

## A FAMILY OF VISCOSITY SPLITTING SCHEME FOR THE NAVIER-STOKES EQUATIONS\*

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### Abstract

In the paper, a family of viscosity splitting method is introduced for solving the initial boundary value problems of Navier-Stokes equation. Some stability and convergence estimates of the method are proved.

### §1. Introduction

Since the publication of Chorin's work in 1973, the convergence problem of viscous splitting for the Navier-Stokes equation has been considered by several authors. Beale and Majda proved a convergence theorem for the Cauchy problems. Chorin, Hughes, McCracken and Marsden suggested a product formula for the initial boundary value problem, without convergence proof, follows:

$$u_n(t) = (H(\frac{t}{n}) \circ \phi \circ E(\frac{t}{n}))^n u_0 \quad (1.1)$$

where  $H(\cdot)$  is the Stokes solver,  $E(\cdot)$  is the Euler solver and  $\phi$  is a so called "vorticity creation operator", the capacity of which is to maintain the no-slip condition at the surface. Ying Long-an considered this scheme and proved that (1.1) does not converge; he also proved that if a nonhomogeneous term is added to the Stokes equation to neutralize the error arising from the operator  $\phi$ , then this scheme converges, the rate of convergence is  $O(k)$  in  $L^\infty(0, T; (H^1(\Omega))^2)$  for the two dimensional case, and  $O(k)$  in  $L^\infty(0, T; (L^2(\Omega))^3)$  for the three dimensional case, where  $k$  is the length of time step. Alessandrini, Douglis and Fabes also considered the initial boundary value problems and proved the convergence of the scheme

$$u_n(t) = (H(\frac{t}{n}) \circ E_M(\frac{t}{n}))^n u_0 \quad (1.2)$$

where  $E_M(\cdot)$  is an approximate Euler solver with the solutions of the Euler equation replaced by polynomials. Zheng and Huang considered a scheme similar to (1.2), where there is also no operator  $\phi$ , but  $E_M(\cdot)$  is replaced by  $E(\cdot)$ ; they proved that the rate

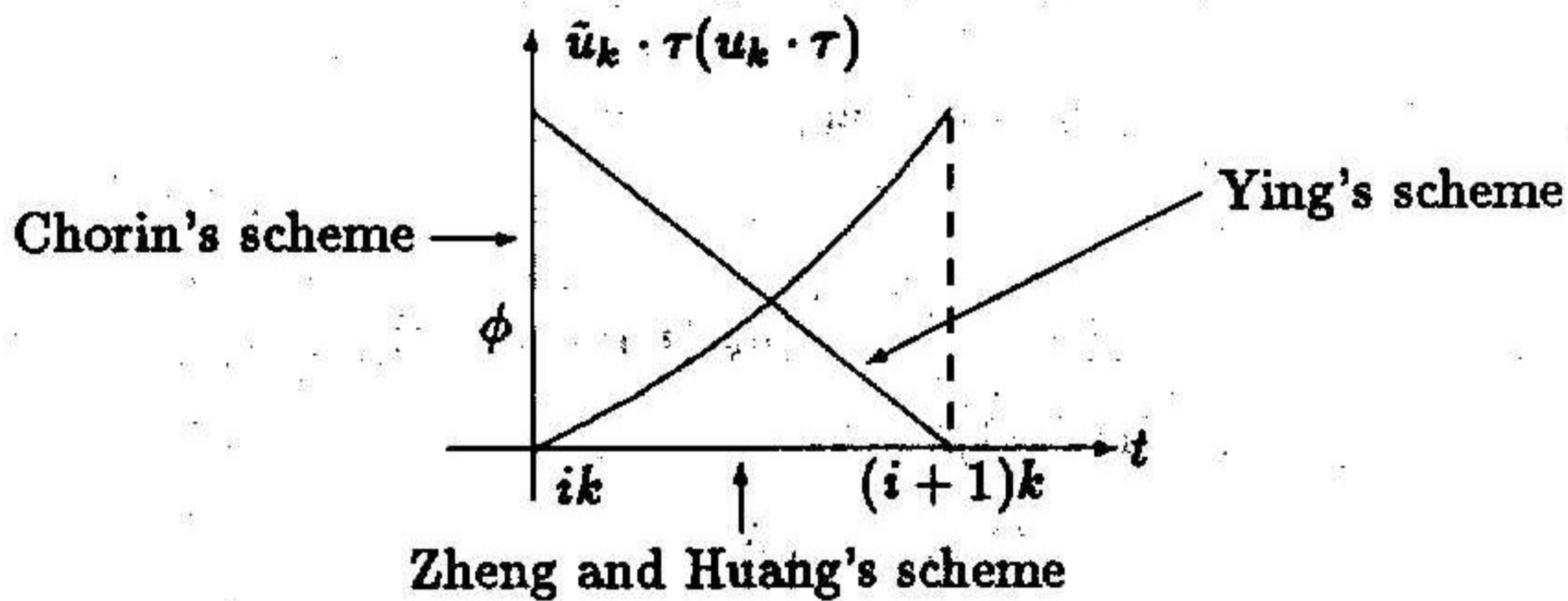
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of convergence for the two dimensional case is  $O(k^{\frac{3}{4}-\epsilon})$  in  $L^\infty(0, T; (L^2(\Omega))^2)$ , where  $0 < \epsilon < 1/4$ . Recently, Ying Long-an considered a scheme

$$u_n(t) = (\hat{H}(\frac{t}{n}) \circ E(\frac{t}{n}))^n u_0 \tag{1.3}$$

where  $\hat{H}(\cdot)$  is the Stokes solver with nonhomogeneous on boundary conditions; he proved that the rate of convergence for the two dimensional case is  $O(k)$  in  $L^\infty(0, T; (H^1(\Omega))^2)$ .

To understand those schemes clearly, let us give a chart.



In the chart,  $\tilde{u}_k$  are the solutions of the Euler equations,  $u_k$  are the solutions of the Stokes equations, and  $\tau$  is the tangent vector.

The purpose of this paper is to study a family of viscosity splitting scheme similar to (1.3). We will prove a convergence theorem where the rate of convergence for the two-dimensional case is  $O(k^{\frac{1}{4}-\epsilon})$  in  $L^\infty(0, T; (H^1(\Omega))^2)$ , where  $0 < \epsilon < 1/4$ . For simplicity, we only consider simply connected bounded domains in  $R^2$ .

### §2. The Scheme and the Main Theorem

Let  $x = (x_1, x_2)$  and  $y = (y_1, y_2)$  be points in  $R^2$  and  $\Omega$  be a simply connected domain in  $R^2$  with sufficiently smooth boundary  $\partial\Omega$ . The initial boundary value problem of the Navier-Stokes equation is given as

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u + \frac{1}{\rho} \nabla P = \nu \Delta u + f, \quad x \in \Omega, t > 0, \tag{2.1}$$

$$\nabla \cdot u = 0, \quad x \in \Omega, t > 0, \tag{2.2}$$

$$u|_{x \in \partial\Omega} = 0, \tag{2.3}$$

$$u|_{t=0} = u_0(x) \tag{2.4}$$

where  $u = (u_1, u_2)$  is the velocity,  $P$  is the pressure, and  $\nu, \rho$  are positive constants. Throughout this paper we assume that the solution  $(u, P)$  of the above problem is sufficiently smooth on  $\bar{\Omega} \times [0, T]$ , and the usual notations  $H^s(\Omega)$  and  $W^{m,p}(\Omega)$  for Sobolev spaces and  $\|\cdot\|_s$  and  $\|\cdot\|_{m,p}$  for norms in Sobolev spaces are applied.

