

## ON THE RESTRICTED PARAMETER IDENTIFICATION PROBLEMS FOR GENERAL VARIATIONAL INEQUALITIES \*

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### Abstract

A restricted parameter identification problem for general variational inequalities is studied using the so-called asymptotic regularization method. Some applications, including the evolution dam problem, are also briefly discussed.

### 1. Introduction

In [4], Hoffmann and Sprekels discussed an identification problem of general variational inequalities under a functional analytic framework. The problem they treated is the following:

Let  $H, X$  be two Hilbert spaces,  $V$  be a separable and reflexive Banach space with dual  $V^*$  and  $X_0$  be another Banach space, such that the embeddings  $V \subset H \subset V^*$  are dense and continuous and  $X_0$  is a dense subspace of  $X$ . The dual pairing between elements of  $V^*$  and  $V$  is denoted by  $\langle \cdot, \cdot \rangle$ . The inner product in  $X$  is denoted by  $[\cdot, \cdot]$ . Let  $C \subset V$  be nonempty, closed and convex. Then, the identification problem is as follows:

Problem ( $\hat{P}$ ). Given  $u^* \in D(S) \cap C$  and  $f^* \in V^*$ , find  $a^* \in X$ , with  $(a^*, u^*) \in D(A_2)$ , such that there exists a  $w^* \in S(u^*)$  which satisfies the variational inequality

$$\langle w^* + A_1(a^*) + A_2(a^*, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \geq 0, \quad \forall v \in C \quad (1.1)$$

where,  $S, A_1, A_2, \Psi$  are some given operators which will be defined in the next section (or see [4]).

The main purpose of this paper is to discuss a similar problem with the restriction  $a^* \in X$  replaced by  $a^* \in K$  for some nonempty, closed and convex subset  $K$  of  $X_0$ . In many physical problems, the parameters we want to find should belong to some specific convex and closed set. The method we use is a combination of those used in [1], [4] and [6].

### 2. Solution to Finite Dimensional Problems

Let  $H, X, V, V^*, X_0$  be the same as in section 1. The norms of these spaces are denoted by  $\|\cdot\|_H, \|\cdot\|_X, \|\cdot\|_V, \|\cdot\|_{V^*}$  and  $\|\cdot\|_{X_0}$ , respectively. Let  $C \subset V$  be nonempty, convex and closed. Let  $K \subset X_0$  be nonempty, convex and closed in  $X$ . we consider the following restricted parameter identification problem:

Problem ( $P$ ). Given  $u^* \in D(S) \cap C, f^* \in V^*$  find  $a^* \in K$ , such that there

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$$\langle T_n(a, u), (\hat{a}, \hat{u}) \rangle = \langle \frac{\varepsilon}{h}u + A_1(a) + A_2(a, u), \hat{u} \rangle + \left[ \frac{a}{h}, \hat{a} \right] - \langle A_1(\hat{a}), u \rangle - \langle A_2(\hat{a}, u), u - u^* \rangle \quad (2 \cdot 10)$$

$$g_n(a, u) = - \langle \frac{\varepsilon}{h}u_n + f^*, u \rangle + \Psi(u) - \left[ \frac{a_n}{h}, a \right] + \langle A_1(a), u^* \rangle \quad (2 \cdot 11)$$

For  $w \in V^* \subset V_N^*$  we set

$$\langle (0, w), (a, u) \rangle = \langle w, u \rangle, \forall (a, u) \in B \quad (2 \cdot 12)$$

Thus, the  $(n+1)$ -th step of Problem  $(P_n)$  is equivalent to solve the following problem:

**Problem  $(T_n)$ .** Find  $(a, u) \in G$ , with  $u \in D(S)$ , such that there exists  $w \in S(u)$ , satisfying

$$\langle (0, w) + T_n(a, u), (\hat{a}, \hat{u}) - (a, u) \rangle + g_n(\hat{a}, \hat{u}) - g_n(a, u) \geq 0, \quad \forall (\hat{a}, \hat{u}) \in G \quad (2 \cdot 13)$$

**Theorem 2.1.** Suppose that  $(A1) - (A7)$  hold and  $\varepsilon > 0$  is given. Then, there exists  $h_0 > 0$ , such that for any  $h \in (0, h_0]$ , Problem  $(P_n)$  has a solution  $\{(a_n, u_n)\}_{n=0}^\infty$ .

