

Approximation of the Spectral Fractional Powers of the Laplace-Beltrami Operator

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Abstract. We consider numerical approximation of spectral fractional Laplace-Beltrami problems on closed surfaces. The proposed numerical algorithms rely on their Balakrishnan integral representation and consists a sinc quadrature coupled with standard finite element methods for parametric surfaces. Possibly up to a log term, optimal rate of convergence are observed and derived analytically when the discrepancies between the exact solution and its numerical approximations are measured in L^2 and H^1 . The performances of the algorithms are illustrated on different settings including the approximation of Gaussian fields on surfaces.

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1. Introduction

In this paper, we consider finite element approximations of the spectral fractional Laplace-Beltrami problem

$$(-\Delta_\gamma)^s \tilde{u} = \tilde{f} \quad \text{on } \gamma, \quad (1.1)$$

where γ is a closed, compact and C^3 hyper-surface in \mathbb{R}^n , $n = 2, 3$ and where the data f is square integrable in γ while satisfying the compatibility condition $\int_\gamma \tilde{f} = 0$. Such system finds applications for instance in the study of Gaussian random fields on surfaces [5, 26, 27].

As we shall see, the spectral negative fractional powers of the Laplace-Beltrami operator $L := -\Delta_\gamma$ are defined using the Balakrishnan formula [3]

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$$L^{-s}\tilde{f} := \frac{\sin(\pi s)}{\pi} \int_0^\infty \mu^{-s}(\mu I + L)^{-1}\tilde{f} d\mu, \quad s \in (0, 1). \tag{1.2}$$

This representation is equivalent to the spectral representation more often used as detailed in Section 2.3.

On Euclidean domains, a two-step numerical approximation strategy based on (1.2) is proposed in [13, 14] for the standard Laplacian. After a change of variable, an exponentially converging sinc quadrature [11]

$$\mathcal{Q}_k^{-s}(L)\tilde{f} = \frac{k \sin(\pi s)}{\pi} \sum_{\ell=-M}^N e^{(1-s)y_\ell} (e^{y_\ell} I + L)^{-1}\tilde{f} \tag{1.3}$$

is advocated for the approximation of the outer integral in (1.2). Here $k > 0$ is the quadrature spacing, $y_\ell = \ell k$, and $M, N \in \mathcal{O}(k^{-2})$ are positive integers. In [13,14], each of the sub-problems $(e^{y_\ell} I + L)^{-1}\tilde{f}$ are approximated independently using a standard continuous piecewise linear finite element method. We refer to [4] for extensions to hp -discretization methods. For completeness, we also mention the reviews [6, 28] describing alternate algorithms for fractional powers of elliptic operators on Euclidean domains.

Regarding the Laplace-Beltrami operator on closed surface, several algorithms for its approximation are available as well. Parametric finite element methods [20] and trace finite element methods [17, 30, 31] rely on polygonal approximations Γ of the exact surface γ . Instead, other numerical methods like the narrow band methods [16, 17] are defined on a neighborhood of γ . We refer to [10, 21] for reviews of these methods and others. All the above mentioned numerical approaches have in common an inherent geometric errors (or consistency errors) resulting from the approximation of γ , thereby leading to the uncharted territory (in the context of approximation of fractional operators) of non-conforming methods.

The main contribution of this work is to develop a new analysis to incorporate the approximation by parametric finite element methods within the framework developed in [14]. The approximate polygonal surface on which the finite element method is defined is related to the exact surface via a C^2 orthogonal projection $\mathbf{P} : \Gamma \rightarrow \gamma$ given by $\mathbf{P}(\mathbf{x}) = \mathbf{x} - d(\mathbf{x})\nabla d(\mathbf{x})$, where d is the signed distance function to γ . In [19, 20] this typical choice of lift is put forward in view of its $\mathcal{O}(h^2)$ approximation of the geometry at the expense of requiring surfaces γ of class C^3 . Here h stands for typical diameter of the faces constituting the approximation Γ . In opposition, favoring practical implementations and applicability to rougher surfaces, a generic continuous piecewise C^2 lift is considered in [7, 8, 29] leading to a reduced $\mathcal{O}(h)$ approximation of the geometry. The latter is sufficient to control with optimal order the H^1 , but not L^2 , discrepancy between the solution to the standard Laplace-Beltrami operator and its parametric linear finite element approximations. However, the analysis of algorithms based on the integral representation (1.2) requires space discretization methods to perform simultaneously well in H^1 and L^2 , thereby exacerbating even more the intricate relation