We divide the interval  $[0, T]$  into equal subintervals with length  $k$ . Then we solve  $\tilde{u}_k(t), \tilde{P}_k(t), u_k(t), P_k(t)$  on each interval  $(ik, (i+1)k), i = 0, 1, \dots$ , according to the following procedure:

$$\frac{\partial \tilde{u}_k}{\partial t} + (\tilde{u}_k \cdot \nabla) \tilde{u}_k + \frac{1}{\rho} \nabla \tilde{P}_k = f, \quad (2.5)$$

$$\nabla \cdot \tilde{u}_k = 0, \quad (2.6)$$

$$\tilde{u}_k \cdot n|_{x \in \partial \Omega} = 0, \quad (2.7)$$

$$\tilde{u}_k(ik) = u_k(ik - 0) \quad (2.8)$$

where  $n$  is the unit outward normal vector and  $u_k(-0) = u_0$ ,

$$\frac{\partial u_k}{\partial t} + \frac{1}{\rho} \nabla P_k = \nu \Delta u_k, \quad (2.9)$$

$$\nabla \cdot u_k = 0, \quad (2.10)$$

$$u_k|_{x \in \partial \Omega} = g\left(\frac{(i+1)k - t}{k}\right) \tilde{u}_k((i+1)k - 0)|_{x \in \partial \Omega}, \quad (2.11)$$

$$u_k(ik) = \tilde{u}_k((i+1)k - 0) \quad (2.12)$$

where  $g(t) \in C^2[0, 1], g(0) = 0, g(1) = 1$ , and

$$|g(t)| \leq \alpha_0, |g'(t)| \leq \alpha_1, |g''(t)| \leq \alpha_2 \quad \forall t \in [0, 1];$$

$g(t)$  exists, for example,  $g(t) = t^n$ , where  $\alpha_0 = 1, \alpha_1 = n, \alpha_2 = n(n-1)$ .

Our main result is the following

**Theorem.** If  $u_0 \in (H^4(\Omega))^2 \cap (H_0^1(\Omega))^2, \nabla \cdot u_0 = 0, f \in L^\infty(0, T; (H^4(\Omega))^2) \cap W^{2,\infty}(0, T; (H^{\frac{1}{2}}(\Omega))^2)$ ,  $u$  is the solution of problem (2.1)–(2.4),  $\tilde{u}_k, u_k$  is the solution of problem (2.5)–(2.12),  $0 \leq s < \frac{3}{2}$ , then

$$\sup_{0 \leq t \leq T} (\|u_k(t)\|_{s+1}, \|\tilde{u}_k(t)\|_{s+1}) \leq M, \quad (2.13)$$

$$\sup_{0 \leq t \leq T} (\|u(t) - u_k(t)\|_1, \|u(t) - \tilde{u}_k(t)\|_1) \leq M' k^{\frac{1}{4} - \epsilon} \quad (2.14)$$

for any  $0 < \epsilon < 1/4$ , where the constants  $M, M'$  depend only on the domain  $\Omega$ , constants  $\epsilon, \nu, s, T, \alpha_0, \alpha_1, \alpha_2$ , functions  $f, u_0$  and  $u$ .

### §3. Solution of the Stokes Equation

We consider the linear Stokes equation

$$\frac{\partial u}{\partial t} + \frac{1}{\rho} \nabla P = \nu \Delta u + f \quad (3.1)$$

coupled with equation (2.2), initial condition (2.4) and a boundary condition (2.3) and a nonhomogeneous boundary condition

$$u|_{x \in \partial \Omega} = u_1(x, t) \quad (3.2)$$

where  $u_1$  satisfies

$$\int_{\partial\Omega} u_1 \cdot n ds = 0, \quad u_1(x, 0) = u_0(x)|_{x \in \partial\Omega}.$$

We extend function  $u_1$  continuously to the domain  $\Omega$  at every time  $t$ , such that  $u_1$  is the solution of the stationary Stokes problem

$$\frac{1}{\rho} \nabla P = \nu \Delta u_1, \quad \nabla u_1 = 0. \quad (3.3)$$

Then by the estimate of the Stokes problems,

$$\|u_1\|_{1,\Omega} \leq C \|u_1\|_{\frac{1}{2},\partial\Omega}. \quad (3.4)$$

Here and hereafter we always denote by  $C$  a generic constant which depends only on the domain  $\Omega$  and constants  $\nu, s, T$ ; by  $C_0$  a generic constant which depends only on the domain  $\Omega$ , constants  $\nu, s, T$ , the known function  $f, u_0$  and the solution  $u$  of problem (2.1)–(2.4); by  $C_1, C_2, \dots, M_0, M_1, \dots$  some other constants which are determined according to special requirements.

$\frac{\partial u_1}{\partial t}$  is also a solution of equation (3.3), so we have

$$\left\| \frac{\partial u_1}{\partial t} \right\|_{1,\Omega} \leq C \left\| \frac{\partial u_1}{\partial t} \right\|_{\frac{1}{2},\partial\Omega}. \quad (3.5)$$

Similarly to Lemma 1 of [1], we have

**Lemma 1.** Let  $v = u - u_1$ ; then

$$\frac{d}{dt} \|\nabla \wedge v\|_0^2 \leq C \left( \left\| \frac{\partial u}{\partial t} \right\|_{\frac{1}{2},\partial\Omega}^2 + \|f\|_0^2 \right) \quad (3.6)$$

where  $\nabla \wedge = \left( \frac{\partial}{\partial x_2}, \frac{\partial}{\partial x_1} \right)$ .

We will use the Helmholtz operator  $P$  and the Stokes operator  $A$  frequently. It is known that

$$(L^2(\Omega))^2 = X \oplus G$$

where

$$X = \text{Closure in } (L^2(\Omega))^2 \text{ of } \{u \in (C_0^\infty(\Omega))^2; \nabla \cdot u = 0\},$$

$$G = \{\nabla p; p \in H^1(\Omega)\}.$$

$P$  is the orthogonal projection  $P : (L^2(\Omega))^2 \rightarrow X$ , which is a bounded operator from  $(H^s(\Omega))^2$  to  $(H^s(\Omega))^2$  for any nonnegative  $s$ .  $A$  is defined as  $A = -P\Delta$  with domain  $D(A) = X \cap \{u \in (H^2(\Omega))^2; u|_{\partial\Omega} = 0\}$  which admits the following properties:

$$\|A^\alpha e^{-tA}\| \leq C t^{-\alpha}, \quad \alpha \geq 0, t > 0, \quad (3.7)$$

$$\frac{1}{C} \|u\|_{2\alpha} \leq \|A^\alpha u\|_0 \leq C \|u\|_{2\alpha}, \quad \forall u \in D(A^\alpha), \alpha \geq 0 \quad (3.8)$$

and if  $0 \leq s < 1/2$ ,  $u \in X \cap (H^s(\Omega))^2$ , then  $u \in D(A^{\frac{s}{2}})$ ; if  $1 \leq s < \frac{3}{2}$ ,  $u \in D(A) \cap (H^{s+1}(\Omega))^2$ , then  $u \in D(A^{\frac{s+1}{2}})$ .