**Proof.** It suffices to prove that for any  $n \geq 1$ , Problem  $(T_n)$  has a solution. To this end, like the proof of Theorem 2.1 of [4], we need to check several things.

First of all, since  $g_n$  is convex and continuous on  $B$ , we have

$$D(\partial g_n) = B \quad (2 \cdot 14)$$

Let us define  $Q: B \rightarrow 2^{B^*}$  by  $Q(a, u) = \{0\} \times S(u)$ . Then,  $Q$  is maximal monotone. By  $(A1)$  and  $(A6)$  and the definition of  $G$ , we have

$$(P_{W_M}(a^*), u^*) \in \text{int}(D(Q)) \cap G \quad (2 \cdot 15)$$

By (2.14), we have

$$\text{int}(D(Q)) \cap D(\partial g_n) \neq \emptyset \quad (2 \cdot 16)$$

and

$$G \cap \text{int}D(Q + \partial g_n) = G \cap \text{int}D(Q) \neq \emptyset \quad (2 \cdot 17)$$

Also, the same argument as in [4], we have

$$\partial(g_n + X_G) = \partial g_n + \partial X_G \quad (2 \cdot 18)$$

where

$$X_G(x) = \begin{cases} 0 & x \in G \\ +\infty & x \in G^c \end{cases} \quad (2 \cdot 19)$$

Now, it remains to check  $T_n$  is continuous, bounded, coercive and pseudomonotone. Since  $\dim W_M, \dim V_N < \infty$ , we can assume that there exist  $\alpha, \beta > 0$ , such that

$$\|a\|_{X_0} \leq \alpha \|a\|_X, \quad \forall a \in W_M \quad (2 \cdot 20)$$

$$\|u\|_V \leq \beta \|u\|_H, \quad \forall u \in V_N \quad (2 \cdot 21)$$

It is easy to show that for any  $(a, u), (\hat{a}, \hat{u}) \in B$

$$\begin{aligned} \|T_n(a, u) - T_n(\hat{a}, \hat{u})\|_{B^*}^2 &\leq \left\{ \left( \frac{\varepsilon}{h} + \alpha\beta^2 \|A_2\| \| \hat{a} \|_X \right) \|u - \hat{u}\|_H \right. \\ &\quad + (\beta \|A_1\| + \alpha\beta^2 \|A_2\| \|u\|_H) \|a - \hat{a}\|_X \left. \right\}^2 \\ &\quad + \left\{ [\beta \|A_1\| + \alpha\beta^2 \|A_2\| (\|u - u^*\|_H + \|u\|_H)] \right. \\ &\quad \left. \cdot \|u - \hat{u}\|_H + \frac{1}{h} \|a - \hat{a}\|_X \right\}^2 \end{aligned} \quad (2 \cdot 22)$$

which gives the continuity and boundedness of  $T_n$ . For the coercivity, let us take  $(a, u) \in G$ ,

$$\begin{aligned} \langle T_n(a, u), (a, u) \rangle &= \langle \frac{\varepsilon}{h}u + A_1(a) + A_2(a, u), u \rangle + \frac{1}{h} \|a\|_X^2 \\ &\quad - \langle A_1(a), u \rangle - \langle A_2(a, u), u - u^* \rangle \\ &= \frac{\varepsilon}{h} \|u\|_H^2 + \frac{1}{h} \|a\|_X^2 + \langle A_2(a, u), u^* \rangle \end{aligned}$$

exists a  $w^* \in S(u^*)$ , satisfying

$$\langle w^* + A_1(a^*) + A_2(a^*, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \geq 0, \quad \forall v \in C \quad (2 \cdot 1)$$

Here similar to [4], we assume;

(A1)  $S; D(S) \subset V \rightarrow 2^{V^*}$  is a maximal monotone graph with  $u^* \in \text{int } D(S)$ .

(A2)  $A_1; X \rightarrow V^*$  is linear and bounded, with

$$\|A_1(a)\|_{V^*} \leq \|A_1\| \|a\|_X, \quad \forall a \in X \quad (2 \cdot 2)$$

(A3)  $A_2; D(A_2) \subset X \times V \rightarrow V^*$  is bilinear with

$$X_0 \times V \subset D(A_2) \quad (2 \cdot 3)$$

$$|\langle A_2(a, u), v \rangle| \leq \|A_2\| \|a\|_{X_0} \|u\|_V \|v\|_{V^*}, \quad \forall (a, u, v) \in X_0 \times V \times V \quad (2 \cdot 4)$$

$$\langle A_2(a, u - v), u - v \rangle \geq \delta \|u - v\|_V^2, \quad \forall (a, u, v) \in K \times C \times C \quad (2 \cdot 5)$$

for some positive number  $\delta$ .

