v) &= \int_0^1 \frac{\partial F}{\partial p_k}(x_j, t^{n+\alpha}, \lambda \hat{\delta}^0 u_j^{n+\alpha} + (1-\lambda) \hat{\delta}^0 v_j^{n+\alpha}, \dots, \\ & \lambda \hat{\delta}^{M-1} u_j^{n+\alpha} + (1-\lambda) \hat{\delta}^{M-1} v_j^{n+\alpha}, \lambda \tilde{\delta}^M u_j^{n+\alpha} + (1-\lambda) \tilde{\delta}^M v_j^{n+\alpha}, \dots, \\ & \lambda \tilde{\delta}^{2M} u_j^{n+\alpha} + (1-\lambda) \tilde{\delta}^{2M} v_j^{n+\alpha}) d\lambda, \quad k = 0, 1, \dots, 2M, \end{aligned} \quad (3.8)$$

$$\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau} = \frac{\Delta_+^M \Delta_-^M (w_j^{n+1} - w_j^n)}{\tau h^{2M}}. \quad (3.9)$$

For simplicity, we write (3.4) in the form

$$(-1)^M \frac{w_j^{n+1} - w_j^n}{\tau} + L_2 + L_3 + L_4 = r_1 + r_2 + R, \quad (3.10)$$

where

$$\begin{aligned} L_2 &= A_j^{n+\alpha}(v) \delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, \\ L_3 &= \sum_{k=0}^{M-1} (E_k)_j^{n+\alpha}(u, v) \bar{\delta}^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau}, \\ L_4 &= \sum_{k=M}^{2M-1} (E_k)_j^{n+\alpha}(u, v) \tilde{\delta}^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau}, \end{aligned}$$

$$\begin{aligned}
r_1 &= \sum_{k=0}^{M-1} (G_k)_j^{n+\alpha} (u, v) \delta^k w_j^{n+\alpha}, \\
r_2 &= \sum_{k=M}^{2M} (G_k)_j^{n+\alpha} (u, v) \tilde{\delta}^k w_j^{n+\alpha}.
\end{aligned} \tag{3.11}$$

Now we will get a series of a priori estimates for the solution of the finite difference system (3.4), (3.5), (3.6).

Making the scalar product of the vector $\delta^{2M} w_j^{n+\alpha} h\tau$ with the finite difference system (3.10) and summing up the resulting relations for $j = M, M+1, \dots, J-M$, we get

$$\begin{aligned}
& (-1)^M \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, w_j^{n+1} - w_j^n) h + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, L_2) h\tau \\
& + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, L_3) h\tau + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, L_4) h\tau \\
& = \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, r_1) h\tau + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, r_2) h\tau + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, R) h\tau.
\end{aligned} \tag{3.12}$$

First, repeating formula (2.2) and the finite difference boundary condition (3.5), we obtain

$$\begin{aligned}
& (-1)^M \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, w_j^{n+1} - w_j^n) h \\
& = \frac{1}{2} \|\delta^M w_h^{n+1}\|_2^2 - \frac{1}{2} \|\delta^M w_h^n\|_2^2 + \left(\alpha - \frac{1}{2}\right) \|\delta^M (w_h^{n+1} - w_h^n)\|_2^2 + B_1,
\end{aligned} \tag{3.13}$$

where

$$\begin{aligned}
B_1 &= \sum_{k=1}^M (-1)^{M-k} \sum_{k=1}^M \left(\frac{\Delta_+^M \Delta_-^{M-k} w_{M-k}^{n+\alpha}}{h^{2M-k}}, \frac{\Delta_+^{k-1} (w_{M-k}^{n+1} - w_{M-k}^n)}{\tau h^{k-1}} \right) \tau \\
& - \sum_{k=1}^M (-1)^{M-k} \sum_{k=1}^M \left(\frac{\Delta_+^M \Delta_-^{M-k} w_{J-M}^{n+\alpha}}{h^{2M-k}}, \frac{\Delta_+^{k-1} (w_{J-M+1}^{n+1} - w_{J-M+1}^n)}{\tau h^{k-1}} \right) \tau.
\end{aligned} \tag{3.14}$$

Using Lemmas 5 and 6, we have

$$\begin{aligned}
|B_1| &\leq c_2 \tau \left\{ \|\delta^{2M} w_h^{n+\alpha}\|_2^2 + \|\delta^M w_h^{n+\alpha}\|_2^2 + \sum_{k=0}^{M-1} \left[\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right|^2 \right. \right. \\
& \left. \left. + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right|^2 \right] + O(h^2) \right\},
\end{aligned} \tag{3.15}$$

where c_2 is independent of τ and h .