Similarly to Lemma 2 of [1], we have

**Lemma 2.** *If  $u_0 \in D(A) \cap (H^{s+1}(\Omega))^2, 0 \leq s < 3/2, f \in L^\infty(0, T; (H^r(\Omega))^2), s - 1 < r < 1/2, u$  is a solution of problem (3.1), (2.2)–(2.4), then*

$$\|u(t)\|_{s+1} \leq C \left( \|u_0\|_{s+1} + \sup_{0 \leq \tau \leq t} \|f(\tau)\|_r \right). \quad (3.9)$$

Now we apply scheme (2.5)–(2.12) to problem (3.1), (2.2)–(2.4). Equation (2.5) is reduced to

$$\frac{\partial \tilde{u}_k}{\partial t} + \frac{1}{\rho} \nabla \cdot \tilde{P}_k = f.$$

We apply the operator  $P$  to it and obtain  $\partial \tilde{u}_k / \partial t = Pf$ . Thus

$$\tilde{u}_k(t) = \tilde{u}_k(ik) + \int_{ik}^t Pf(\tau) d\tau \quad ik \leq t < (i+1)k. \quad (3.10)$$

Let

$$v(t) = u_k(t) - g\left(\frac{(i+1)k - t}{k}\right) (\tilde{u}_k((i+1)k - 0) - \tilde{u}_k(ik)). \quad (3.11)$$

Then by (2.8)–(2.12),  $v$  is the solution of

$$\begin{aligned} \frac{\partial v}{\partial t} + \frac{1}{\rho} \nabla \cdot P_k v &= \nu \Delta v + \nu g\left(\frac{(i+1)k - t}{k}\right) \Delta (\tilde{u}_k((i+1)k - 0) - \tilde{u}_k(ik)) \\ &\quad + \frac{1}{k} g'\left(\frac{(i+1)k - t}{k}\right) (\tilde{u}_k((i+1)k - 0) - \tilde{u}_k(ik)), \end{aligned} \quad (3.12)$$

$$\nabla \cdot v = 0, \quad (3.13)$$

$$v|_{x \in \partial \Omega} = 0, \quad (3.14)$$

$$v(ik) = \tilde{u}_k(ik) = u_k(ik - 0) = v(ik - 0). \quad (3.15)$$

Therefore  $v$  is a continuous function on  $\bar{\Omega} \times [0, T]$ .

By (3.8), (3.10), we have

$$\begin{aligned} u_k(t) &= e^{-\nu t A} u_0 + \sum_{i=0}^{[\frac{t}{k}]-1} \int_{ik}^{(i+1)k} e^{-\nu(t-\tau)A} \left\{ \nu g\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P \Delta P f(\xi) d\xi \right. \\ &\quad \left. + \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P f(\xi) d\xi \right\} d\tau \\ &\quad + \int_{[\frac{t}{k}]k}^t e^{-\nu(t-\tau)A} \left\{ \nu g\left(\frac{([\frac{t}{k}] + 1)k - \tau}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P \Delta P f(\xi) d\xi \right. \\ &\quad \left. + \frac{1}{k} g'\left(\frac{([\frac{t}{k}] + 1)k - \tau}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P f(\xi) d\xi \right\} d\tau \\ &\quad + g\left(\frac{([\frac{t}{k}] + 1)k - \tau}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P f(\tau) d\tau \end{aligned} \quad (3.16)$$

where  $[ \ ]$  denotes the integral part of a number.

**Lemma 3.** *If  $0 \leq s < 3/2, s - 1 < r < 1/2, u_0 \in D(A) \cap (H^{s+1}(\Omega))^2, f \in L^\infty(0, T; (H^{2+r}(\Omega))^2) \cap W^{1,\infty}(0, T; (H^r(\Omega))^2)$ , then*

$$\begin{aligned} \|u_k(t)\|_{s+1} \leq & C(\|u_0\|_{s+1} + k \sup_{0 < \zeta < ([\frac{t}{k}] + 1)k} \|f(\zeta)\|_{2+r} + \sup_{0 < \zeta < ([\frac{t}{k}] + 1)k} \|f(\zeta)\|_r \\ & + C([\frac{t}{k}] + 1)k - t) \sup_{[\frac{t}{k}]k \leq \zeta < ([\frac{t}{k}] + 1)k} \|f(\zeta)\|_{s+1}. \end{aligned} \quad (3.17)$$

*Proof.* The estimate of the first term is obvious. Besides, we have

$$\begin{aligned} & \left\| e^{-\nu(t-\tau)A} \nu g\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P \Delta P f(\xi) d\xi \right\|_{s+1} \\ & \leq C \left\| A^{\frac{s+1-r}{2}} e^{-\nu(t-\tau)A} \int_{ik}^{(i+1)k} A^{\frac{r}{2}} P \Delta P f(\xi) d\xi \right\|_0 \\ & \leq Ck \sup_{ik \leq \zeta < (i+1)k} \|f(\zeta)\|_{2+r} (t - \tau)^{-\frac{s+1-r}{2}} \end{aligned}$$

and

$$\begin{aligned} & \left\| e^{-\nu(t-\tau)A} \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P \Delta P f(\xi) d\xi \right\|_{s+1} \\ & \leq C \left\| A^{\frac{s+1-r}{2}} e^{-\nu(t-\tau)A} \frac{1}{k} \int_{ik}^{(i+1)k} A^{\frac{r}{2}} P \Delta P f(\xi) d\xi \right\|_0 \\ & \leq Ck \sup_{ik \leq \zeta < (i+1)k} \|f(\zeta)\|_r (t - \tau)^{-\frac{s+1-r}{2}}. \end{aligned}$$

By the mean value theorem,

$$g\left(\frac{(i+1)k - \tau}{k}\right) = g'(\zeta) \cdot \left(\frac{(i+1)k - \tau}{k}\right)$$

where  $0 < \zeta < \frac{(i+1)k - \tau}{k}, ik < \tau < (i+1)k,$

$$\left\| g\left(\frac{([\frac{t}{k}] + 1)k - t}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P f(\tau) d\tau \right\|_{s+1} \leq C([\frac{t}{k}] + 1)k - t \|f\|_{s+1}.$$

Then (3.17) follows.

**Lemma 4.** *If  $0 \leq s < 3/2, s - 1 < r < 1/2, u_0 \in D(A) \cap (H^{s+1}(\Omega))^2, f \in L^\infty(0, T; (H^{2+r}(\Omega))^2) \cap W^{1,\infty}(0, T; (H^r(\Omega))^2)$ , and the solution  $u$  of problem (3.1), (2.2)–(2.4) is sufficiently smooth, then for any  $0 < \varepsilon < (3 - 2s)/4,$*

$$\sup_{0 \leq t \leq T} (\|u(t) - u_k(t)\|_{s+1}, \|u(t) - \tilde{u}_k(t)\|_{s+1}) \leq C_0 k^{\frac{3-2s}{4} - \varepsilon} \quad (3.18)$$

*Proof.* By (3.6) and

$$u(t) = e^{-\nu t A} u_0 + \int_0^t e^{-\nu(t-\tau)A} P f(\tau) d\tau \quad (3.19)$$

we have

$$\begin{aligned}
 u(t) - u_k(t) &= \sum_{i=0}^{[\frac{t}{k}] - 1} \int_{ik}^{(i+1)k} e^{-\nu(t-\tau)A} \left\{ -\nu g\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P \Delta P f(\xi) d\xi \right. \\
 &\quad \left. + P f(\tau) - \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P f(\xi) d\xi \right\} d\tau \\
 &\quad + \int_{[\frac{t}{k}]k}^t e^{-\nu(t-\tau)A} \left\{ -\nu g\left(\frac{([\frac{t}{k}] + 1)k - \tau}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P \Delta P f(\xi) d\xi \right. \\
 &\quad \left. + P f(\tau) - \frac{1}{k} g'\left(\frac{([\frac{t}{k}] + 1)k - \tau}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P f(\xi) d\xi \right\} d\tau \\
 &\quad - g\left(\frac{([\frac{t}{k}] + 1)k - t}{k}\right) \int_{[\frac{t}{k}]k}^{([\frac{t}{k}] + 1)k} P f(\tau) d\tau.
 \end{aligned}$$

