

# The Sufficient and Necessary Condition of Lagrange Stability of Quasi-periodic Pendulum Type Equations\*

CONG FU-ZHONG<sup>1,2</sup>, LIANG XIN<sup>1</sup> AND HAN YUE-CAI<sup>1</sup>

(1. *Fundamental Department, Aviation University of Air Force, Changchun, 130022*)

(2. *Institute of Mathematics, Jilin University, Changchun, 130012*)

Communicated by Li Yong

**Abstract:** The quasi-periodic pendulum type equations are considered. A sufficient and necessary condition of Lagrange stability for this kind of equations is obtained. The result obtained answers a problem proposed by Moser under the quasi-periodic case.

**Key words:** Lagrange stability, pendulum type equation, KAM theorem

**2000 MR subject classification:** 37J40

**Document code:** A

**Article ID:** 1674-5647(2010)01-0076-09

## 1 Introduction

The Lagrange stability of pendulum type equations is an important topic, which is proposed by Moser<sup>[1]</sup>. Moser<sup>[2]</sup>, Levi<sup>[3]</sup> and You<sup>[4]</sup> investigated such topic for the periodic situation, respectively. In particular, You obtained a sufficient and necessary condition for Lagrange stability of the equation (1.1) in [4].

Recently, Bibikov<sup>[5]</sup> developed a KAM theorem for nearly integrable Hamiltonian systems with one degree of freedom under the quasi-periodic perturbation. In fact, his KAM theorem is of parameter type. Using this theorem he discussed the stability of equilibrium of a class of the second order nonlinear differential equations.

In this note we study quasi-periodic pendulum type equations. Under the standard Diophantine condition of frequency  $\omega$ , a sufficient and necessary condition of Lagrange stability for quasi-periodic pendulum type equations is obtained. This answers Moser's problem under the quasi-periodic case.

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\*Received date: April 21, 2009.

Foundation item: Partially supported by the NSF (10871203, 10601019) of China and the NCET (07-0386) of China.

We consider a nonlinear pendulum type equation

$$\frac{d^2x}{dt^2} + p(t, x) = 0, \tag{1.1}$$

where

$$p(t, x + 1) = p(t, x),$$

and  $p(t, x)$  is a quasi-periodic function in  $t$  with basic frequencies  $\omega = (\omega_1, \dots, \omega_n)$ , that is,

$$p(t, x) = f(\omega t, x) \tag{1.2}$$

for some function  $f(\theta, x)$  defined on  $T^n \times T^1$ . Here  $T^n = R^n/Z^n$  is an  $n$ -dimensional torus.

Assume that  $f(\theta, x)$  is a real analytic function on  $T^n \times T$  and the frequency  $\omega$  satisfies Diophantine condition as follows:

$$|\langle k, \omega \rangle| \geq \gamma |k|^{-(n+1)}, \quad 0 \neq k \in Z^n \tag{1.3}$$

for a given  $\gamma > 0$ , where  $\langle \cdot, \cdot \rangle$  denotes the usual inner product.

We are in a position to state the main result of this paper.

**Theorem 1.1**    *Assume that (1.3) holds. Then system (1.1) is Lagrange stable if and only if*

$$\int_{T^n \times T^1} f(\theta, x) d\theta dx = 0. \tag{1.4}$$

Moreover, if (1.3) and (1.4) hold, equation (1.1) possesses infinitely many quasi-periodic solutions with  $n + 1$  basic frequencies (including  $\omega_1, \dots, \omega_n$ ).

- Diophantine condition (1.3) can be replaced by a general form

$$|\langle k, \omega \rangle| \geq \gamma |k|^{-\tau_*}, \quad 0 \neq k \in Z^n \tag{1.5}$$

with some constant  $\tau_* > n$ . Here we assume (1.3) for the convenience of the proof of Theorem 1.1.

- Huang<sup>[6]</sup> considered a class of almost periodic pendulum-type equations. He proved the existence of unbounded solutions of the equations. Summing up the works developed by Mose<sup>[2]</sup>, Levi<sup>[3]</sup>, You<sup>[4]</sup> and Huang<sup>[6]</sup>, respectively, and Theorem 1.1, we can obtain a satisfactory answer to Moser's problem.
- Recently, Lin and Wang<sup>[7]</sup> have concerned with a dual quasi-periodic system as follows:

$$\frac{d^2x}{dt^2} + \frac{\partial g}{\partial x}(t, x) = 0, \tag{1.6}$$

where  $g(t, x)$  is quasi-periodic in  $t$  and  $x$  with frequencies  $\Omega^1 = (\omega_1, \dots, \omega_n)$  and  $\Omega^2 = (\omega_{n+1}, \dots, \omega_{n+m})$ , respectively. Under the assumptions

$$(\Omega^1, \Omega^2) \in O_\gamma = \{(\Omega^1, \Omega^2) \in R^{n+m} : |\langle k, \Omega^1 \rangle + \langle l, \Omega^2 \rangle| \geq \gamma(|k| + |l|)^{-\tau_*}, \\ \forall 0 \neq (k, l) \in Z^{n+m}, \tau_* > n + m\}$$

and

$$\forall j \in N, \exists A(j) \geq j, \quad \text{s.t. } (\Omega^1, A(j)\Omega^2) \in O_\gamma,$$

they proved that all the solutions of (1.6) are bounded (see [7]). It is easy to find that as  $m = 1$ , their modified Diophantine condition is stronger than (1.5); in addition, the result of [7] is a sufficient condition to ensure Lagrange stability. This differs from Theorem 1.1.