Similarly, there is

$$\begin{aligned} \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, L_2) h \tau &= \frac{1}{2} \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+1}, A_j^{n+\alpha} \delta^{2M} w_j^{n+1}) h \\ &\quad - \frac{1}{2} \sum_{j=M}^{J-M} (\delta^{2M} w_j^n, A_j^{n+\alpha} \delta^{2M} w_j^n) h \\ &\quad + (\alpha - \frac{1}{2}) \sum_{j=M}^{J-M} (\delta^{2M} (w_j^{n+1} - w_j^n), A_j^{n+\alpha} \delta^{2M} (w_j^{n+1} - w_j^n)) h. \end{aligned} \quad (3.16)$$

Moreover, we have

$$\begin{aligned} \left| \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, L_3) h \tau \right| &\leq c_3(\bar{A}) \tau \left[\|\delta^{2M} w_h^{n+\alpha}\|_2^2 + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 \right. \\ &\quad \left. + \sum_{k=0}^{M-1} (|\psi_{0k}^{n+1} - \tilde{\psi}_{0k}^{n+1}|^2 + |\psi_{0k}^n - \tilde{\psi}_{0k}^n|^2 + |\psi_{1k}^{n+1} - \tilde{\psi}_{1k}^{n+1}|^2 + |\psi_{1k}^n - \tilde{\psi}_{1k}^n|^2) \right] + \tau O(h^2), \end{aligned} \quad (3.17)$$

where $c_3(\bar{A})$ is independent of τ and h , and

$$\bar{A} = \max_{\substack{n=0,1,\dots,N-1 \\ j=0,1,\dots,J}} \left(\left\| \frac{\partial A}{\partial p_0} \right\|_\infty, \left\| \frac{\partial A}{\partial p_1} \right\|_\infty, \dots, \left\| \frac{\partial A}{\partial p_{2M-1}} \right\|_\infty \right)_j^{n+\alpha}. \quad (3.18)$$

Similarly, we have

$$\begin{aligned} \left| \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+\alpha}, -L_4 + r_1 + r_2 + R) h \tau \right| &\leq c_4(\bar{A}, \bar{F}) \tau \left[\|\delta^{2M} w_h^{n+\alpha}\|_2^2 \right. \\ &\quad \left. + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 + \sum_{k=0}^{M-1} (|\psi_{0k}^{n+1} - \tilde{\psi}_{0k}^{n+1}|^2 + |\psi_{0k}^n - \tilde{\psi}_{0k}^n|^2 \right. \\ &\quad \left. + |\psi_{1k}^{n+1} - \tilde{\psi}_{1k}^{n+1}|^2 + |\psi_{1k}^n - \tilde{\psi}_{1k}^n|^2) + R^2 \right] + \tau O(h^2), \end{aligned} \quad (3.19)$$

where $c_4(\bar{A}, \bar{F})$ is independent of τ and h , and

$$\bar{F} = \max_{\substack{n=0,1,\dots,N-1 \\ j=0,1,\dots,J}} \left(\left\| \frac{\partial F}{\partial p_0} \right\|_\infty, \left\| \frac{\partial F}{\partial p_1} \right\|_\infty, \dots, \left\| \frac{\partial F}{\partial p_{2M}} \right\|_\infty \right)_j^{n+\alpha}. \quad (3.20)$$

Substituting (3.13), (3.15), (3.16), (3.17), (3.19) into the relation (3.12), we obtain

$$\begin{aligned} \frac{1}{2} \left(\|\delta^M w_h^{n+1}\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+1}, A_j^{n+\alpha}(v) \delta^{2M} w_j^{n+1}) h \right) &- \frac{1}{2} \left(\|\delta^M w_h^n\|_2^2 \right. \\ &\quad \left. + \sum_{j=M}^{J-M} (\delta^{2M} w_j^n, A_j^{n+\alpha}(v) \delta^{2M} w_j^n) h \right) + (\alpha - \frac{1}{2}) \left[\|\delta^M (w_h^{n+1} - w_h^n)\|_2^2 \right. \end{aligned}$$

$$\begin{aligned}
& + \sum_{j=M}^{J-M} (\delta^{2M} (w_j^{n+1} - w_j^n), A_j^{n+\alpha}(v) \delta^{2M} (w_j^{n+1} - w_j^n)) h \\
& \leq c_5(\bar{A}, \bar{F}) \tau (\|\delta^{2M} w_h^{n+\alpha}\|_2^2 + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 + Q^2),
\end{aligned} \tag{3.21}$$

where $c_5(\bar{A}, \bar{F})$ is a constant depending only on \bar{A} and \bar{F} , and

$$\begin{aligned}
Q^2 = R^2 + \sum_{k=0}^{M-1} & \left[\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right|^2 + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right|^2 \right. \\
& \left. + |\psi_{0k}^{n+1} - \tilde{\psi}_{0k}^{n+1}|^2 + |\psi_{0k}^n - \tilde{\psi}_{0k}^n|^2 + |\psi_{1k}^{n+1} - \tilde{\psi}_{1k}^{n+1}|^2 + |\psi_{1k}^n - \tilde{\psi}_{1k}^n|^2 \right] + O(h^2).
\end{aligned} \tag{3.22}$$

We assume

$$1/2 \leq \alpha \leq 1. \tag{3.23}$$

Thus, according to the assumption (2), there is

$$\left(\alpha - \frac{1}{2} \right) \left[\|\delta^M (w_h^{n+1} - w_h^n)\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} (w_j^{n+1} - w_j^n), A_j^{n+\alpha}(v) \delta^{2M} (w_j^{n+1} - w_j^n)) h \right] \geq 0. \tag{3.24}$$