Some estimates are the same as in the proof of Lemma 3. And we have

$$\begin{aligned}
 &\left\| \int_{ik}^{(i+1)k} e^{-\nu(t-\tau)A} \left( P f(\tau) - \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P f(\xi) d\xi \right) d\tau \right\|_{s+1} \\
 &= \left\| \int_{ik}^{(i+1)k} e^{-\nu(t-\zeta)A} P f(\zeta) d\zeta - \int_{ik}^{(i+1)k} \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} P f(\zeta) d\zeta d\tau \right\|_{s+1} \\
 &= \left\| \int_{ik}^{(i+1)k} -\frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} (e^{-\nu(t-\tau)A} - e^{-\nu(t-\zeta)A}) P f(\zeta) d\zeta d\tau \right\|_{s+1} \\
 &= \left\| \int_{ik}^{(i+1)k} -e^{-\nu(t-\tau)A} \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} (I - e^{-(\tau-\zeta)A}) P f(\zeta) d\zeta d\tau \right\|_{s+1} \\
 &= \left\| \int_{ik}^{(i+1)k} -e^{-\nu(t-\tau)A} \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} A \int_0^{\tau-\zeta} e^{-\nu\xi A} d\xi P f(\zeta) d\zeta d\tau \right\|_{s+1} \\
 &\leq C \left\| \int_{ik}^{(i+1)k} A^{1-\frac{\epsilon}{2}} - e^{-\nu(t-\tau)A} \frac{1}{k} g'\left(\frac{(i+1)k - \tau}{k}\right) \int_{ik}^{(i+1)k} \int_0^{\tau-\zeta} A^{\frac{2s+1}{4} + \epsilon} \right. \\
 &\quad \left. \times e^{-\nu\xi A} d\xi A^{\frac{1}{4} - \frac{\epsilon}{2}} P f(\zeta) d\zeta d\tau \right\|_0 \\
 &\leq C \int_{ik}^{(i+1)k} (t - \tau)^{-1 + \frac{\epsilon}{2}} \frac{1}{k} \int_{ik}^{(i+1)k} (\tau - \zeta)^{\frac{3-2s}{4} - \epsilon} d\zeta \|f\|_{\frac{1}{2} - \epsilon} d\tau \\
 &\leq C \sup_{ik \leq \zeta < (i+1)k} \|f(\zeta)\|_{\frac{1}{2} - \epsilon} k^{\frac{3-2s}{4} - \epsilon} \int_{ik}^{(i+1)k} (t - \tau)^{-1 + \frac{\epsilon}{2}} d\tau.
 \end{aligned}$$

Then the estimate for  $\|u(t) - u_k(t)\|_{s+1}$  is obtained.

Now we estimate  $\|u(t) - \tilde{u}_k(t)\|_{s+1}$ . Since  $u$  is sufficiently smooth, we have

$$\|u(t) - u(ik)\|_{s+1} \leq C_0 k, \quad t \in [ik, (i+1)k].$$

By (3.10) and the initial condition (2.8),

$$\|\tilde{u}_k(t) - u_k(ik - 0)\|_{s+1} \leq Ck \sup_{ik \leq \tau \leq t} \|f(\tau)\|_{s+1}.$$

Therefore

$$\|u(t) - \tilde{u}_k(t)\|_{s+1} \leq C_0 k + \|u(ik) - u_k(ik - 0)\|_{s+1} \leq C_0 k^{\frac{3-2s}{4} - \epsilon}.$$

Now, we state some results about the Euler equation:

$$\frac{\partial u}{\partial t} + (u \cdot \nabla)u + \frac{1}{\rho} \nabla P = f, \quad (3.20)$$

$$\nabla \cdot u = 0, \quad (3.21)$$

$$u \cdot n|_{x \in \partial \Omega} = 0, \quad (3.22)$$

$$u|_{t=0} = u_0(x). \quad (3.23)$$

**Lemma 5.** *If integer  $m \geq 3$ ,  $\|u_0\|_m \leq M_1$ ,  $u_0 \in X$ , then there is a constant  $C > 0$  such that*

$$k_0 = \frac{1}{C(M_1 + \sup_{0 \leq t \leq T} \|f(t)\|_m + 1)} \quad (3.24)$$

where  $0 \leq t \leq k_0$ ; solution  $u$  of (3.20)–(3.23) satisfies

$$\|u\|_\sigma \leq C_1(\|u_0\|_\sigma + 1) \quad (3.25)$$

where  $\sigma \leq m$ , the constant  $C_1$  depends only on the domain  $\Omega$ , constants  $m, \sigma, T$  and  $\sup_{0 \leq t \leq T} \|f(t)\|_m$ .

Now,  $u$  is assumed to be an arbitrary smooth function,  $u(\cdot, t) \in X$ ,  $\xi(y, \tau; t)$  is the characteristic which satisfies

$$\frac{\partial}{\partial t} \xi(y, \tau; t) = u(\xi(y, \tau; t), t), \quad \xi(y, \tau; \tau) = y$$

$u_0 \in H^1(\Omega)$ ,  $\omega$  is the solution of

$$\frac{\partial \omega}{\partial t} + u \cdot \nabla \omega = -\nabla \wedge f = F, \quad \omega|_{t=0} = -\nabla \wedge u_0 = \omega_0$$

and  $\psi$  is the stream function which satisfies

$$-\Delta \psi = \omega, \quad \psi|_{x \in \partial \Omega} = 0.$$

Let

$$\Psi(y) = \psi(\xi(y, t; 0)), \quad \theta = -\Delta \Psi.$$

Then we have

**Lemma 6.** *If  $u_0 \in D(A)$ , then*

$$\|\theta(t) - \omega(t)\|_0 \leq C_2 t \|u_0\|_1 + \int_0^t \|F(\tau)\|_0 d\tau \quad (3.26)$$

where the constant  $C_2$  depends only on the domain  $\Omega$  and function  $u$ .

The above results were proved in [1].

#### §4. Some Estimates for the Viscosity Splitting Scheme

In this section, we give some estimates for the solutions of scheme (2.5)–(2.12). We always denote by  $u$  and  $\omega$  the solution of problem (2.1)–(2.4) and associated vorticity, and by  $\omega_k$  and  $\tilde{\omega}_k$  the associated vorticity of  $u_k$  and  $\tilde{u}_k$ .



**Lemma 7.** If  $0 < r < 1$ , then

$$\|(w \cdot \nabla)w\|_r \leq C\|w\|_1\|w\|_2 \quad (4.1)$$

for  $w \in (H^2(\Omega))^2$  and

$$\|(w \cdot \nabla)w\|_{2+r} \leq C\|w\|_1\|w\|_4 \quad (4.2)$$

for  $w \in (H^4(\Omega))^2$ .

*Proof.* By the imbedding theorem, the interpolation inequality and the Hölder inequality, letting  $p = \frac{2}{2-r}$ , we have

$$\begin{aligned} \|(w \cdot \nabla)w\|_r &\leq C\|(w \cdot \nabla)w\|_{1,p} \leq C(\|w\|_{0, \frac{2}{1-r}}\|w\|_2 + \|w\|_{1,2p}^2) \\ &\leq C(\|w\|_1\|w\|_2 + \|w\|_{1+\frac{r}{2}}^2) \leq C(\|w\|_1\|w\|_2 + \|w\|_1\|w\|_{1+r}) \leq C\|w\|_1\|w\|_2. \end{aligned}$$

The proof of (4.2) is similar.

We have assumed in the main theorem that  $u_0 \in D(A) \cap (H^4(\Omega))^2$ . It was proved in [6] that the solution of the Euler equation belongs to  $L^\infty(0, T; (C^{1,\lambda}(\Omega))^2)$  globally provided  $u_0 \in X \cap (C^{1,\lambda}(\Omega))^2$ . By the equation

$$\frac{\partial}{\partial t} \xi(y, \tau; t) = u(\xi(y, \tau; t), t), \quad \xi(y, \tau; \tau) = y,$$

$$\omega(x, t) = \omega_0(\xi(x, t; 0)) + \int_0^t F(\xi(x, t; \zeta), \zeta) d\zeta,$$

$$u = \nabla \wedge \psi, \quad -\Delta \psi = \omega, \quad \psi|_{x \in \partial\Omega} = 0$$

it is easy to see that  $u \in L^\infty(0, T; (H^4(\Omega))^2)$ . Applying this result to scheme (2.5)–(2.12), we get  $\tilde{u}_k \in L^\infty(0, k; (H^4(\Omega))^2)$ . We will prove in the next lemma that  $u_k(jk - 0) \in (H^4(\Omega))^2$  provided  $\tilde{u}_k(t) \in (H^{s+1}(\Omega))^2$  on  $[0, jk)$  by induction  $\tilde{u}_k(t) \in (H^4(\Omega))^2$  for all  $t \in [0, T]$ .