(A4)  $\Psi; V \rightarrow \mathbb{R}$  is continuous and convex.

(A5) Problem (P) has at least one solution  $a^* \in K$ .

Now we turn to study a finite dimensional analogue of Problem (P). Let  $V_N \subset V, W_M \subset X_0$  be two finite dimensional subspaces, satisfying the following assumptions;

(A6)  $u^* \in V_N, P_{W_M}(K) \subset K$ , where,  $P_{W_M}; X \rightarrow W_M$  is the orthogonal projection.

(A7) For any  $a \in (I - P_{W_M})(K) \subset W_M^\perp, u, v \in C \cap V_N$ ,

$$\langle A_1(a) + A_2(a, u), v - u^* \rangle = 0 \quad (2 \cdot 6)$$

Our finite dimensional identification problem is the following;

**Problem (P<sup>N</sup>).** Given  $u^* \in D(S) \cap C \cap V_N, f^* \in V^*$ , find  $a^N \in K \cap W_M$ , such that there exists a  $w^* \in S(u^*)$ , satisfying

$$\langle w^* + A_1(a^N) + A_2(a^N, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \geq 0 \quad \forall v \in C \cap V_N \quad (2 \cdot 7)$$

We now introduce a sequence of systems of variational inequalities, the solutions of which will converge to a solution of Problem (P<sup>N</sup>). Let  $\varepsilon > 0, h > 0$  be given, we consider the following problem;

**Problem (P<sub>h</sub>).** Given  $(a_0, u_0) \in (K \cap W_M) \times (D(S) \cap C \cap V_N)$ , find  $(a_n, u_n) \in (K \cap W_M) \times (D(S) \cap C \cap V_N)$ , such that there exists a  $w_n \in S(u_n)$ , satisfying

$$\left\{ \begin{array}{l} \langle \frac{u_{n+1} - u_n}{h} + w_{n+1} + A_1(a_{n+1}) + A_2(a_{n+1}, u_{n+1}) - f^*, \hat{u} - u_{n+1} \rangle \\ \quad + \Psi(\hat{u}) - \Psi(u_{n+1}) \geq 0 \\ \left[ \frac{a_{n+1} - a_n}{h}, \hat{a} - a_{n+1} \right] - \langle A_1(\hat{a} - a_{n+1}) \\ \quad + A_2(\hat{a} - a_{n+1}, u_{n+1}), u_{n+1} - u^* \rangle \geq 0 \end{array} \right. \quad (2 \cdot 8)$$

$$\forall (\hat{a}, \hat{u}) \in G_{\underline{\Delta}}(K \cap W_M) \times (C \cap V_N), n = 1, 2, \dots$$

It is clear that at  $(n+1)$ -th step of Problem (P<sub>h</sub>), we want to solve the following equivalent problem;

For  $(a_n, u_n) \in (K \cap W_M) \times (D(S) \cap C \cap V_N)$ , find  $(a, u) \in (K \cap W_M) \times (D(S) \cap C \cap V_N)$ , such that there exists a  $w \in S(u)$ , with

$$\left\{ \begin{array}{l} \langle \frac{u - u_n}{h} + w + A_1(a) + A_2(a, u) - f^*, \hat{u} - u \rangle + \Psi(\hat{u}) - \Psi(u) \\ \quad + \left[ \frac{a - a_n}{h}, \hat{a} - a \right] - \langle A_1(\hat{a} - a) + A_2(\hat{a} - a, u), u - u^* \rangle \geq 0 \end{array} \right. \quad (2 \cdot 9)$$

$$\forall (\hat{a}, \hat{u}) \in G$$

Now, let us set  $B = W_M \times V_N$ . The dual pairing between elements of  $B^*$  and  $B$  is denoted by  $\langle \cdot, \cdot \rangle$ . It is clear that  $\dim B < \infty$ . We define  $T_n; B \rightarrow B^*$  and  $g_n; B \rightarrow \mathbb{R}$  as follows;

$$\begin{aligned}
&\geq \frac{\varepsilon}{h} \|u\|_H^2 + \frac{1}{h} \|a\|_X^2 - \alpha\beta \|A_2\| \|a\|_X \|u\|_H \|u^*\|_V \\
&\geq \left(\frac{\varepsilon}{h} - \frac{\alpha\beta}{2} \|A_2\| \|u^*\|_V\right) \|u\|_H^2 \\
&\quad + \left(\frac{1}{h} - \frac{\alpha\beta}{2} \|A_2\| \|u^*\|_V\right) \|a\|_X^2 \tag{2.23}
\end{aligned}$$