Hence, we have

$$\begin{aligned}
& \frac{1}{2} (\|\delta^M w_h^{n+1}\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+1}, A_j^{n+\alpha+1}(v) \delta^{2M} w_j^{n+1}) h) \\
& - \frac{1}{2} (\|\delta^M w_h^n\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^n, A_j^{n+\alpha}(v) \delta^{2M} w_j^n) h) \\
& \leq c_5(\bar{A}, \bar{F}) \tau (\|\delta^{2M} w_h^{n+\alpha}\|_2^2 + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 + Q^2) \\
& + \left(\frac{\tau}{2} \right) \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+1}, \frac{A_j^{n+\alpha+1} - A_j^{n+\alpha}}{\tau} \delta^{2M} w_j^{n+1}) h.
\end{aligned} \tag{3.25}$$

Let

$$\bar{A} = \max_{\substack{n=0,1,\dots,N-1 \\ j=0,1,\dots,J}} \left\{ \left\| \frac{\partial A}{\partial p_0} \right\|_\infty, \left\| \frac{\partial A}{\partial p_1} \right\|_\infty, \dots, \left\| \frac{\partial A}{\partial p_{2M-1}} \right\|_\infty, \left\| A_j^{n+\alpha} \right\|_\infty, \left\| \frac{A_j^{n+\alpha+1} - A_j^{n+\alpha}}{\tau} \right\|_\infty \right\}. \tag{3.26}$$

Then, we have

$$\begin{aligned}
& \frac{1}{2} (\|\delta^M w_h^{n+1}\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{n+1}, A_j^{n+\alpha+1}(v) \delta^{2M} w_j^{n+1}) h) \\
& - \frac{1}{2} (\|\delta^M w_h^n\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^n, A_j^{n+\alpha}(v) \delta^{2M} w_j^n) h) \\
& \leq c_6(\bar{A}, \bar{F}) \tau (\|\delta^{2M} w_h^{n+1}\|_2^2 + \|\delta^{2M} w_h^n\|_2^2 + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 + Q^2).
\end{aligned} \tag{3.27}$$

Summing up the resulting relations (3.27) for $n = 0, 1, \dots, l$, we get

$$\begin{aligned} & \frac{1}{2} (\|\delta^M w_h^{l+1}\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{l+1}, A_j^{l+\alpha+1}(v) \delta^{2M} w_j^{l+1})_h) - \frac{1}{2} (\|\delta^M w_h^0\|_2^2 \\ & + \sum_{j=M}^{J-M} (\delta^{2M} w_j^0, A_j^\alpha(v) \delta^{2M} w_j^0)_h) \leq c_7(\check{A}, \bar{F}) \left(\sum_{n=0}^{l+1} (\|\delta^{2M} w_h^n\|_2^2 + \|\delta^M w_h^n\|_2^2) \tau + \bar{Q}^2 \right), \end{aligned} \quad (3.28)$$

where $c_7(\check{A}, \bar{F})$ is a constant depending only on \check{A} and \bar{F} , and

$$\begin{aligned} \bar{Q} = & R + \max_{n=0,1,\dots,N} \sum_{k=0}^{M-1} \left(|\psi_{0k}^n - \tilde{\psi}_{0k}^n| + |\psi_{1k}^n - \tilde{\psi}_{1k}^n| \right) \\ & + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{M-1} \left(\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right| \right. \\ & \left. + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right| \right) + O(h). \end{aligned} \quad (3.29)$$

Using the assumption (2), we have

$$\|\delta^M w_h^{l+1}\|_2^2 + \sum_{j=M}^{J-M} (\delta^{2M} w_j^{l+1}, A_j^{l+\alpha+1}(v) \delta^{2M} w_j^{l+1})_h \geq c_8 (\|\delta^{2M} w_h^{l+1}\|_2^2 + \|\delta^M w_h^{l+1}\|_2^2), \quad (3.30)$$

where $c_8 > 0$ is a constant independent of τ and h . Hence, we have

$$\begin{aligned} \|\delta^M w_h^{l+1}\|_2^2 + \delta^{2M} w_h^{l+1}\|_2^2 \leq & c_9(\check{A}, \bar{F}) \left(\sum_{n=0}^{l+1} (\|\delta^{2M} w_h^n\|_2^2 \right. \\ & \left. + \|\delta^M w_h^n\|_2^2) \tau + \|\delta^{2M} w_h^0\|_2^2 + \|\delta^M w_h^0\|_2^2) \tau + \bar{Q}^2 \right), \end{aligned} \quad (3.31)$$

where $c_9(\check{A}, \bar{F})$ is a constant depending only on \check{A} and \bar{F} .

From Lemma 4, when τ is sufficiently small, we get the estimate

$$\max_{n=0,1,\dots,N} (\|\delta^M w_h^n\|_2^2 + \delta^{2M} w_h^n\|_2^2) \leq c_{10}(\check{A}, \bar{F}) (\|\delta^{2M} w_h^0\|_2^2 + \|\delta^M w_h^0\|_2^2) + \bar{Q}^2, \quad (3.32)$$

where $c_{10}(\check{A}, \bar{F})$ is a constant depending only on \check{A} and \bar{F} .

