

## THE INERTIAL FRACTAL SETS FOR NONLINEAR SCHRÖDINGER EQUATIONS\*

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**Abstract** The existence of inertial fractal sets for weakly dissipative Schrödinger equations which possess  $(E_0, E)$  type compact attractor is proved. The estimates of the upper bounds of fractal dimension of inertial fractal set are also obtained.

**Key Words** Schrödinger inertial fractal set.

**Classification** 35Q55.

### 1. Introduction

In the study of the inertial manifold of the 2D Navier-Stokes equations (NSE) representing turbulent flows, one finds out that [2] since there exist spectral barriers and spectral gap conditions, the existence of an inertial manifold for 2D NSE is still a mystery. Recently, Eden et al. [3] have studied and discovered that some dissipative evolution equations with real coefficients, for which the  $(E, E)$  type compact attractors exist, including 2D NSE, have a kind of set similar to inertial manifold-inertial set. This paper advances the previous results to complex weakly infinite dimensional dynamical system that only possesses  $(E_0, E)$  type compact attractors.

### 2. Main Results

Let  $D(A)$ ,  $V$  be two Hilbert spaces,  $D(A)$  be dense in  $V$  and compactly imbedded into  $V$ .

We study

$$\frac{du}{dt} + Au + g(u) = f(x), \quad t > 0, x \in \Omega \quad (1)$$

$$u(0) = u_0 \quad (2)$$

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$$u|_{\partial\Omega} = 0 \quad (3)$$

where  $\Omega$  is a bounded open set in  $R^n$ ,  $\partial\Omega$  is smooth.  $A$  is a positive self adjoint operator with a compact inverse. Let  $\{w_n, n = 1, 2, \dots\}$  denote the complete set of eigenvectors of  $A$ , the corresponding eigenvalues are

$$0 < \lambda_1 < \lambda_2 < \dots < \lambda_n < \dots \nearrow +\infty \quad (4)$$

We assume that the nonlinear semigroup  $S(t)$  defined in (1)–(3) possesses a  $(D(A), V)$  type compact attractor, namely, there exists a compact  $\mathcal{A}$  in  $V$ ,  $\mathcal{A}$  attracts all bounded subsets in  $D(A)$  and it is invariant under the action of  $S(t)$ .

**Definition 1** A compact set  $M$  in  $V$  is called an inertial fractal set of  $(D(A), V)$  type for  $(S(t), B)$  if  $\mathcal{A} \subseteq M \subseteq B$  and

1.  $S(t)M \subseteq M, \forall t \geq 0$ ,
2.  $M$  has finite fractal dimension,  $d_F(M) < \infty$ ,
3. there exist positive constants  $c_0, c_1$  such that

$$\text{dist}_V(S(t)B, M) \leq c_0 e^{-c_1 t}, \quad \forall t > 0$$

where  $\text{dist}_V(A, B) = \sup_{x \in A} \inf_{y \in B} |x - y|_V$ ,  $B$  is a positively invariant set for  $S(t)$  in  $V$ .

**Definition 2**<sup>[3]</sup> If for every  $\delta \in \left(0, \frac{1}{8}\right)$ , there exists an orthogonal projection  $P_{N_0}$  of rank equal to  $N_0$  such that for every  $u$  and  $v$  in  $B$ , either

$$|S(t_*)u - S(t_*)v|_V \leq \delta |u - v|_V \quad (5)$$

or

$$|Q_{N_0}(S(t_*)u - S(t_*)v)|_V \leq |P_{N_0}(S(t_*)u - S(t_*)v)|_V \quad (6)$$

Then we call  $S(t)$  is squeezing in  $B$ , where  $Q_{N_0} = I - P_{N_0}$ .