**Lemma 8.** If  $\sup_{0 \leq t \leq jk} \|\tilde{u}_k(t)\|_1 \leq M_0$ , where  $j$  is a positive integer, then

$$\|u_k(jk - 0)\|_\sigma \leq C_3 k^{-\frac{\sigma-s-1}{2}} \left( \sup_{0 \leq \tau < jk} \|\tilde{u}_k(\tau)\|_{s+1} + 1 \right) \quad (4.3)$$

where  $s+1 \leq \sigma \leq 4$ ,  $1 < s < \frac{3}{2}$ , the constant  $C_3$  depends only on domain  $\Omega$ , constants  $\sigma, s, \nu, T, M_0, \alpha_0, \alpha_1, \alpha_2$  and the function  $f$ .

*Proof.* We denote by  $C_3$  a generic constant which possesses the above property. Let  $w = \frac{\partial v}{\partial t}$ ,  $\pi = \frac{\partial P_k}{\partial t}$ , where  $(v, P_k)$  is the solution of (3.11)–(3.14). Then we differentiate those equations formally with respect to  $t$ , and obtain

$$\begin{aligned} \frac{\partial w}{\partial t} + \frac{1}{\rho} \nabla \pi &= \nu \Delta w - \frac{\nu}{k} g' \left( \frac{jk-t}{k} \right) \Delta (\tilde{u}_k(jk-0) + \tilde{u}_k((j-1)k)) \\ &\quad - \frac{1}{k^2} g'' \left( \frac{jk-t}{k} \right) (\tilde{u}_k(jk-0) + \tilde{u}_k((j-1)k)), \end{aligned}$$

$$\begin{aligned} \nabla \cdot w &= 0, \\ w|_{x \in \partial \Omega} &= 0, \end{aligned}$$

$$w((j-1)k) = \nu P \Delta \tilde{u}_k(jk-0) + \frac{1}{k} g'(1) (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)).$$

$\partial v / \partial t$  is its weak solution, but the above problem possesses a strong solution

$$\begin{aligned} w(t) &= e^{-\nu(t-(j-1)k)A} w((j-1)k) - \nu \int_{(j-1)k}^t e^{-\nu(t-\tau)A} \left( -\frac{\nu}{k} g' \left( \frac{jk-t}{k} \right) \Delta (\tilde{u}_k(jk-0) \right. \\ &\quad \left. - \tilde{u}_k((j-1)k)) - \frac{1}{k^2} g'' \left( \frac{jk-t}{k} \right) (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)) \right) d\tau. \end{aligned} \quad (4.4)$$

Hence (4.4) is the expression of  $\partial v / \partial t$ .

We estimate  $\|w((j-1)k)\|_{s-1}$  by equation (2.5) and Lemma 7. Because

$$\begin{aligned} \left\| \frac{\partial}{\partial t} \tilde{u}_k(jk-0) \right\|_{s-1} &= \|P(f - (\tilde{u}_k \cdot \nabla) \tilde{u}_k)\|_{s-1} \\ &\leq C_3 \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k(\tau)\|_1 \|\tilde{u}_k(\tau)\|_2 + 1 \right) \\ &\leq C_3 \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k(\tau)\|_2 + 1 \right) \end{aligned} \quad (4.5)$$

therefore

$$\|w((j-1)k)\|_{s-1} \leq C_3 \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k(\tau)\|_{s+1} + 1 \right).$$

By (4.4),

$$\begin{aligned} \|w(t)\|_2 &\leq C \left( \|A^{1-\frac{s-1}{2}} e^{-\nu(t-(j-1)k)A} A^{\frac{s-1}{2}} w((j-1)k) \|_0 \right. \\ &\quad + \frac{1}{k} \int_{(j-1)k}^t \|A^{1-\frac{s-1}{2}} e^{-\nu(t-\tau)A} A^{\frac{s-1}{2}} P \Delta (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)) \|_0 d\tau \\ &\quad + \frac{1}{k^2} \int_{(j-1)k}^t \|A^{1-\frac{s-1}{2}} e^{-\nu(t-\tau)A} A^{\frac{s-1}{2}} (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)) \|_0 d\tau \\ &\leq C(t-(j-1)k)^{-1+\frac{s-1}{2}} \|A^{\frac{s-1}{2}} w((j-1)k) \|_0 \\ &\quad + \frac{C}{k} \int_{(j-1)k}^t (t-\tau)^{-1+\frac{s-1}{2}} \|A^{\frac{s-1}{2}} P \Delta (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)) \|_0 d\tau \\ &\quad + \frac{C}{k^2} \int_{(j-1)k}^t (t-\tau)^{-1+\frac{s-1}{2}} \|A^{\frac{s-1}{2}} (\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)) \|_0 d\tau \\ &\leq C_3 \left( (t-(j-1)k)^{-1+\frac{s-1}{2}} + \frac{(t-(j-1)k)^{\frac{s-1}{2}}}{k} \right) \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right). \end{aligned}$$

As  $t = jk - 0$ , we have

$$\|w(jk-0)\|_2 \leq C_3 k^{-1+\frac{s-1}{2}} \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right) \quad (4.6)$$

We apply the operator  $P$  to equation (3.12) for  $t = jk - 0$  and obtain

$$\|Av(jk-0)\|_0 \leq \|w(jk-0)\|_2 + \frac{C}{k} \|\tilde{u}_k(jk-0) - \tilde{u}_k((j-1)k)\|_2. \quad (4.7)$$

By the interpolation inequality and (4.5),

$$\begin{aligned} \frac{1}{k} \|\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)\|_2 &\leq \frac{C}{k} \|\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)\|_{s+1}^{1-\frac{s-1}{2}} \\ &\times \|\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)\|_{s-1}^{\frac{s-1}{2}} \leq C_3 k^{-1+\frac{s-1}{2}} \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right). \end{aligned}$$

By (4.6),

$$\|Av(jk - 0)\|_2 \leq C_3 k^{-1+\frac{s-1}{2}} \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right).$$

By (3.11),

$$\|u_k(jk - 0)\|_4 = \|v(jk - 0)\|_4 \leq C \|Av(jk - 0)\|_2.$$

Therefore

$$\|u_k(jk - 0)\|_4 \leq C k^{-1+\frac{s-1}{2}} \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right). \quad (4.7)$$

Applying (3.19) to problem (3.12)-(3.15), we get

$$\begin{aligned} v(jk - 0) &= e^{-\nu k A} \tilde{u}_k((j-1)k) + \int_{(j-1)k}^{jk} e^{-\nu(jk-\tau)A} \left( \nu g\left(\frac{jk-\tau}{k}\right) \Delta(\tilde{u}_k(jk - 0) \right. \\ &\quad \left. - \tilde{u}_k((j-1)k)) + \frac{1}{k} g'\left(\frac{jk-\tau}{k}\right) (\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)) \right) d\tau. \end{aligned}$$

Therefore

$$\begin{aligned} \|v(jk - 0)\|_{s+1} &\leq C \|e^{-\nu k A} A^{s+1} \tilde{u}_k((j-1)k)\|_0 \\ &+ C \int_{(j-1)k}^{jk} (\|Ae^{-\nu(jk-\tau)A} g'(\zeta) \frac{jk-\tau}{k} A^{\frac{s-1}{2}} P \Delta(\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k))\| \\ &+ \|A^{\frac{s+1-r}{2}} e^{-\nu(jk-\tau)A} \frac{1}{k} g'\left(\frac{jk-\tau}{k}\right) A^{\frac{r}{2}} (\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k))\|_0) d\tau \\ &\leq C \|\tilde{u}_k((j-1)k)\|_{s+1} + C \int_{(j-1)k}^{jk} \frac{1}{k} \|\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)\|_{s+1} d\tau \\ &+ C \int_{(j-1)k}^{jk} (jk - \tau)^{-\frac{s+1-r}{2}} \frac{1}{k} \|\tilde{u}_k(jk - 0) - \tilde{u}_k((j-1)k)\|_r d\tau \end{aligned}$$

where  $s - 1 < r < 1/2$ . Then by (4.5) we get

$$\|v(jk - 0)\|_{s+1} \leq C_3 \left( \sup_{(j-1)k \leq \tau < jk} \|\tilde{u}_k\|_{s+1} + 1 \right) \quad (4.8)$$

by (3.15) and  $v(jk - 0) = u_k(jk - 0)$ . Applying the interpolation inequality to (4.7) and (4.8), we obtain (4.3).