From Lemmas 3 and 6, we obtain

$$\max_{n=0,1,\dots,N} \|\delta^k w_h^n\|_2^2 \leq c_{11}(\check{A}, \bar{F}) \left(\sum_{l=0}^{2M} \|\delta^l w_h^0\|_2^2 + \bar{Q} \right), \quad k = 0, 1, \dots, 2M, \quad (3.33)$$

where $c_{11}(\check{A}, \bar{F})$ is a constant depending only on \check{A} and \bar{F} .

Now we estimate $\delta^k \left(\frac{w_h^{n+1} - w_h^n}{\tau} \right)$, $k = 0, 1, \dots, 2M$. Similarly, making the scalar product of the vector $\delta^{2M} \left(\frac{w_j^{n+1} - w_j^n}{\tau} \right) h$ with the finite difference system (3.10) and summing up

the resulting relations for $j = M, M + 1, \dots, J - M$, we get

$$\begin{aligned}
& (-1)^M \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, \frac{w_j^{n+1} - w_j^n}{\tau} \right) h + \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, L_2 \right) h \\
& + \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, L_3 \right) h + \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, L_4 \right) h \\
& = \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, r_1 \right) h + \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, r_2 \right) h \\
& + \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, R \right) h. \tag{3.34}
\end{aligned}$$

First, using Lemma 1 and the finite difference boundary condition (3.5), we obtain

$$(-1)^M \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, \frac{w_j^{n+1} - w_j^n}{\tau} \right) h = \left\| \delta^M \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2^2 + B_2, \tag{3.35}$$

where

$$\begin{aligned}
B_2 &= (-1)^{M-k} \sum_{k=1}^M \left(\frac{\Delta_+^M \Delta_-^{M-k} (w_{M-k}^{n+1} - w_{M-k}^n)}{\tau h^{2M-k}}, \frac{\Delta_+^{k-1} (w_{M-k}^{n+1} - w_{M-k}^n)}{\tau h^{k-1}} \right) \\
&- (-1)^{M-k} \sum_{k=1}^M \left(\frac{\Delta_+^M \Delta_-^{M-k} (w_{J-M}^{n+1} - w_{J-M}^n)}{\tau h^{2M-k}}, \frac{\Delta_+^{k-1} (w_{J-M+1}^{n+1} - w_{J-M+1}^n)}{\tau h^{k-1}} \right). \tag{3.36}
\end{aligned}$$

Using Lemmas 5 and 6, we have

$$\begin{aligned}
|B_2| &\leq c_{12} \varepsilon_1 \left(\left\| \delta^{2M} \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2^2 + \left\| \delta^M \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2^2 \right) + c_{13} (\varepsilon_1) \sum_{k=0}^{M-1} \left(\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} \right. \right. \\
&\quad \left. \left. - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right|^2 + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right|^2 \right) + O(h^2), \tag{3.37}
\end{aligned}$$

where c_{12}, c_{13} are independent of τ and h .

Moreover, we have

$$\begin{aligned}
& \left| \sum_{j=M}^{J-M} \left(\delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau}, -L_3 - L_4 + r_1 + r_2 + R \right) h \right| \\
& \leq \left(\frac{5a_0}{8} \right) \left\| \delta^{2M} \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2^2 + c_{14} (\bar{A}, F) \left(\left\| \delta^{2M} w_h^{n+\alpha} \right\|_2^2 \right. \\
& \quad \left. + \left\| \delta^M w_h^{n+1} \right\|_2^2 + \left\| \delta^M w_h^n \right\|_2^2 + \sum_{k=0}^{M-1} \left[\left| \psi_{0k}^{n+1} - \tilde{\psi}_{0k}^{n+1} \right|^2 + \left| \psi_{0k}^n - \tilde{\psi}_{0k}^n \right|^2 \right. \right. \\
& \quad \left. \left. + \left| \psi_{1k}^{n+1} - \tilde{\psi}_{1k}^{n+1} \right|^2 + \left| \psi_{1k}^n - \tilde{\psi}_{1k}^n \right|^2 \right] + R^2 \right) + O(h^2), \tag{3.38}
\end{aligned}$$

where c_{14} is independent of τ and h .

We take ϵ_1 , such that

$$\epsilon_1 c_{12} \leq \frac{a_0}{8}. \tag{3.39}$$

Substituting (3.37),(3.39) into the relation (3.34), we obtain

$$\begin{aligned} & \|\delta^M \frac{w_h^{n+1} - w_h^n}{\tau}\|_2^2 + (\frac{a_0}{4}) \|\delta^{2M} \frac{w_h^{n+1} - w_h^n}{\tau}\|_2^2 \\ & \leq c_{15}(\bar{A}, \bar{F}) (\|\delta^{2M} w_h^{n+\alpha}\|_2^2 + \|\delta^M w_h^{n+1}\|_2^2 + \|\delta^M w_h^n\|_2^2 + Q^2), \end{aligned} \tag{3.40}$$

where $c_{15}(\bar{A}, \bar{F})$ is a constant depending only on \bar{A} and \bar{F} .