**Theorem 1** Suppose (1)–(3) satisfies the following conditions

1. there exists a  $(D(A), V)$  type compact attractor  $\mathcal{A}$ .
2. there exists a compact set  $B$  in  $V$  which is positively invariant for  $S(t)$ .
3.  $S(t)$  is squeezing and Lipschitz continuous, that is there exists a bounded function  $l(t)$  such that  $|S(t)u - S(t)v|_V \leq l(t)|u - v|_V$  for every  $u, v$  in  $B$ .

Then (1)–(3) admits a  $(D(A), V)$  type inertial fractal set  $M$  for  $(S(t), B)$  and

$$M = \bigcup_{0 \leq t \leq t_*} S(t)M_* \quad (7)$$

where

$$M_* = \mathcal{A} \cup \left( \bigcup_{j=1}^{\infty} \bigcup_{k=1}^{\infty} S(t_*)^j (E^{(k)}) \right) \quad (8)$$



Moreover,

$$d_F(M) \leq 1 + N_0 \log \left( 1 + \sqrt{2}l/\delta \right) / \log \frac{1}{\theta} \quad (9)$$

$$\text{dist}_V(S(t)B, M) \leq c_0 e^{-c_1 t} \quad (10)$$

where  $\theta, N_0, E^{(k)}$  are defined as in [3],  $l$  is the Lipschitz constant for  $S(t_*)$  in  $B$ .  $t_*$  is a positive constant.

**Proof** We utilize that  $B$  is compact in  $V$  and it is positive invariance for  $S(t)$ , with  $B$  instead of  $X$  in [3], note also that  $S(t)$  is Lipschitz continuous and has a squeezing property in  $B$ , then this theorem is proved by the same manner of the proof of Theorem 1 in [3].

**Proposition 1** Suppose that problem (1)–(3) possesses a unique global solution,  $u \in C_w(R_+, D(A))$ , if  $u_0 \in D(A)$ ;  $u \in C(R_+, V)$  if  $u_0 \in V$ . Moreover there exist closed absorbing sets  $B_0, B_1$  in  $D(A), V$  respectively. Then nonlinear semigroup  $S(t)$  defined by problem (1)–(3) possesses a  $(D(A), V)$  type compact attractor

$$\mathcal{A} = \overline{\bigcap_{t \geq 0} S(t)B_0} \quad (11)$$

$\mathcal{A}$  is bounded in  $D(A)$ . Notation  $C_w$  denotes the class of function which is weakly continuous with respect to  $t$  in topology of  $D(A)$ .

**Proof** From [5] we know  $\mathcal{A}$  is a weakly compact attractor in  $D(A)$  and attracts all bounded set in  $D(A)$  with respect to weak topology in  $D(A)$ . Since weakly bounded property is equivalent to strongly bounded property in Hilbert space, we deduce that  $\mathcal{A}$  is bounded set in  $D(A)$ , by the compact imbedding of  $D(A)$  into  $V$  we know  $\mathcal{A}$  is compact in  $V$ . Suppose  $B$  is any bounded set in  $D(A)$ , since  $\mathcal{A}$  attracts every bounded set in  $D(A)$  with respect to weak topology in  $D(A)$ , we can extract a sequence  $S(t_n)B$ , which weakly converges to  $\mathcal{A}$  in  $D(A)$  as  $t_n \rightarrow +\infty$ , by the compact imbedding of  $D(A)$  into  $V$  we know  $S(t_n)B$  strongly converges to  $\mathcal{A}$  in  $V$ , this shows that  $\mathcal{A}$  is a  $(D(A), V)$  type attractor.

**Proposition 2** There exists  $t_0(B_0)$  such that

$$B = \bigcup_{0 \leq t \leq t_0(B_0)} S(t)B_0 \quad (12)$$

is a compact, positively invariant set in  $V$  and is absorbing set for all bounded subset in  $D(A)$ .