Hence, for given  $\varepsilon > 0$ , we can choose  $h_0 > 0$ , such that for any  $h \in (0, h_0]$ ,  $T_h$  is coercive with respect to  $0 \in B^*$ .

Finally, since  $T_h$  is continuous and  $\dim B < \infty$  we have

$$\lim_{m \rightarrow \infty} \{T_h(a_m, u_m), (a_m, u_m) - (a, u)\} = \{T_h(\hat{a}, \hat{u}), (\hat{a}, \hat{u}) - (a, u)\} \tag{2.24}$$

$\forall (a, u) \in B$

whenever  $(a_m, u_m) \rightarrow (\hat{a}, \hat{u})$  weakly. That means  $T_h$  is pseudomonotone. Then, our theorem follows a general theorem on variational inequalities (see [4] or [8]).

**Theorem 2.2.** Suppose (A1) – (A7) hold and  $\{(a_n, u_n)\}_{n=1}^\infty$  is a solution to Problem  $(P_h)$ . Then, there exists an  $a_\infty \in K \cap W_M$ , such that

$$\|u_n - u^*\|_V \rightarrow 0 \quad \text{as } n \rightarrow \infty \tag{2.25}$$

$$\|a_n - a_\infty\|_X \rightarrow 0 \quad \text{as } n \rightarrow \infty \tag{2.26}$$

and  $a_\infty$  is a solution of Problem  $(P^N)$ .

**Proof.** Set  $q_n = u_n - u^*$ ,  $\gamma_n = a_n - a^*$ . Similar to [4], we can get the following a priori estimates.

$$\varepsilon \|q_{n+1}\|_H^2 + \|\gamma_{n+1}\|_X^2 + \delta \|q_{n+1}\|_V^2 \leq \varepsilon \|q_n\|_H^2 + \|\gamma_n\|_X^2 \tag{2.27}$$

$$\begin{aligned}
\sup_{n \in \mathbb{N}} \{\varepsilon \|q_n\|_H^2 + \|\gamma_n\|_X^2\} + 2\delta h \sum_{k=1}^{\infty} \|q_k\|_V^2 \\
\leq \varepsilon \|q_0\|_H^2 + \|\gamma_0\|_X^2 < \infty \tag{2.28}
\end{aligned}$$

Thus, (2.25) follows (2.28). On the other hand, (2.28) implies  $\|a_n\|_X$  is bounded. Therefore there is a subsequence  $a_{n_k}$  such that

$$a_{n_k} \rightarrow a_\infty \in K \cap W_M \text{ in } X \tag{2.29}$$

It is clear that  $a_\infty$  is a solution of Problem  $(P^N)$ . The derivation of (2.27) and (2.28) shows that the same estimates also hold if we replace  $\gamma_n$  by  $a_n - a_\infty$ . Thus, we have, in particular,

$$\varepsilon \|q_{n+1}\|_H^2 + \|a_{n+1} - a_\infty\|_X^2 \leq \varepsilon \|q_n\|_H^2 + \|a_n - a_\infty\|_X^2 \tag{2.30}$$

This implies  $\lim_{n \rightarrow \infty} (\varepsilon \|q_n\|_H^2 + \|a_n - a_\infty\|_X^2)$  exists. Together with the proved (2.25), we have

$$\lim_{n \rightarrow \infty} \|a_n - a_\infty\|_X = d \tag{2.31}$$

Then, (2.26) follows (2.29) and (2.31).

### 3. Stability and Solution of Problem $(P)$

In this section we first show that the limit point  $a_\infty$  of  $(P_h)$  is stable against perturbations in the initial data.