From (3.33), we obtain

$$\max_{n=0,1,\dots,N} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2^2 \leq c_{16}(\bar{A}, \bar{F}) \left(\sum_{l=0}^{2M} \|\delta^l w_h^0\|_2^2 + \bar{Q} \right), \quad k = 0, 1, \dots, 2M, \tag{3.41}$$

where $c_{16}(\bar{A}, \bar{F})$ is a constant depending only on \bar{A} and \bar{F} .

Hence we have the following theorem.

Theorem 1. *Under conditions (1)–(5) and (3.23), assume that the solution u of system (1.1)–(1.3) has $|\delta^k u_j^n| \leq \bar{M} (j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M)$, and $|\delta^k \frac{u_j^{n+1} - u_j^n}{\tau}| \leq \bar{M} (j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M)$. Then, when τ and h are sufficiently small, there exists the solution $\{w_j^n\} (j = 0, 1, \dots, J; n = 0, 1, \dots, N)$ of system (3.4)–(3.6), such that $|\delta^k w_j^n| \leq \bar{M} (j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M)$ and $|\delta^k \frac{w_j^{n+1} - w_j^n}{\tau}| \leq \bar{M}, (j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M)$.*

Proof. For any discrete function $z = \{z_j^n | j = 0, 1, \dots, J; n = 0, 1, \dots, N\}$, we construct the following mapping Φ , which maps $z \in \mathcal{R}^{m(J+1)(N+1)}$ onto $w \in \mathcal{R}^{m(J+1)(N+1)}$:

$$\begin{aligned} & (-1)^M \frac{w_j^{n+1} - w_j^n}{\tau} + A_j^{n+\alpha} (u - z) \delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau} \\ & + \sum_{k=0}^{M-1} (E_k)_j^{n+\alpha} (u, u - z) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau} \\ & + \sum_{k=M}^{2M-1} (E_k)_j^{n+\alpha} (u, u - z) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{u_j^{n+1} - u_j^n}{\tau} \\ & = \sum_{k=0}^{M-1} (G_k)_j^{n+\alpha} (u, u - z) \delta^k w_j^{n+\alpha} + \sum_{k=M}^{2M} (G_k)_j^{n+\alpha} (u, u - z) \delta^k w_j^{n+\alpha} + R, \end{aligned} \tag{3.42}$$

$$\frac{\Delta_+^k w_0^n}{h^k} = \psi_{0k}^n - \tilde{\psi}_{0k}^n + O(h), \quad \frac{\Delta_-^k w_J^n}{h^k} = \psi_{1k}^n - \tilde{\psi}_{1k}^n + O(h), \quad k = 0, 1, \dots, M-1, \tag{3.43}$$

$$w_j^0 = \phi_j - \tilde{\phi}_j, \tag{3.44}$$

where

$$\begin{aligned} (E_k)_j^{n+\alpha}(u, u-z) &= \int_0^1 \frac{\partial A}{\partial p_k}(x_j, t^{n+\alpha}, \delta^0 u_j^{n+\alpha} - (1-\lambda)\delta^0 z_j^{n+\alpha}, \dots, \\ &\quad \delta^{M-1} u_j^{n+\alpha} - (1-\lambda)\delta^{M-1} z_j^{n+\alpha}, \tilde{\delta}^M u_j^{n+\alpha} - (1-\lambda)\tilde{\delta}^M z_j^{n+\alpha}, \dots, \\ &\quad \tilde{\delta}^{2M-1} u_j^{n+\alpha} - (1-\lambda)\tilde{\delta}^{2M-1} z_j^{n+\alpha}) d\lambda, \quad k=0, 1, \dots, 2M-1, \end{aligned} \quad (3.45)$$

$$\begin{aligned} (G_k)_j^{n+\alpha}(u, u-z) &= \int_0^1 \frac{\partial F}{\partial p_k}(x_j, t^{n+\alpha}, \hat{\delta}^0 u_j^{n+\alpha} - (1-\lambda)\hat{\delta}^0 z_j^{n+\alpha}, \dots, \\ &\quad \hat{\delta}^{M-1} u_j^{n+\alpha} - (1-\lambda)\hat{\delta}^{M-1} z_j^{n+\alpha}, \tilde{\delta}^M u_j^{n+\alpha} - (1-\lambda)\tilde{\delta}^M z_j^{n+\alpha}, \dots, \\ &\quad \tilde{\delta}^{2M} u_j^{n+\alpha} - (1-\lambda)\tilde{\delta}^{2M} z_j^{n+\alpha}) d\lambda, \quad k=0, 1, \dots, 2M. \end{aligned} \quad (3.46)$$

Let

$$\begin{aligned} \Omega &= \left\{ z = \{z_j^n\} \mid |\delta^k z_j^n| \leq \bar{M}, (j=0, 1, \dots, J; n=0, 1, \dots, N; k=0, 1, \dots, 2M), \right. \\ &\quad \left. \left| \delta^k \frac{z_j^{n+1} - z_j^n}{\tau} \right| \leq \bar{M}, (j=0, 1, \dots, J; n=0, 1, \dots, N; k=0, 1, \dots, 2M) \right\}. \end{aligned} \quad (3.47)$$