**Proof** By the definition of  $B_0$  we know that, there exists  $t_0(B_0)$  such that

$$S(t)B_0 \subseteq B_0 \quad \text{for } t \geq t_0(B_0)$$

It is easy to check that  $B$  defined in (12) satisfies that result of this proposition. Indeed, denoting  $t = kt_0(B_0) + t_1$ ,  $0 \leq t_1 \leq t_0(B_0)$ , we have

$$S(t)B = \overline{\bigcup_{t_1 \leq s \leq t_0(B_0)} S(s)S(kt_0(B_0))B_0} \bigcup \overline{\bigcup_{0 \leq s \leq t_1} S(s)S((k+1)t_0(B_0))B_0}$$

$$\subseteq \overline{\bigcup_{t_1 \leq s \leq t_0(B_0)} S(s)B_0} \cup \overline{\bigcup_{0 \leq s \leq t_1} S(s)B_0} \subseteq \overline{\bigcup_{0 \leq s \leq t_0(B_0)} S(s)B_0} = B$$

Since  $D(A)$  is imbedded into  $V$  compactly, we deduce that  $B$  is compact in  $V$ , absorba-  
bility of  $B$  is clear.

**Proposition 3** *Let  $u_1(t), u_2(t)$  be two solutions of problem (1)-(3) with  $u_1(0), u_2(0) \in B$  respectively, setting  $w(t) = u_1 - u_2$ . If*

$$1. |w(t)|_V^2 \leq ke^{\alpha t} |w(0)|_V^2, \tag{13}$$

$$2. \frac{d}{dt} \varphi(Q_N w) + c_0 \varphi(Q_N w) \leq c_1 \lambda_{N+1}^{-2\beta} |Q_N w|_V^2 \tag{14}$$

*holds, then there exists  $t_*$  such that  $S(t_*)$  is Lipschitz continuous and squeezing in  $B$  where  $\varphi(Q_N w)$  satisfies*

$$|Q_N w(t)|_V^2 \leq k_0 \varphi(Q_N w) \leq k_1 |Q_N w(t)|_V^2 \tag{15}$$

$k_0, k_1, k, c_0, c_1, \alpha, \beta$  are positive constants independent of  $w(t)$ ,  $Q_N w = w|_{Q_N V}$   $\lambda_{N+1}$  is eigenvalue as in (4),  $N$  satisfies

$$c_1 k_0 k (\alpha + c_0)^{-1} \lambda_{N+1}^{-2\beta} e^{2\alpha t_*} < \frac{1}{256} \tag{16}$$

$t_*$  satisfies

$$k_1 e^{-c_0 t_*} < \frac{1}{256} \tag{17}$$

**Proof** From (14), by Gronwall's inequality we have

$$\begin{aligned} \varphi(Q_N w) &\leq \varphi(Q_N w(0)) e^{-c_0 t} + c_1 k \lambda_{N+1}^{-2\beta} e^{\alpha t} |Q_N w(0)|_V^2 e^{-c_0 t} \int_0^t e^{(\alpha+c_0)s} ds \\ &\leq k_0^{-1} k_1 |Q_N w(0)|_V^2 e^{-c_0 t} + c_1 k (\alpha + c_0)^{-1} \lambda_{N+1}^{-2\beta} e^{2\alpha t} |Q_N w(0)|_V^2 \\ &\leq |w(0)|_V^2 \left[ k_0^{-1} k_1 e^{-c_0 t} + c_1 k (\alpha + c_0)^{-1} \lambda_{N+1}^{-2\beta} e^{2\alpha t} \right] \end{aligned} \tag{18}$$

Let  $t_*$  be large enough so that

$$k_1 e^{-c_0 t_*} < \frac{1}{256} \tag{19}$$

Next we choose  $N$  large enough so that

$$c_1 k_0 k (\alpha + c_0)^{-1} e^{2\alpha t_*} \lambda_{N+1}^{-2\beta} < \frac{1}{256} \tag{20}$$