**Theorem 3.1.** Let (A1) – (A7) hold. Assume that initial data  $(a_0^\lambda, u_0^\lambda)$ ,  $|\lambda| \leq \lambda_0$ , are given such that

$$a_0^\lambda \rightarrow a_0^0, u_0^\lambda \rightarrow u_0^0, \text{ as } \lambda \rightarrow 0 \tag{3.1}$$

Then there is an  $\hat{h} \in (0, h_0]$  such that for  $0 < h \leq \hat{h}$  the following assertion holds: If  $\{a_n^\lambda, u_n^\lambda\}_{n \geq 1}$  solves  $(P_h)$  with initial data  $(a_0^\lambda, u_0^\lambda)$ ,  $|\lambda| \leq \lambda_0$ , and  $a_\infty^\lambda$  is the limit point of  $\{a_n^\lambda\}$ , then

$$a_\infty^\lambda \rightarrow a_\infty^0, \text{ as } \lambda \rightarrow 0 \tag{3.2}$$

**Proof.** Let  $0 < h \leq h_0$ . From (2.8), we have

$$\begin{aligned} & \langle e \frac{u_{n+1}^\lambda - u_n^\lambda}{h} + w_{n+1}^\lambda + A_1(a_{n+1}^\lambda) + A_2(a_{n+1}^\lambda, u_{n+1}^\lambda) - f^*, v - u_{n+1}^\lambda \rangle \\ & + \Psi(v) - \Psi(u_{n+1}^\lambda) \geq 0, \quad \forall v \in C \cap V_N \end{aligned} \quad (3.3)$$

with some  $w_{n+1}^\lambda \in S(u_{n+1}^\lambda)$ ,

$$\begin{aligned} & \left[ \frac{a_{n+1}^\lambda - a_n^\lambda}{h}, \eta - a_{n+1}^\lambda \right] - \langle A_1(\eta - a_{n+1}^\lambda) + A_2(\eta - a_{n+1}^\lambda, u_{n+1}^\lambda), u_{n+1}^\lambda - u^* \rangle \geq 0 \\ & \quad \forall \eta \in K \cap W_M \end{aligned} \quad (3.4)$$

Let  $y_n^\lambda = u_n^\lambda - u_n^0$ ,  $\gamma_n^\lambda = a_n^\lambda - a_n^0$ ,  $q_n^\lambda = u_n^\lambda - u^*$ . Then it follows from (3.3), (3.4):

$$\begin{aligned} & \langle e \frac{u_{n+1}^\lambda - u_n^\lambda}{h} + w_{n+1}^\lambda + A_1(a_{n+1}^\lambda) + A_2(a_{n+1}^\lambda, u_{n+1}^\lambda) - f^*, u_{n+1}^\lambda - u_{n+1}^0 \rangle \\ & + \Psi(u_{n+1}^\lambda) - \Psi(u_{n+1}^0) \leq 0 \leq \langle e \frac{u_{n+1}^0 - u_n^0}{h} + w_{n+1}^0 + A_1(a_{n+1}^0) \\ & + A_2(a_{n+1}^0, u_{n+1}^0) - f^*, u_{n+1}^\lambda - u_{n+1}^0 \rangle + \Psi(u_{n+1}^\lambda) - \Psi(u_{n+1}^0) \end{aligned}$$

hence

$$\begin{aligned} & \langle e \frac{y_{n+1}^\lambda - y_n^\lambda}{h}, y_{n+1}^\lambda \rangle + \langle A_2(a_{n+1}^0, y_{n+1}^\lambda), y_{n+1}^\lambda \rangle \\ & + \langle A_1(\gamma_{n+1}^\lambda) + A_2(\gamma_{n+1}^\lambda, u_{n+1}^\lambda), y_{n+1}^\lambda \rangle \leq 0 \end{aligned} \quad (3.5)$$

Putting  $\eta = a_{n+1}^0$  in (3.4) yields:

$$\begin{aligned} & \left[ \frac{\gamma_{n+1}^\lambda - \gamma_n^\lambda}{h}, \gamma_{n+1}^\lambda \right] + \left[ \frac{a_{n+1}^0 - a_n^0}{h}, \gamma_{n+1}^\lambda \right] - \langle A_1(\gamma_{n+1}^\lambda) + A_2(\gamma_{n+1}^\lambda, u_{n+1}^\lambda), y_{n+1}^\lambda \rangle \\ & - \langle A_1(\gamma_{n+1}^\lambda) + A_2(\gamma_{n+1}^\lambda, u_{n+1}^\lambda), q_{n+1}^0 \rangle \leq 0 \end{aligned}$$

and putting  $\lambda = 0$ ,  $\eta = a_{n+1}^0$  in (3.4) yields:

$$\left[ \frac{a_{n+1}^0 - a_n^0}{h}, \gamma_{n+1}^\lambda \right] \geq \langle A_1(\gamma_{n+1}^\lambda) + A_2(\gamma_{n+1}^\lambda, u_{n+1}^0), q_{n+1}^0 \rangle$$