Similarly to Lemma 9 of [1], we have

**Lemma 9.** If  $\sup_{0 \leq \tau < jk} \|\tilde{u}_k(\tau)\|_1 \leq M_0$ , where  $j$  is a positive integer, and there are constants  $C_1, k_0$ , such that

$$\|\tilde{u}_k(t)\|_\sigma \leq C_1 (\|\tilde{u}_k(ik)\|_\sigma + 1), \quad \sigma = s+1 \text{ or } 4 \quad (4.9)$$

for  $ik < t < (i+1)k$ , where  $i$  is any integer satisfying  $0 \leq i \leq j$ , and  $1 < s < 3/2$ ,  $0 < k \leq k_0$ , then

$$\sup_{0 \leq t < (j+1)k} \|\tilde{u}_k(t)\|_{s+1} \leq M_2 \quad (4.10)$$

for  $0 < k \leq k_1 \leq k_0$ , where the constants  $M_2, k_1$  depend only on the domain  $\Omega$ , constants  $C_1, \nu, s, T, M_0, \alpha_0, \alpha_1, \alpha_2$  and functions  $f, u_0$ .

If we replace  $(\tilde{u}_k \cdot \nabla)\tilde{u}_k$  in equation (2.5) by  $(u \cdot \nabla)u$ , then (2.5) becomes a linear equation

$$\frac{\partial \tilde{u}_k}{\partial t} + \frac{1}{\nu} \nabla \tilde{P}_k = f - (u \cdot \nabla)u. \quad (4.11)$$

The solution of problem (4.15), (2.6)–(2.12) is denoted  $\tilde{u}^*, \tilde{P}^*, u^*, P^*$ . Let  $\tilde{\omega}^*, \omega^*$  be the associated vorticities. By Lemma 4,

$$\sup_{0 \leq t \leq T} (\|u(t) - u^*(t)\|_{s'+1}, \|u(t) - \tilde{u}^*(t)\|_{s'+1}) \leq C_0 k^{\frac{3-2s'}{4}-\epsilon} \quad (4.12)$$

for any  $s', 0 \leq s' < 3/2, 0 < \epsilon < (3 - 2s')/4$ .

**Lemma 10.** If  $1 < s < 3/2, \|\tilde{u}_k(t)\|_{s+1} \leq M_2$ , for  $ik \leq t < (i+1)k$ , then

$$\|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{\frac{1}{2}, \partial\Omega} \leq C_5 k \left( \sup_{ik \leq \tau < (i+1)k} \|\tilde{u}^* - \tilde{u}_k\|_{1, \Omega} + k^{\frac{1}{4}-\epsilon} \right) \quad (4.13)$$

for any  $\epsilon, 0 < \epsilon < \frac{1}{4}$ , where the constant  $C_5$  depends only on the domain  $\Omega$ , the constants  $\epsilon, s, \nu, M_2$ , the functions  $f, u_0$ , and the solution  $u$  of (2.1)–(2.4).

*Proof.* We denote by  $C_5$  a generic constant with the above property. By (4.11) and (2.5)

$$\frac{\partial \tilde{\omega}^*}{\partial t} + u \cdot \nabla \omega = -\nabla \wedge f, \quad \frac{\partial \tilde{\omega}_k}{\partial t} + \tilde{u}_k \cdot \nabla \tilde{\omega}_k = -\nabla \wedge f.$$

Subtracting one equation from the other we obtain

$$\frac{\partial \tilde{\omega}^* - \tilde{\omega}_k}{\partial t} + u \cdot \nabla (\tilde{\omega}^* - \tilde{\omega}_k) = u \cdot \nabla (\tilde{\omega}^* - \omega) - (u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k. \quad (4.14)$$

By Lemma 6,

$$\begin{aligned} \|\theta - (\tilde{\omega}^* - \tilde{\omega}_k)((i+1)k - 0)\|_0 &\leq C_5 k \|(\tilde{u}^* - \tilde{u}_k)(ik)\|_1 \\ &+ \int_{ik}^{(i+1)k} \|u \cdot \nabla (\tilde{\omega}^* - \omega) - (u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k\|_0 d\tau \end{aligned} \quad (4.15)$$

where  $\theta = -\Delta \Psi, \Psi(y) = \psi(\xi(y, (i+1)k; ik))$ ,  $\psi$  is the stream function corresponding to  $(\tilde{u}^* - \tilde{u}_k)(ik)$ .

We estimate the integrand by (4.12),

$$\|u \cdot \nabla (\tilde{\omega}^* - \omega)\|_0 \leq C_5 \|\tilde{u}^* - u\|_2 \leq C_5 k^{\frac{1}{4}-\epsilon},$$

for any  $0 < \epsilon < 1/4$ . Let  $p = 2/(2-s), q = 2/(s-1)$ . Then

$$\begin{aligned} \|(u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k\|_0 &= \left( \int_{\Omega} |(u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k|^2 dx \right)^{\frac{1}{2}} \\ &\leq \left( \int_{\Omega} |\nabla \tilde{\omega}_k|^p dx \right)^{\frac{1}{p}} \left( \int_{\Omega} |u - \tilde{u}_k|^q dx \right)^{\frac{1}{q}} \leq \|\tilde{\omega}_k\|_{1, \Omega} \|u - \tilde{u}_k\|_{0, q}. \end{aligned}$$

By the imbedding theorem and (4.12),

$$\begin{aligned} \|\tilde{\omega}_k\|_{1,p} &\leq \|\tilde{\omega}_k\|_s \leq C\|\tilde{u}_k\|_{s+1}, \\ \|u - \tilde{u}_k\|_{0,q} &\leq C\|u - \tilde{u}_k\|_1 \leq C_0(\|\tilde{u}^* - \tilde{u}_k\|_1 + k^{\frac{3}{4}-\epsilon}). \end{aligned}$$

Therefore

$$\|u \cdot \nabla(\tilde{\omega}^* - \omega) - (u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k\|_0 \leq C_5(\|\tilde{u}^* - \tilde{u}_k\|_1 + k^{\frac{1}{4}-\epsilon}). \quad (4.16)$$

Substituting (4.16) into (4.15), we obtain

$$\|\theta - (\tilde{\omega}^* - \tilde{\omega}_k)((i+1)k - 0)\|_0 \leq C_5 k \left( \sup_{ik \leq \tau < (i+1)k} \|\tilde{u}^* - \tilde{u}_k\|_1 + k^{\frac{1}{4}-\epsilon} \right). \quad (4.17)$$

Since  $\psi|_{x \in \partial\Omega}$  and  $\frac{\partial\psi}{\partial n}|_{x \in \partial\Omega}$  are zero, we have

$$\begin{aligned} \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{\frac{1}{2},\partial\Omega} &= \|\nabla \wedge \psi - (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{\frac{1}{2},\partial\Omega} \\ &\leq C\|\nabla \wedge \psi - (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{1,\Omega}. \end{aligned} \quad (4.18)$$

Let  $\phi$  be the stream function corresponding to the velocity  $\nabla \wedge \phi - (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)$ . Then it is the solution of

$$-\Delta \phi = \theta - (\tilde{\omega}^* - \tilde{\omega}_k)((i+1)k - 0), \quad \phi|_{\partial\Omega} = 0.$$

By the estimate for the elliptic problems,

$$\|\phi\|_2 \leq C\|\theta - (\tilde{\omega}^* - \tilde{\omega}_k)((i+1)k - 0)\|_0.$$

By definition,

$$\nabla \wedge \phi = \nabla \wedge \psi - (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0).$$

Thus (4.17) and (4.18) yield (4.13).