From (18)-(20) we obtain that

$$k_0 \varphi(Q_N w(t)) \leq \frac{1}{2} \delta^2 |w(0)|_V^2, \quad \delta \in \left(0, \frac{1}{8}\right) \tag{21}$$

Then from (15) we have

$$|Q_N w(t_*)|_V^2 \leq \frac{1}{128} |w(0)|_V^2 \tag{22}$$



So

$$|w(t_*)|_V^2 = |P_N w|_V^2 + |Q_N w|_V^2 < 2|Q_N w(t_*)|_V^2 < \frac{1}{64}|w(0)|_V^2$$

when  $|Q_N w(t_*)|_V^2 > |P_N w(t_*)|_V^2$ . It completes the proof of proposition. By Propositions 1-3 and Theorem 1, we immediately have

**Theorem 2** Suppose that problem (1)-(3) satisfies the conditions of Proposition 3 and there exist bounded and closed absorbing sets  $B_0, B_1$  in  $D(A), V$  respectively.

Then  $(S(t), B)$  admits a  $(D(A), V)$  type inertial fractal set  $M$  and

$$d_F(M) \leq 1 + N_0 \log(1 + \sqrt{2}l/\delta) / \log \frac{1}{\theta} \quad (23)$$

$$\text{dist}_V(S(t)B, M) \leq c_0 e^{-c_1 t} \quad (24)$$

where  $l = ke^{\alpha t_*}$ ,  $\delta \in (0, \frac{1}{8})$ ,  $4\delta < \theta < 1$ ,  $c_0, c_1$  are constants,  $N_0$  satisfies (20),  $t_*$  satisfies (19).

## 2. Application

We consider

$$i \frac{du}{dt} - Au + g(|u|^2)u + i\gamma u = f(x), \quad (t, x) \in R_+ \times (0, l) \quad (25)$$

$$u(0) = u_0 \quad (26)$$

$$u(0, t) = u(l, t) = 0 \quad (\text{or } u(x, t) = u(x+l, t), \forall t > 0, x \in R) \quad (27)$$

where  $A = -\frac{\partial^2}{\partial x^2}$ ,  $g(s) \in C^2(R_+)$  satisfies

$$\lim_{s \rightarrow +\infty} \frac{h(s) - wG(s)}{s^3} \leq 0 \quad (28)$$

$$\lim_{s \rightarrow +\infty} \frac{G_+(s)}{s^3} = 0 \quad (29)$$

$$h(s) = sg(s), \quad G(s) = \int_0^s g(\sigma) d\sigma, \quad G_+(s) = \max\{0, G(s)\} \quad (30)$$

Let  $D(A) = H^2(0, l) \cap H_0^1(0, l)$ ,  $V = H_0^1(0, l)$  (or

$$D(A) = \{v \in H_{loc}^2(R), v(x+l) = v(x), \forall x \in R\}$$

$$V = \{v \in H_{loc}^1(R), v(x+l) = v(x), \forall x \in R\}$$

The norm of  $u$  in  $D(A)$  and  $V$  is defined by

$$\|u\|_{D(A)} = [ |u|_0^2 + l^2 |u_x|_0^2 + l^4 |u_{xx}|_0^2 ]^{1/2} \quad (31)$$

$$\|u\|_V = [ |u|_0^2 + l^2 |u_x|_0^2 ]^{1/2}, \quad |\cdot|_0 \text{ is the norm of } L^2(0, l) \quad (32)$$

**Proposition 4**<sup>[5]</sup> Suppose that  $g$  satisfies (28)-(29),  $f \in L^2(0, l)$ , then for problem (25)-(27), we have the following statements.

1. If  $u_0 \in V (D(A))$ , then there exists unique solution  $u$  and  $u \in C(R_+, V) \cap L^\infty(R_+, V)$ . ( $u \in C(R_+, D(A)) \cap L^\infty(R_+, D(A))$ )
2. There exists bounded closed absorbing set  $B_0, B_1$  respectively  $B_0 = \{u \in D(A), \|u\|_{D(A)} \leq \rho_{\infty,2}\}$ ,  $B_1 = \{u \in V, \|u\|_V \leq \rho_{\infty,1}\}$ .