So we have

$$\begin{aligned} & \langle A_1(\gamma_{n+1}^\lambda) + A_2(\gamma_{n+1}^\lambda, u_{n+1}^\lambda), y_{n+1}^\lambda \rangle \\ & \geq \left[ \frac{\gamma_{n+1}^\lambda - \gamma_n^\lambda}{h}, \gamma_{n+1}^\lambda \right] - \langle A_2(\gamma_{n+1}^\lambda, y_{n+1}^\lambda), q_{n+1}^0 \rangle \end{aligned} \quad (3.6)$$

Combining (3.5) and (3.6), we get

$$\begin{aligned} & \langle e \frac{y_{n+1}^\lambda - y_n^\lambda}{h}, y_{n+1}^\lambda \rangle + \left[ \frac{\gamma_{n+1}^\lambda - \gamma_n^\lambda}{h}, \gamma_{n+1}^\lambda \right] \\ & + \langle A_2(a_{n+1}^0, y_{n+1}^\lambda), y_{n+1}^\lambda \rangle - \langle A_2(\gamma_{n+1}^\lambda, y_{n+1}^\lambda), q_{n+1}^0 \rangle \leq 0 \end{aligned} \quad (3.7)$$

This is the same inequality as (2.25) in [4]. Starting from this inequality and using the same arguments as in [4], we can obtain the assertion of Theorem 3.1.

Now we discuss the situation as  $\dim V_N \rightarrow \infty$ . Let  $\{V_N\}_{N \geq 2}$  be a sequence of subspaces of  $V$  such that (A6) holds and  $u_0 \in D(S) \cap C \cap V_N, \forall N \geq 2$ . Assume to each  $N$  that there is a subspace  $W_{M(N)}$  of  $X_0$  such that (A7) holds and  $a_0 \in W_{M(N)}$ .

We assume further that:

(A8)  $(V, \|\cdot\|)$  is a Hilbert space, i. e.,  $\|\cdot\|_V$  is induced by an inner product  $(\cdot, \cdot)$  on  $V$ .

(A9)  $V_N \subset V_{N+1}, \forall N \geq 2; \bigcup_{N=2}^{\infty} V_N$  is dense in  $V$ .  $P_{V_N}(C) \subset C, \forall N \geq 2$ , where  $P_{V_N}$  denotes the  $(\cdot, \cdot)$ -orthogonal projection operator onto  $V_N$ .

(A10)  $a_n \in K, a_n \rightarrow a$  weakly in  $X$  implies  $A_2(a_n, u^*) \rightarrow A_2(a, u^*)$  weakly in  $V^*$ .

**Theorem 3.3.** Let (A1) - (A10) hold. If  $\{a_\infty^N\}$  denotes a sequence of limit points of the solution of  $(P_{M(N)})$ , then each subsequence has a weak cluster point in  $K$  which solves (P).

**Proof.** By Theorem 2.2 for any  $N \geq 2$ , there exists an  $a_\infty^N \in K \cap W_{M(N)}$  such that with some  $w_\infty^N \in S(u^*)$

$$\langle w_\infty^N + A_1(a_\infty^N) + A_2(a_\infty^N, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \geq 0, \quad (3.8)$$

$$\forall v \in C \cap V_N$$

The a priori estimate (2.28) gives that  $\{a_\infty^N\}$  is bounded in  $X$ . Thus a subsequence, again denoted by  $a^N$ , converges weakly in  $X$  to some  $a \in K$ . By the boundedness of  $S(u^*)$  we may assume that  $w^N \rightarrow w^*$  weakly in  $V^*$ , where  $w^* \in S(u^*)$  by the maximal monotonicity.

Now we show that  $a_\infty$  is a solution of (P) with  $w^* \in S(u^*)$ .