Repeating the procedure of the proof in §3, we can obtain

$$\max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_2 + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \leq K_1(\bar{A}, F) \left(\sum_{k=0}^{2M} \|\delta^k w_h^0\|_2 + \bar{Q} \right), \quad (3.48)$$

where $K_1(\bar{A}, F)$ is a constant depending only on \bar{A} and F . When $z \in \Omega$, from the assumption (3) and (4), the relations (3.26), (3.20) can be replaced respectively by the following

$$\bar{A} = \max_{\substack{(z,t) \in D \\ |p_0|, \dots, |p_{2M-1}| \leq 2\bar{M}}} \left\{ \begin{array}{l} \left\| \frac{\partial A}{\partial p_0} \right\|_\infty, \left\| \frac{\partial A}{\partial p_1} \right\|_\infty, \dots, \left\| \frac{\partial A}{\partial p_{2M-1}} \right\|_\infty, \\ \left\| A \right\|_\infty, \left\| \frac{\partial A}{\partial t} \right\|_\infty \end{array} \right\} \leq K_2 \quad (3.49)$$

and

$$F = \max_{\substack{(z,t) \in D \\ |p_0|, \dots, |p_{2M}| \leq 2\bar{M}}} \left(\left\| \frac{\partial F}{\partial p_0} \right\|_\infty, \left\| \frac{\partial F}{\partial p_1} \right\|_\infty, \dots, \left\| \frac{\partial F}{\partial p_{2M}} \right\|_\infty \right) \leq K_3. \quad (3.50)$$

Consequently, there are

$$\max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_2 + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \leq K_4 \left(\sum_{k=0}^{2M} \|\delta^k w_h^0\|_2 + \bar{Q} \right). \quad (3.51)$$

Here K_2, K_3, K_4 are independent of h and τ .

From (1.8), we have

$$\max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_2 + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \leq K_5(\tau + h), \quad (3.52)$$

where K_5 is independent of h and τ .

From Lemma 2 , we get

$$\max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_\infty + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_\infty \leq K_5 \left(\frac{\tau}{h^{\frac{1}{2}}} + h^{\frac{1}{2}} \right). \quad (3.53)$$

Taking

$$h^{\frac{1}{2}} \leq \frac{\bar{M}}{2K_5}, \quad \frac{\tau}{h^{\frac{1}{2}}} \leq \frac{\bar{M}}{2K_5}, \quad (3.54)$$

we have the following estimates:

$$|\delta^k w_j^n| \leq \bar{M}, \quad j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M \quad (3.55)$$

and

$$\left| \delta^k \frac{w_j^{n+1} - w_j^n}{\tau} \right| \leq \bar{M}, \quad j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M. \quad (3.56)$$

Therefore ,

$$\Phi(\Omega) \subset \Omega. \quad (3.57)$$

In addition, Ω is a convex set and Φ is continuous. From Brouwer's theorem, the mapping Φ has at least one fixed-point w , such that $\Phi w = w$. Obviously, this $\{w_j^n\}$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$) is the solution of the system (3.4)–(3.6). Theorem 1 is proved .

Corollary 1. Under the same assumptions as in Theorem 1, the finite difference system (1.4), (1.6), (1.7) has at least one solution $\{v_j^n\}$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). Moreover, we have the estimates

$$|\delta^k v_j^n| \leq 2\bar{M}, \quad j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M \quad (3.58)$$

and

$$\left| \delta^k \frac{v_j^{n+1} - v_j^n}{\tau} \right| \leq 2\bar{M}, \quad j = 0, 1, \dots, J; n = 0, 1, \dots, N; k = 0, 1, \dots, 2M. \quad (3.59)$$

§4

In this section we shall derive uniqueness, stability, convergence and error estimates .

First, we can obtain the following uniqueness theorem.

Theorem 2. Under the same assumptions as in Theorem 1, the finite difference system (1.4), (1.6), (1.7) has a unique solution $\{v_j^n\}$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$) .

Proof. Assume that $\{v_j^n\}$ and $\{\bar{v}_j^n\}$ are two solutions of the finite difference system (1.4), (1.6), (1.7). Let $w_j^n = v_j^n - \bar{v}_j^n$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). We can obtain

$$\begin{aligned}
& (-1)^M \frac{w_j^{n+1} - w_j^n}{\tau} + A_j^{n+\alpha}(\bar{v}) \delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau} \\
& + \sum_{k=0}^{M-1} (E_k)_j^{n+\alpha}(v, \bar{v}) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{v_j^{n+1} - v_j^n}{\tau} \\
& + \sum_{k=M}^{2M-1} (E_k)_j^{n+\alpha}(v, \bar{v}) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{v_j^{n+1} - v_j^n}{\tau} \\
& = \sum_{k=0}^{M-1} (G_k)_j^{n+\alpha}(v, \bar{v}) \delta^k w_j^{n+\alpha} + \sum_{k=M}^{2M} (G_k)_j^{n+\alpha}(v, \bar{v}) \delta^k w_j^{n+\alpha} + R, \tag{4.1}
\end{aligned}$$