From Proposition 2,

$$B = \overline{\bigcup_{0 \leq t \leq t_0(B_0)} S(t)B_0} \quad (33)$$

is a positively invariant compact convex set in  $V$ . In order to prove the existence of inertial fractal set of  $\{S(t), B\}$ , according to Theorem 2, the condition of Proposition 3 must be checked.

Let  $u_1, u_2$  be two solutions for problem (25)–(27),  $u_1(0), u_2(0) \in B$ , we set  $w(t) = u_1(t) - u_2(t)$ , then  $w(t)$  satisfies

$$i \frac{\partial w}{\partial t} - Aw + g(|u_1|^2)u_1 - g(|u_2|^2)u_2 + i\gamma w = 0 \quad (34)$$

By using

$$\frac{1}{2} \frac{d}{dt} |w_x|_0^2 = \text{Im}(iw_t - Aw, Aw) \quad (35)$$

and

$$\frac{1}{2} \frac{d}{dt} |w|_0^2 = \text{Im}(iw_t - Aw, w) \quad (36)$$

we have

$$\frac{1}{2} \frac{d}{dt} \|w\|_V^2 = \text{Im} \left( g(|u_2|^2)u_2 - g(|u_1|^2)u_1, w + l^2 Aw \right) - \gamma \|w\|_V^2 \quad (37)$$

Note that  $g(s) \in C^2(R_+)$ , so

$$g(|u_2|^2)u_2 - g(|u_1|^2)u_1 = g(|\xi|^2)w + g'(|\xi|^2)\xi^2\bar{w} + g'(|\xi|^2)|\xi|^2w \quad (38)$$

where  $\xi = \tau u_1 + (1 - \tau)u_2 \in B$ ,  $\tau \in (0, 1)$ . (notice that  $B$  is convex)

By using (38) we have

$$\text{Im} \left( g(|u_2|^2)u_2 - g(|u_1|^2)u_1, w \right) = \text{Im} \left( g'(|\xi|^2)\xi^2\bar{w}, w \right)$$

Note that  $|\xi|_{L^\infty} \leq \rho_{\infty,2}$ ;  $|g'(|\xi|^2)| \leq C$ , we have

$$\text{Im} \left( g(|u_2|^2)u_2 - g(|u_1|^2)u_1, w \right) \leq c\rho_{\infty,2}^2 |w|_0^2 \quad (39)$$

Also

$$\begin{aligned} \text{Im} \left( g(|u_2|^2)u_2 - g(|u_1|^2)u_1, Aw \right) &= \text{Im} \left( g(|\xi|^2)w \right. \\ &\quad \left. + g'(|\xi|^2)\xi^2w + g'(|\xi|^2)|\xi|^2w, Aw \right) \end{aligned}$$

$$= \text{Im} \left( 4g'(|\xi|^2) \text{Re}(\xi \bar{\xi}_x) w, w_x \right) + \text{Im} \left( g'(|\xi|^2) \xi^2 \bar{w}_x, w_x \right) \\ + \text{Im} \left( 2g''(|\xi|^2) \text{Re}(\xi \bar{\xi}_x) \bar{w} + 2g'(|\xi|^2) \xi \xi_x \bar{w} + 2g''(|\xi|^2) \text{Re}(\xi \xi_x) |\xi|^2 w, w_x \right) \quad (40)$$

Now using  $|\xi_x|_{L^\infty} \leq |\xi_x|_1^{1/2} |\xi|_0^{1/2} \leq \rho_{\infty,2}$  and  $L^\infty$  estimates on  $g'(|\xi|^2)$ ,  $g''(|\xi|^2)$ , we infer that

$$\left| \text{Im} \left( g(|u_2|^2) u_2 - g(|u_1|^2) u_1, Aw \right) \right| \leq c_3 |w_x|_0^2 + c'_4 \int_0^l |w| |w_x| dx \leq c_4 \|w\|_V^2 \quad (41)$$