**Lemma 11.** If  $1 < s < 3/2$ ,  $\|\tilde{u}_k(t)\|_{s+1} \leq M_2$ , then

$$\sup_{0 \leq t \leq T} (\|u(t) - u_k(t)\|_1, \|u(t) - \tilde{u}_k(t)\|_1) \leq C_6 k^{\frac{1}{4}-\epsilon} \quad (4.19)$$

for any  $0 < \epsilon < \frac{1}{4}$ , where the constant  $C_6$  depends only on the domain  $\Omega$ , constants  $\epsilon, \nu, s, T, M_2, \alpha_0, \alpha_1, \alpha_2$ , function  $f, u_0$  and the solution  $u$  of (2.1)-(2.4).

*Proof.* We denote by  $C_6$  a generic constant which possesses the above property. Taking inner product (4.14) with  $(\tilde{\omega}^* - \tilde{\omega}_k)$  and noting that

$$((\tilde{u}_k \cdot \nabla)(\tilde{\omega}^* - \tilde{\omega}_k), \tilde{\omega}^* - \tilde{\omega}_k) = 0$$

we obtain

$$\frac{1}{2} \frac{\partial}{\partial t} \|\tilde{\omega}^* - \tilde{\omega}_k\|_0^2 \leq \|u \cdot \nabla(\tilde{\omega}^* - \omega) - (u - \tilde{u}_k) \cdot \nabla \tilde{\omega}_k\|_0 \|\tilde{\omega}^* - \tilde{\omega}_k\|_0.$$

By (4.16), the right hand side is bounded by

$$\frac{C_6}{2} (\|\tilde{u}^* - \tilde{u}_k\|_1^2 + k^{2(\frac{1}{4}-\epsilon)}) + \frac{1}{2} \|\tilde{\omega}^* - \tilde{\omega}_k\|_0^2.$$

Since  $\tilde{\omega}^* - \tilde{\omega}_k$  is the vorticity corresponding to velocity  $\tilde{u}^* - \tilde{u}_k$ , as in the proof of the last lemma, we get

$$\|\tilde{u}^* - \tilde{u}_k\|_1 \leq C \|\tilde{\omega}^* - \tilde{\omega}_k\|_0. \quad (4.20)$$

Hence

$$\frac{d}{dt} \|\tilde{\omega}^* - \tilde{\omega}_k\|_0^2 \leq C_6 (\|\tilde{\omega}^* - \tilde{\omega}_k\|_0^2 + k^{2(\frac{1}{4}-\epsilon)}).$$

By the Gronwall inequality,

$$\|(\tilde{\omega}^* - \tilde{\omega}_k)(t)\|_0^2 \leq e^{C_6 t} (\|(\tilde{\omega}^* - \tilde{\omega}_k)(ik)\|_0^2 + k^{1+2(\frac{1}{4}-\epsilon)}). \quad (4.21)$$

Let  $t = (i+1)k - 0$ . Then

$$\|(\tilde{\omega}^* - \tilde{\omega}_k)((i+1)k - 0)\|_0^2 \leq e^{C_6 k} (\|(\tilde{\omega}^* - \tilde{\omega}_k)(ik)\|_0^2 + k^{1+2(\frac{1}{4}-\epsilon)}). \quad (4.22)$$

Applying Lemma 1 to problem (2.9)-(2.12), we have

$$\frac{d}{dt} \|\nabla \wedge (u^* - u_k - \nabla \wedge u_1)\|_0^2 \leq C \left\| \frac{\partial u_1}{\partial t} \right\|_{\frac{1}{2}, \partial \Omega}^2 \quad (4.23)$$

where  $u_1$  is the solution of stationary Stokes equation (3.3) with boundary condition

$$u_1(t)|_{x \in \partial \Omega} = g\left(\frac{(i+1)k - t}{k}\right) (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)|_{x \in \partial \Omega}. \quad (4.24)$$

Then we have

$$\begin{aligned} & \|(\omega^* - \omega_k)((i+1)k - 0) - \nabla \wedge u_1((i+1)k - 0)\|_0^2 \\ & \leq \|(\omega^* - \omega_k)(ik) - \nabla \wedge u_1(ik)\|_0^2 + C \int_{ik}^{(i+1)k} \left\| \frac{\partial u_1(\tau)}{\partial \tau} \right\|_{\frac{1}{2}, \partial \Omega}^2 d\tau. \end{aligned} \quad (4.25)$$

By uniqueness,  $u_1((i+1)k - 0) = 0$ . Then by the estimate for the solution of the stationary Stokes problem with boundary value (4.24) and by Lemma 10,

$$\begin{aligned} \|u_1(ik)\|_{1, \Omega} & \leq C \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{x \in \partial \Omega} \\ & \leq C_6 k \left( \sup_{ik \leq \tau < (i+1)k} \|(\tilde{u}^* - \tilde{u}_k)(\tau)\|_{1, \Omega} + k^{\frac{1}{4}-\epsilon} \right). \end{aligned}$$

Besides, we have

$$\left. \frac{\partial u_1}{\partial t} \right|_{x \in \partial \Omega} = \frac{1}{k} g' \left( \frac{(i+1)k - t}{k} \right) (\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)|_{x \in \partial \Omega}.$$

Hence

$$\begin{aligned} \left\| \frac{\partial u_1}{\partial t} \right\|_{\frac{1}{2}, \partial \Omega} & \leq \frac{C}{k} \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{x \in \partial \Omega} \\ & \leq C_6 \left( \sup_{ik \leq \tau < (i+1)k} \|(\tilde{u}^* - \tilde{u}_k)(\tau)\|_{1, \Omega} + k^{\frac{1}{4}-\epsilon} \right). \end{aligned} \quad (4.26)$$

Substituting the above inequalities into (4.25), we obtain

$$\begin{aligned} \|(\omega^* - \omega_k)((i+1)k - 0)\|_0^2 & \leq \|(\omega^* - \omega_k)(ik)\|_0^2 + 2\|(\omega^* - \omega_k)(ik)\|_0 \\ & \times C_6 k \left( \sup_{ik \leq \tau < (i+1)k} \|(\tilde{u}^* - \tilde{u}_k)(\tau)\|_{1, \Omega} + k^{\frac{1}{4}-\epsilon} \right) \end{aligned}$$

$$+ C_6 k \left( \sup_{ik \leq \tau < (i+1)k} \|(\tilde{u}^* - \tilde{u}_k)(\tau)\|_1^2 + k^{2(\frac{1}{4}-\epsilon)} \right).$$

By (4.20),

$$\begin{aligned} \|(\omega^* - \omega_k)((i+1)k - 0)\|_0^2 &\leq (1 + C_6 k) \|(\omega^* - \omega_k)(ik)\|_0^2 \\ &\quad + C_6 k \left( \sup_{ik \leq \tau < (i+1)k} \|(\tilde{u}^* - \tilde{u}_k)(\tau)\|_1^2 + k^{2(\frac{1}{4}-\epsilon)} \right). \end{aligned}$$

Substituting (4.22) in it and noting the initial condition (2.12), we get

$$\begin{aligned} \|(\omega^* - \omega_k)((i+1)k - 0)\|_0^2 &\leq e^{C_6 k} (1 + C_6 k) \|(\omega^* - \omega_k)(ik)\|_0^2 \\ &\quad + C_6 k (\|(\tilde{\omega}^* - \tilde{\omega}_k)(ik)\|_0^2 + k^{1+2(\frac{1}{4}-\epsilon)}). \end{aligned}$$

By the initial condition (2.8),

$$\|(\omega^* - \omega_k)((i+1)k - 0)\|_0^2 \leq (1 + C_6 k) \|(\omega^* - \omega_k)(ik)\|_0^2 + C_6 k^{1+2(\frac{1}{4}-\epsilon)}.$$

We get by induction that

$$\begin{aligned} \|(\omega^* - \omega_k)(ik)\|_0^2 &\leq C_6 e^{C_6 T} k^{2(\frac{1}{4}-\epsilon)} \quad (\text{by (4.21)}), \\ \|(\tilde{\omega}^* - \tilde{\omega}_k)(t)\|_0^2 &\leq C_6 k^{2(\frac{1}{4}-\epsilon)} \quad 0 \leq t \leq T \quad (\text{by (4.20)}), \\ \|(\tilde{u}^* - \tilde{u}_k)(t)\|_1^2 &\leq C_6 k^{2(\frac{1}{4}-\epsilon)} \quad 0 \leq t \leq T \quad (\text{by (4.23)}), \\ \|(\omega^* - \omega_k)(t)\|_1^2 &\leq C_6 k^{2(\frac{1}{4}-\epsilon)}, \quad 0 \leq t \leq T. \end{aligned} \tag{4.27}$$

By (4.12) and the triangle inequality we obtain (4.19).