$$\frac{\Delta_+^k w_0^n}{h^k} = 0, \quad \frac{\Delta_-^k w_j^n}{h^k} = 0, \quad k = 0, 1, \dots, M-1, \tag{4.2}$$

$$w_j^0 = 0. \tag{4.3}$$

Using Lemmas 1-6 and Corollary 1, and repeating the procedure of §3, from (4.1)-(4.3), we have

$$\max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_2 + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \leq K_6 \left(\sum_{k=0}^{2M} \|\delta^k w_h^0\|_2 + Q \right), \tag{4.4}$$

where K_6 is independent of τ and h . From (4.2) and (4.3), we get

$$\bar{v}_j^n \equiv v_j^n, \quad j = 0, 1, \dots, J; n = 0, 1, \dots, N. \tag{4.5}$$

Theorem 2 is proved.

Now we derive the following stability Theorem.

Theorem 3. Under assumptions (1)-(5) and (3.26) and by choosing suitable τ and h , the solution of the finite difference system (1.4), (1.6), (1.7) is stable with respect to the initial boundary value ϕ , ψ_{0k} , ψ_{1k} and nonlinear coefficient A and F .

Proof. Suppose $\{v_j^n\} (j = 0, 1, \dots, J; n = 0, 1, \dots, N)$ satisfies

$$\begin{cases}
(-1)^M \frac{v_j^{n+1} - v_j^n}{\tau} + A_j^{n+\alpha}(v) \frac{\Delta_+^M \Delta_-^M (v_j^{n+1} - v_j^n)}{\tau h^{2M}} = F_j^{n+\alpha}(v), \\
\frac{\Delta_+^k v_0^n}{h^k} = \psi_{0k}^n, \quad \frac{\Delta_-^k v_j^n}{h^k} = \psi_{1k}^n, \quad k = 0, 1, \dots, M-1, \\
v_j^0 = \phi_j,
\end{cases} \tag{4.6}$$

and $\{\bar{v}_j^n\} (j = 0, 1, \dots, J; n = 0, 1, \dots, N)$ satisfies

$$\begin{cases}
(-1)^M \frac{\bar{v}_j^{n+1} - \bar{v}_j^n}{\tau} + \bar{A}_j^{n+\alpha}(\bar{v}) \frac{\Delta_+^M \Delta_-^M (\bar{v}_j^{n+1} - \bar{v}_j^n)}{\tau h^{2M}} = \bar{F}_j^{n+\alpha}(\bar{v}), \\
\frac{\Delta_+^k \bar{v}_0^n}{h^k} = \bar{\psi}_{0k}^n, \quad \frac{\Delta_-^k \bar{v}_j^n}{h^k} = \bar{\psi}_{1k}^n, \quad k = 0, 1, \dots, M-1, \\
\bar{v}_j^0 = \bar{\phi}_j.
\end{cases} \tag{4.7}$$

Let $w_j^n = v_j^n - \tilde{v}_j^n$ ($j = 0, 1, \dots, J; n = 0, 1, \dots, N$). Subtracting (4.7) from (4.6) yields

$$\begin{aligned} & (-1)^M \frac{w_j^{n+1} - w_j^n}{\tau} + A_j^{n+\alpha}(\tilde{v}) \delta^{2M} \frac{w_j^{n+1} - w_j^n}{\tau} \\ & + \sum_{k=0}^{M-1} (E_k)_j^{n+\alpha}(v, \tilde{v}) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{v_j^{n+1} - v_j^n}{\tau} \\ & + \sum_{k=M}^{2M-1} (E_k)_j^{n+\alpha}(v, \tilde{v}) \delta^k w_j^{n+\alpha} \delta^{2M} \frac{v_j^{n+1} - v_j^n}{\tau} \\ & = \sum_{k=0}^{M-1} (G_k)_j^{n+\alpha}(v, \tilde{v}) \delta^k w_j^{n+\alpha} + \sum_{k=M}^{2M} (G_k)_j^{n+\alpha}(v, \tilde{v}) \delta^k w_j^{n+\alpha} + R_1, \end{aligned} \quad (4.8)$$

$$\frac{\Delta_+^k w_0^n}{h^k} = \psi_{0k}^n - \tilde{\psi}_{0k}^n, \quad \frac{\Delta_-^k w_J^n}{h^k} = \psi_{1k}^n - \tilde{\psi}_{1k}^n, \quad k = 0, 1, \dots, M-1, \quad (4.9)$$

$$w_j^0 = \phi_j - \tilde{\phi}_j, \quad (4.10)$$

where

$$R_1 = (A_j^{n+\alpha}(\tilde{v}) - \tilde{A}_j^{n+\alpha}(\tilde{v})) \delta^{2M} \frac{v_j^{n+1} - \tilde{v}_j^n}{\tau} + F_j^{n+\alpha}(\tilde{v}) - \tilde{F}_j^{n+\alpha}(\tilde{v}). \quad (4.11)$$