Combining (37), (39), with (41), we have

$$\frac{d}{dt} \|w(t)\|_V^2 \leq c_6 \|w(t)\|_V^2 \quad (42)$$

Then

$$\|w(t)\|_V^2 \leq e^{c_6 t} \|w(0)\|_V^2 \quad (43)$$

where  $c_6$  depends only on  $\gamma, \rho_{\infty,2}, g, g', g''$ .

Let

$$\varphi(w) = \int_0^l \left\{ |w_x|^2 - g(|\xi|^2) |w|^2 - 2g'(|\xi|^2) \text{Re}(\xi \bar{w})^2 \right\} dx \quad (44)$$

Using the fact that  $|\xi|_{L^\infty} \leq \rho_{\infty,2}$  for  $\xi \in B$ ,  $g(|\xi|^2), g'(|\xi|^2) \leq c$ , we have

$$\|Q_N w(t)\|_V^2 \leq 2l^2 \varphi(Q_N w) \leq 2c_2 l^2 \|Q_N w(t)\|_V^2 \quad (45)$$

when

$$\lambda_{N+1} \geq l^{-2} + 2c_0 + 4c_0 \rho_{\infty,2}^2 \quad (46)$$

where  $c_2 = \max \{ l^{-2}, c_0 + 2c_0 \rho_{\infty,2}^2 \}$ .

We multiply (34) by  $\gamma \bar{w}$  and integrate on  $(0, l)$ , take the real part. Next we multiply again (34) by  $-\bar{w}_t$  and integrate on  $(0, l)$  take the real part, then we obtain respectively

$$\text{Im} \int_0^l \gamma \bar{w}_t w dx - \int_0^l \gamma |w_x|^2 dx + \gamma \int_0^l g'(|\xi|^2) |\xi|^2 |w|^2 dx + \gamma \int_0^l g(|\xi|^2) |w|^2 dx \\ + \text{Re} \int_0^l \gamma g'(|\xi|^2) \text{Re}(\xi \bar{w})^2 dx = 0 \quad (47)$$

$$\frac{1}{2} \frac{d}{dt} \left[ \int_0^l |w_x|^2 dx - \int_0^l \left[ 2g'(|\xi|^2) \text{Re}(\xi \bar{w})^2 + g(|\xi|^2) |w|^2 \right] dx \right] \\ + \gamma \text{Im} \int_0^l w \bar{w}_t dx = r(t, w) \quad (48)$$

where

$$r(t, w) = -\frac{1}{2} \int_0^l \| |w|^2 \frac{\partial}{\partial t} g(|\xi|^2) + \text{Re}(\xi \bar{w}) \frac{\partial}{\partial t} g'(|\xi|^2) \right.$$



$$+ 2g'(|\xi|^2) \operatorname{Re}(\xi\bar{w}) \operatorname{Re}(\xi_t\bar{w}) dx \quad (49)$$

We deduce from (47) and (48) that

$$\frac{1}{2} \frac{d}{dt} \varphi(w) + \gamma |w_x|_0^2 - R(t, w) = r(t, w) \quad (50)$$

where

$$\begin{aligned} R(t, w) = & \gamma \int_0^l g'(|\xi|^2) |\xi|^2 |w|^2 dx + \gamma \int_0^l g(|\xi|^2) |w|^2 dx \\ & + \gamma \operatorname{Re} \int_0^l g'(|\xi|^2) \operatorname{Re}(\xi\bar{w})^2 dx \end{aligned} \quad (51)$$

$$\text{Note that } \xi \in B, \text{ so } |R(t, w)| \leq c(\rho_{\infty, 2}, \gamma) |w|_0^2. \quad (52)$$