**Lemma 12.** *If  $i > 0$ ,  $0 \leq s < 3/2$ , and  $\|\tilde{u}_k(t)\|_{s+1} \leq M_2$ , for  $ik \leq t < (i+1)k$ , then  $\|u_k(t)\|_{s+1} \leq M_3$  on the same interval, where the constant  $M_3$  depends only on the domain  $\Omega$ , the constants  $\epsilon, \nu, s, T, M_2$ , the function  $f, u_0$ , and the solution  $u$  of problem (2.1)–(2.4).*

*Proof.* Let  $v = u^* - u_k - u_1$ , where  $u_1$  is the solution of the stationary Stokes equation (3.3) with boundary condition (4.24). Then  $v$  is the solution of

$$\frac{\partial v}{\partial t} + \frac{1}{\rho} \nabla (P^* - P_k - P_1) = \nu \Delta v - \frac{\partial u_1}{\partial t}, \quad \nabla \cdot v = 0, \quad v|_{x \in \partial \Omega} = 0,$$

$$v(ik) = u^*(ik) - u_k(ik) - u_1(ik).$$

By (3.5), (4.26), (4.27),

$$\left\| \frac{\partial u_1}{\partial t} \right\|_{1, \Omega} \leq C_7 k^{\frac{1}{4}-\epsilon}$$

where the constant  $C_7$  has the same property as  $M_3$ . By (4.24) and the estimate for the Stokes problem, we get

$$\begin{aligned} \|u_1\|_{s+1, \Omega} &\leq C \|u_1\|_{s+\frac{1}{2}, \partial \Omega} \leq C \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{s+\frac{1}{2}, \partial \Omega} \\ &\leq C \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{s+1, \Omega}. \end{aligned} \tag{4.28}$$

By Lemma 2,

$$\begin{aligned} \|v(t)\|_{s+1} &\leq C \left( \|u^*(ik) - u_k(ik)\|_{s+1} + \|u_1(ik)\|_{s+1} + \sup_{ik \leq \tau < (i+1)k} \left\| \frac{\partial u_1}{\partial t} \right\|_{\tau} \right) \\ &\leq C \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{s+1} + \|u_1(ik)\|_1 + \sup_{ik \leq \tau < (i+1)k} \left\| \frac{\partial u_1}{\partial t} \right\|_1 \\ &\leq C \|(\tilde{u}^* - \tilde{u}_k)((i+1)k - 0)\|_{s+1} + C_7 k^{\frac{1}{4}-\epsilon}. \end{aligned} \quad (4.29)$$

By the triangle inequality,

$$\|u_k\|_{s+1} \leq \|v\|_{s+1} + \|u^*\|_{s+1} + \|u_1\|_{s+1}.$$

We apply (4.12) to get the estimate of  $\|u^*\|_{s+1}$  and  $\|\tilde{u}^*\|_{s+1}$ . Then the estimate for  $\|u_k\|_{s+1}$  follows from (4.28) and (4.29).

### §5. Proof of the Theorem

We may assume that  $1 < s < 3/2$ . Let  $M_0 = 2 \max_{0 \leq t \leq T} \|u(t)\|_1$ . We set  $m = 4$  and  $\sigma = 4$  or  $\sigma = s + 1$  in Lemma 5. Then, take the large  $C_1$ . Taking  $\sigma = 4$ , we determine constant  $C_3$  in Lemma 8, and constant  $M_2$  in Lemma 9. Raise  $M_2$  if necessary, such that

$$M_2 \geq C_1 (\|u_0\|_{s+1} + 1). \quad (5.1)$$

Then we determine constants  $C_5, C_6, M_3$  in Lemmas 10, 11 and 12 respectively.

Let  $m = 4$ . From (3.24) and Lemma 8, we solve  $k_0$  by

$$k_0 = \frac{1}{C[C_3 k_0^{\frac{s-3}{2}} (M_2 + 1) + \sup \|f\|_4 + 1]}, \quad (5.2)$$

that is

$$C[C_3 k_0^{\frac{s-3}{2}} (M_2 + 1) + k_0 \sup_{0 \leq t \leq T} \|f(t)\|_4 + k_0] = 1.$$

Since the left-hand side is monotone from zero to infinity on the interval  $k_0 \in [0, \infty)$ , (5.2) admits a unique solution  $k_0 > 0$ . Then we take constant  $k_1$  in Lemma 8, and reduce  $k_1$ , if necessary, such that

$$\|u_0\|_4 \leq C_3 k_1^{\frac{s-3}{2}} (M_2 + 1), \quad (5.3)$$

$$C_6 k_1^{\frac{1}{4}-\epsilon} \leq \frac{M_0}{2}. \quad (5.4)$$

With these determined constants, we prove by induction that if  $0 < k < k_1$ , then

$$\begin{aligned} \|\tilde{u}_k(t)\|_1 &\leq M_0, \quad \|u_k(t)\|_1 \leq M_0, \quad \|\tilde{u}_k^c(t)\|_{s+1} \leq M_2, \\ \|u(t) - u_k(t)\|_0 &\leq C_6 k^{\frac{1}{4}-\epsilon}, \quad \|u(t) - \tilde{u}_k(t)\|_0 \leq C_6 k^{\frac{1}{4}-\epsilon}. \end{aligned} \quad (5.5)$$



Two cases are considered simultaneously: (a)  $j = 0$ , (b)  $j > 0$ , and the above assertion is valid for  $0 \leq t < jk$ . By Lemma 8 and (5.3),

$$\|u_k(ik - 0)\|_4 \leq C_3 k^{\frac{s-3}{2}} (M_2 + 1)$$

for  $0 \leq i \leq j, j > 0$ , or  $j = 0$ . Then we set  $m = 4$  in Lemma 5. Because  $k_0$  satisfies (5.2) and  $k_1 \leq k_0$ , the conditions of Lemma 5 are fulfilled provided we take the initial value to be  $u_k(ik - 0)$ ,  $0 \leq i \leq j$ . If  $j > 0$ , from (3.25) we know the conditions of Lemma 9 are fulfilled, we get (4.10). If  $j = 0$ , by (5.1) and Lemma 5, (4.10) is also true, by Lemma 11, (5.5) holds for  $0 \leq t < (j + 1)k$ . By (5.4),  $\|\tilde{u}_k\|_1 \leq M_0$ ,  $\|u_k(t)\|_1 \leq M_0$  on the same interval. Thus the induction is complete.

Applying Lemma 12 we obtain the upper bound of  $\|u_k(t)\|_{s+1}$ . Thus (2.13) and (2.14) are verified for  $k \leq k_1$ . If  $k > k_1$ , there are at most  $1 + \lceil \frac{T}{k_1} \rceil$  steps, and the upper bounds of (2.13) and (2.14) are easily obtained.

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