

Projections, Birkhoff Orthogonality and Angles in Normed Spaces*

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Abstract: Let X be a Minkowski plane, i.e., a real two dimensional normed linear space. We use projections to give a definition of the angle $A_q(\mathbf{x}, \mathbf{y})$ between two vectors \mathbf{x} and \mathbf{y} in X , such that \mathbf{x} is Birkhoff orthogonal to \mathbf{y} if and only if $A_q(\mathbf{x}, \mathbf{y}) = \frac{\pi}{2}$. Some other properties of this angle are also discussed.

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1 Introduction and Preliminaries

In the research of geometry in inner spaces, orthogonality plays a very important role. In general normed spaces, many new orthogonalities have been introduced, such as Birkhoff orthogonality in [1], isosceles orthogonality in [2] and so on. These definitions of orthogonalities are different, and their relations were discussed in [3]. In 1993, Milicic^[4] introduced g-orthogonality in normed spaces via Gateaux derivatives. In [5], it is shown that the angle $A(\mathbf{x}, \mathbf{y})$ in X satisfies the basic properties. In [6] and [7], there are more about the geometry of Minkowski plane. James^[8] gave a result of Birkhoff orthogonality in l_2^∞ .

Birkhoff orthogonality was introduced by Birkhoff^[1] in 1935, which is the first notion of orthogonality in normed spaces.

Definition 1.1 Let \mathbf{x} and \mathbf{y} be two vectors in a normed space X . \mathbf{x} is said to be Birkhoff orthogonal to \mathbf{y} , denoted by $\mathbf{x} \perp_B \mathbf{y}$, if for any $t \in \mathbf{R}$

$$\|\mathbf{x} + t\mathbf{y}\| \geq \|\mathbf{x}\|.$$

In 1993, Milicic^[4] introduced g-orthogonality in normed spaces via Gateaux derivatives. In fact, one has the notion of g-angle related to g-orthogonality.

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Definition 1.2 The functional $g : X^2 \rightarrow \mathbf{R}$ is defined by

$$g(\mathbf{x}, \mathbf{y}) = \frac{1}{2} \|\mathbf{x}\| (\tau_+(\mathbf{x}, \mathbf{y}) + \tau_-(\mathbf{x}, \mathbf{y})),$$

where

$$\tau_{\pm}(\mathbf{x}, \mathbf{y}) = \lim_{t \rightarrow \pm 0} \frac{\|\mathbf{x} + t\mathbf{y}\| - \|\mathbf{x}\|}{t}.$$

The g -angle between two vectors \mathbf{x} and \mathbf{y} , denoted by $A_g(\mathbf{x}, \mathbf{y})$, is given by

$$A_g(\mathbf{x}, \mathbf{y}) = \arccos \frac{g(\mathbf{x}, \mathbf{y})}{\|\mathbf{x}\| \|\mathbf{y}\|}.$$

Furthermore, \mathbf{x} is said to be g -orthogonal to \mathbf{y} , denoted by $\mathbf{x} \perp_g \mathbf{y}$, if

$$g(\mathbf{x}, \mathbf{y}) = 0,$$

i.e.,

$$A_g(\mathbf{x}, \mathbf{y}) = \frac{\pi}{2}.$$

In an inner product space $(X, \langle \cdot, \cdot \rangle)$, the angle $A(\mathbf{x}, \mathbf{y})$ between two nonzero vectors \mathbf{x} and \mathbf{y} in X is usually given by

$$A(\mathbf{x}, \mathbf{y}) = \arccos \frac{\langle \mathbf{x}, \mathbf{y} \rangle}{\|\mathbf{x}\| \|\mathbf{y}\|},$$

where $\|\mathbf{x}\| = \langle \mathbf{x}, \mathbf{x} \rangle^{1/2}$ denotes the induced norm in X . One may observe that the angle $A(\mathbf{x}, \mathbf{y})$ in X satisfies the following basic properties (see [5]):

◊ Parallelism: $A(\mathbf{x}, \mathbf{y}) = 0$ if and only if \mathbf{x} and \mathbf{y} are of the same direction; $A(\mathbf{x}, \mathbf{y}) = \pi$ if and only if \mathbf{x} and \mathbf{y} are of opposite direction.

◊ Symmetry: $A(\mathbf{x}, \mathbf{y}) = A(\mathbf{y}, \mathbf{x})$ for every $\mathbf{x}, \mathbf{y} \in X$.

◊ Homogeneity:

$$A(a\mathbf{x}, b\mathbf{y}) = \begin{cases} A(\mathbf{x}, \mathbf{y}), & ab > 0; \\ \pi - A(\mathbf{x}, \mathbf{y}), & ab < 0. \end{cases}$$

◊ Continuity: If $\mathbf{x}_n \rightarrow \mathbf{x}$ and $\mathbf{y}_n \rightarrow \mathbf{y}$ (in norm), then $A(\mathbf{x}_n, \mathbf{y}_n) \rightarrow A(\mathbf{x}, \mathbf{y})$.

The g -angle is identical with the usual angle in an inner space and has the following properties:

(I) Part of parallelism property: If \mathbf{x} and \mathbf{y} are of the same direction, then

$$A_g(\mathbf{x}, \mathbf{y}) = 0;$$

if \mathbf{x} and \mathbf{y} are of opposite direction, then

$$A_g(\mathbf{x}, \mathbf{y}) = \pi.$$

(II) Part of homogeneity property:

$$A_g(a\mathbf{x}, b\mathbf{y}) = A_g(\mathbf{x}, \mathbf{y}), \quad \mathbf{x}, \mathbf{y} \in X, a, b \in \mathbf{R};$$

(III) Homogeneity property:

$$A_g(a\mathbf{x}, b\mathbf{y}) = \begin{cases} A_g(\mathbf{x}, \mathbf{y}), & ab > 0; \\ \pi - A_g(\mathbf{x}, \mathbf{y}), & ab < 0. \end{cases}$$

(IV) Part of continuity property: If $\mathbf{y}_n \rightarrow \mathbf{y}$ (in norm), then $A_g(\mathbf{x}, \mathbf{y}_n) \rightarrow A_g(\mathbf{x}, \mathbf{y})$.

However, g -orthogonality is not equivalent to Birkhoff orthogonality. In this article, we use projections to give a definition of the angle $A_q(\mathbf{x}, \mathbf{y})$ between two vectors \mathbf{x} and \mathbf{y} such that \mathbf{x} is Birkhoff orthogonal to \mathbf{y} if and only if

$$A_q(\mathbf{x}, \mathbf{y}) = \frac{\pi}{2}.$$