Let  $v \in C$  be arbitrary. By (A9),  $P_{V_N}v \in C \cap V_N$  and  $\|P_{V_N}v - v\|_V \rightarrow 0$ , as  $N \rightarrow \infty$ . We have

$$\begin{aligned} & \langle w^* + A_1(a_\infty) + A_2(a_\infty, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \\ &= [\langle w_\infty^N + A_1(a_\infty^N) + A_2(a_\infty^N, u^*) - f^*, P_{V_N}v - u^* \rangle + \Psi(P_{V_N}v) - \Psi(u^*)] \\ & \quad + [\langle w^* - w_\infty^N + A_1(a_\infty - a_\infty^N) + A_2(a_\infty - a_\infty^N, u^*), P_{V_N}v - u^* \rangle \\ & \quad + \Psi(v) - \Psi(P_{V_N}v)] + [\langle w^* + A_1(a_\infty) + A_2(a_\infty, u^*) - f^*, v - P_{V_N}v \rangle] \end{aligned}$$

The first bracket is nonnegative by (3.8), and the second and third brackets approach 0 as  $N \rightarrow \infty$ . Hence passing to the limit as  $N \rightarrow \infty$  yields

$$\langle w^* + A_1(a_\infty) + A_2(a_\infty, u^*) - f^*, v - u^* \rangle + \Psi(v) - \Psi(u^*) \geq 0, \forall v \in C$$

i. e.  $a_\infty$  solves Problem (P).

#### 4. Applications

The method in this paper can be applied to many physical problems including all the examples in [4]. For the sake of comparison, we take Example 1 in [4] as our first example and discuss it once again using our method. Then we take nonstationary dam problem as our second example. In our examples below  $\Omega \subset R^m$  is open and bounded with a sufficiently smooth boundary  $\partial\Omega$ .

**Example 1.** Consider the problem

$$\begin{aligned} & \text{Given } u^* \in H_0^1(\Omega) \cap H^{1,\infty}(\Omega) \text{ and } f^* \in H^{-1}(\Omega) \text{ find a matrix} \\ & a^* = (a_{ij}^*) \text{ with } a^* \in K \text{ such that } -\nabla \cdot (a^* \nabla u^*) = f^* \end{aligned} \quad (4.1)$$

If we assume that

$$K = \{a = (a_{ij}); a_{ij} \in L^2(\Omega)\}$$

then problem (4.1) is just the same as Example 1 in [4]. Now let  $K$  be the set of physically admissible parameters which we assume to be of the form

$$\begin{aligned} K = \{a = (a_{ij}); a_{ij} \in L^\infty(\Omega), a_{ij} = a_{ji}, \|a_{ij}\|_{L^\infty(\Omega)} \leq \beta, \\ \xi^T a(x) \xi \geq \alpha |\xi|^2, \forall \xi \in R^m, \text{ a. e. in } \Omega\} \end{aligned} \quad (4.2)$$

here  $\alpha > 0, \beta > 0$  are fixed constants.

Problem (4.1) with  $K$  satisfying (4.2) is the restricted parameter identification problem. After making some specifications as in [4], one can see that the assumptions (A1) - (A10) might be satisfied. Therefore we can apply the method which is developed in previous sections to this problem.

**Example 2.** (Nonstationary dam problem)

We consider nonstationary fluid (say water) flows through a porous medium (say dam)  $\Omega \subset R^m$ . Let  $\Gamma_1$  be the boundary to the imperious ground,  $T \in R, 0 < T < \infty$ , and set  $Q = \Omega \times (0, T)$ ,  $\sum_1 = \Gamma_1 \times (0, T)$ ,  $\sum = \partial\Omega \times (0, T)$ ,  $\sum_2 = \sum \setminus \sum_1$ . Assume that the boundary data for pressure  $u(x, t)$  are given by

$$g^* \in L^2(0, t; H^{1,\infty}(\Omega)), g^* \geq 0 \quad (4.3)$$

Now we can state the weak formulation for the nonstationary dam problem as follows