Using Lemma and Corollary 1, and repeating the procedure of §3, from (4.8)–(4.10), we have

$$\begin{aligned} & \max_{n=0,1,\dots,N} \sum_{k=0}^{2M} \|\delta^k w_h^n\|_2 + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{2M} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \\ & \leq K_7 \left[\sum_{k=0}^{2M} \|\delta^k (\phi_h - \tilde{\phi}_h)\|_2 + \max_{n=0,1,\dots,N} \sum_{k=0}^{M-1} (|\psi_{0k}^n - \tilde{\psi}_{0k}^n| + |\psi_{1k}^n - \tilde{\psi}_{1k}^n|) \right. \\ & + \max_{n=0,1,\dots,N-1} \sum_{k=0}^{M-1} \left(\left| \frac{\psi_{0k}^{n+1} - \psi_{0k}^n}{\tau} - \frac{\tilde{\psi}_{0k}^{n+1} - \tilde{\psi}_{0k}^n}{\tau} \right| + \left| \frac{\psi_{1k}^{n+1} - \psi_{1k}^n}{\tau} - \frac{\tilde{\psi}_{1k}^{n+1} - \tilde{\psi}_{1k}^n}{\tau} \right| \right) \\ & \left. + \max_{n=0,1,\dots,N-1} \|A_h^{n+\alpha} - \tilde{A}_h^{n+\alpha}\|_\infty + \max_{n=0,1,\dots,N-1} \|F_h^{n+\alpha} - \tilde{F}_h^{n+\alpha}\|_\infty \right], \end{aligned} \quad (4.12)$$

where K_7 is independent of τ and h . Thus, the theorem is proved.

Obviously, using the results of §3, we also have the following error estimates and convergence.

Theorem 4. Under the same assumptions as in Theorem 1, we have

$$\max_{n=0,1,\dots,N} \|\delta^k w_h^n\|_2 \leq K_8(\tau + h), \quad k = 0, 1, \dots, 2M, \quad (4.13)$$

$$\max_{n=0,1,\dots,N} \|\delta^k w_h^n\|_\infty \leq K_9(\tau + h), \quad k = 0, 1, \dots, 2M-1, \quad (4.14)$$

$$\max_{n=0,1,\dots,N} \|\delta^{2M} w_h^n\|_\infty \leq K_{10} \left(\frac{\tau}{h^{\frac{1}{2}}} + h^{\frac{1}{2}} \right), \quad (4.15)$$

$$\max_{n=0,1,\dots,N-1} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_2 \leq K_{11}(\tau + h), k = 0, 1, \dots, 2M, \quad (4.16)$$

$$\max_{n=0,1,\dots,N-1} \left\| \delta^k \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_\infty \leq K_{12}(\tau + h), k = 0, 1, \dots, 2M - 1, \quad (4.17)$$

$$\max_{n=0,1,\dots,N-1} \left\| \delta^{2M} \frac{w_h^{n+1} - w_h^n}{\tau} \right\|_\infty \leq K_{13} \left(\frac{\tau}{h^{\frac{1}{2}}} + h^{\frac{1}{2}} \right), \quad (4.18)$$

where $K_i, i = 8, 9, \dots, 13$, are independent of τ and h .

Corollary 2. Under the same assumptions as in Theorem 1, the solution of the finite difference system (1.4), (1.6), (1.7) has the following convergence results: When $\tau \rightarrow 0$ and $h \rightarrow 0$, for all $k = 0, 1, \dots, 2M$ we have

$$\|\delta^k(u_h - v_h)\|_2 \rightarrow 0, n = 0, 1, \dots, N, \quad (4.19)$$

$$\left\| \delta^k \left(\frac{u_h^{n+1} - u_h^n}{\tau} - \frac{v_h^{n+1} - v_h^n}{\tau} \right) \right\|_2 \rightarrow 0, n = 0, 1, \dots, N - 1. \quad (4.20)$$

When $\tau \rightarrow 0$ and $h \rightarrow 0$, for all $j = 0, 1, \dots, J$, and $k = 0, 1, \dots, 2M - 1$ we have

$$|\delta^k(u_j^n - v_j^n)| \rightarrow 0, n = 0, 1, \dots, N, \quad (4.21)$$

$$|\delta^k \left(\frac{u_j^{n+1} - u_j^n}{\tau} - \frac{v_j^{n+1} - v_j^n}{\tau} \right)| \rightarrow 0, n = 0, 1, \dots, N - 1. \quad (4.22)$$

When $\frac{\tau}{h^{\frac{1}{2}}} \rightarrow 0$ and $h \rightarrow 0$, for all $j = 0, 1, \dots, J$, we have

$$|\delta^{2M}(u_j^n - v_j^n)| \rightarrow 0, n = 0, 1, \dots, N, \quad (4.23)$$

$$|\delta^{2M} \left(\frac{u_j^{n+1} - u_j^n}{\tau} - \frac{v_j^{n+1} - v_j^n}{\tau} \right)| \rightarrow 0, n = 0, 1, \dots, N - 1. \quad (4.24)$$

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