Returning to (25) we have

$$iu_t = Au - g(|u|^2)u - i\gamma u - f$$

According to  $u \in B, f \in L^2(0, l), u \in L^\infty(R_+, D(A))$ , we have  $u_t \in L^2(0, l)$ , and  $\xi_t \in L^2(0, l)$  that is  $|\xi_t|_0 \leq c(\rho_{\infty, 2}, |f|_0)$ . Therefore we obtain

$$\begin{aligned} |r(t, w)| & \leq c_1 \int_0^l |w|^2 |\xi_t| dx \leq c_1 |\xi_t| |w|_{L^4}^2 \leq c |w_x|_0^{1/2} |w|_0^{3/2} \\ & \leq \frac{\gamma}{2} |w_x|_0^2 + \frac{3}{4} c^{4/3} (2\gamma)^{-1/3} |w|_0^2 \end{aligned} \quad (53)$$

Substituting (52), (53) into (50), we obtain

$$\frac{d}{dt} \varphi(w) + \gamma |w_x|_0^2 \leq c_3 |w|_0^2 \quad (54)$$

where  $c_3 = c_1 c(\rho_{\infty, 2}, |f|_0) + 3c^{4/3}/4\sqrt[3]{2\gamma}$ ,  $c_1, c$  are constants which do not depend on  $w$ , constant  $c(\rho_{\infty, 2}, |f|_0)$  depends only on  $\rho_{\infty, 2}, |f|_0$ .

Using

$$\left| \int_0^l g(|\xi|^2) |w|^2 dx + 2 \int_0^l g'(|\xi|^2) \operatorname{Re}(\xi\bar{w})^2 dx \right| \leq c_4 |w|_0^2$$

we obtain

$$\frac{d}{dt} \varphi(Q_N w) + \gamma \varphi(Q_N w) \leq c_5 \lambda_{N+1}^{-1} \|Q_N w\|_V^2 \quad (55)$$

where  $c_5 = c_3 + c_4$ ,  $N$  satisfies (45).

Finally, we have

**Theorem 3** Suppose that  $u_1(t), u_2(t)$  be two solutions of the problem (25)–(27),  $f \in L^2(0, l), u_0 \in D(A)$ , then under the conditions (28)–(29), there exists the inertial fractal set  $M$  of  $(S(t), B)$  in  $V$  and

$$d_F(M) \leq c \max \left\{ \sqrt{l^{-2} + 2c_0 + 4c_0^2 \rho_{\infty, 2}^2}, 16e^{c_5 t} c_5^{1/2} (c_5 + \gamma)^{-1/2} \right\} + 2 \quad (56)$$



$$\text{dist}_V(S(t)B, M) \leq c_0 e^{-c_1 t} \quad (57)$$

$t_*$  satisfies  $2c_2 l^2 e^{-\gamma t_*} < \frac{1}{256}$ , constants  $c_0, c_1, c, c_6$ , do not depend on  $w$ ,  $c_2$  is defined by (46).

**Proof** By Propositions 4, (43) and (55), we deduce that there exists an inertial fractal set for  $(S(t), B)$ , where  $N_0$ , satisfy

$$\lambda_{N_0+1} \geq \max \left\{ 2c_0 + 4c_0^2 \rho_{\infty,2}^2 + l^{-2}, 256c_5 e^{2c_6 t_*} (\gamma + c_5)^{-1} \right\} \quad (58)$$

We choose  $\delta < \frac{1}{8}$ ,  $4\delta < \theta < 1$ , and observe  $\lambda_{N_0+1} \geq c_0 N_0^2$  in (23), the complex space is regarded as the product of the two real spaces, we obtain the (56), (57) follows with (24).

**Remark** If we solve  $t_*$  from the inequality  $2c_2 l^2 e^{-\gamma t_*} \leq \frac{1}{256}$ , then (56) will not contain  $t_*$ .

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