Given  $a^* \in K$  (see (4.2)), find a pair

$$(u^*, \gamma^*) \in L^2(0, T; H^1(\Omega)) \times L^\infty(Q) \text{ with } u^* \geq 0 \text{ in } Q, u^* = g^* \text{ on } \sum_2, \\ \gamma^* \in H(u^*), \gamma^*(x, 0) = \gamma_0 \text{ in } \Omega, \text{ such that}$$

$$\iint_Q \nabla v \cdot a^* (\nabla u^* + \gamma^* \vec{e}) - \gamma^* v_t \leq 0, \quad \forall v \in H^1(Q), \quad (4.4)$$

$$v = 0 \text{ on } \Omega \times \{0, T\}, v = 0 \text{ on } \sum_2 \cap \{g^* > 0\},$$

$$v \geq 0 \quad \text{on} \quad \sum_2 \cap [g^* = 0]$$

where  $\vec{e} = \nabla x_m$ . Set

$$\hat{H}^1(\Omega) = \{v \in H^1(\Omega); v = 0 \text{ on } \partial\Omega \setminus \Gamma_1\} \quad (4.5)$$

and let  $(u^*, \lambda^*)$  be a solution of (4.4). Then for any  $v \in \mathcal{D}(0, T; \hat{H}^1(\Omega))$ , we have

$$\iint_Q \nabla v \cdot a^*(\nabla u^* + \gamma^* \vec{e}) - \gamma^* v_i = 0$$

i. e.

$$\iint_Q \gamma^* v_i = \iint_Q \nabla v \cdot a^*(\nabla u^* + \gamma^* \vec{e})$$

Therefore

$$\begin{aligned} \left| \iint_Q \gamma^* v_i \right| &\leq \left\{ \iint_Q |a^*(\nabla u^* + \gamma^* \vec{e})|^2 \right\}^{1/2} \cdot \left\{ \iint_Q |\nabla v|^2 \right\}^{1/2} \\ &\leq C \cdot \|v\|_{L^2(0, T; H^1(\Omega))} \end{aligned}$$

This shows that

$$\gamma_i^* \in L^2(0, T; \hat{H}^1(\Omega)^*) \quad (4.6)$$

and

$$\iint_Q \nabla v \cdot a^*(\nabla u^* + \gamma^* \vec{e}) + \langle \gamma_i^* | v \rangle = 0, \quad \forall v \in L^2(0, T; \hat{H}^1(\Omega)) \quad (4.7)$$

where  $\langle \cdot | \cdot \rangle$  denotes the dual pairing between elements of  $L^2(0, T; \hat{H}^1(\Omega)^*)$  and  $L^2(0, T; \hat{H}^1(\Omega))$ . (4.7) can be rewritten as;

$$\iint_Q \nabla v \cdot a^*(\nabla u^* + \nabla g^* + \gamma^* \vec{e}) + \langle \gamma_i^* | v \rangle = 0, \quad \forall v \in L^2(0, T; \hat{H}^1(\Omega)) \quad (4.8)$$

where  $u^* \in L^2(0, T; \hat{H}^1(\Omega))$ ,  $u^* \geq -g^*$ .

Now we can describe the corresponding restricted parameter identification problem as follows;

$$\begin{cases} \text{Given } u^* \in L^2(0, T; \hat{H}^1(\Omega)) \text{ with } u^* \geq -g^* \text{ and } \gamma^* \subset H(u^* + g^*), \\ \gamma_i^* \in L^2(0, T; \hat{H}^1(\Omega)^*), \text{ find } a^* \in K \text{ such that (4.8) holds.} \end{cases} \quad (4.9)$$

We show that the theory of above sections applies.

Let

$$H = L^2(Q)$$

$$V = L^2(0, T; \hat{H}^1(\Omega)) \text{ where } \hat{H}^1(\Omega) \text{ is defined by (4.5)}$$

$$C = V$$

$$X = \{a = (a_{ij}); a_{ij} \in L^2(\Omega), \forall i, j\}$$

$$X_0 = \{a = (a_{ij}); a_{ij} \in L^\infty(\Omega), \forall i, j\}$$

$$K \text{ is defined by (4.2)}$$

and let

$$S = \theta$$

$$\langle A_1(a) | v \rangle = \iint_Q \nabla v \cdot a(\nabla g^* + \gamma^* \vec{e})$$

$$\langle A_2(a, u) | v \rangle = \iint_Q \nabla v \cdot a \nabla u$$

$$\langle f | v \rangle = - \langle \gamma_i^* | v \rangle$$

$$\Psi = 0$$

Using these notations, it is easy to see that problem (4.9) is a special case of Problem (P) which is described in section 2. Using the same arguments as in Example 3 (Dam problem) of [4], one can easily see that all the assumptions (A1) — (A10) might be satisfied if we additionally have that  $u^* \in L^2(0, T; H^{1,\infty}(\Omega))$ .

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